NASA Contractor Report 181707

SPACE STATION RT&E UTILIZATION STUDY

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(NASA-CR-181707) SPACE STATION RT AND F
UTILIZATION STUDY (Teledyne Brown Engineering) 102 p

CSCL 228

Unclas
63/18 0234598

Teledyne Brown Engineering Cummings Research Park Huntsville, AL 35807

Contract No. NAS1-18228 (Task 4) September 1989



Langley Research Center Hampton, Virginia 23665-5225

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LIST OF ACRONYMS

A&R Automation and Robotics

ADS Attitude Determination System

AFGL Air Force Geophysics Laboratory

AFRPL Air Force Rocket Propulsion Lab

AFSD Air Force Space Division

AFTAC Air Force Tactical Air Command

AFWAL Air Force Wright Aeronautical Laboratories

AMD Aerospace Medical Division

APAE Attached Payload Accommodation Equipment

ARC Ames Research Center

BAC Boeing Aerospace Company

CELSS Closed Experimental Life Support System

CMS Contamination Monitoring System

CSS Crew Support Station

CSTI Civil Space Technology Initiative

DOD Department of Defense
DSN Deep Space Network

ELV Expendable Launch Vehicle

EM Electromagnetic

EMU EVA Mobility Unit

EVA Extra Vehicular Activity

FF Free-Flyer

FTS Flight Telerobotic Servicer

GDC General Dynamics Corporation

GE General Electric

GEM Gaseous Environment Monitor

GPS Global Positioning System

GSFC Goddard Space Flight Center

IVA Intra-Vehicular Activity

JPL Jet Propulsion Laboratory

JSC Johnson Space Center

KSC Kennedy Space Center

LaRC Langley Research Center

LIST OF ACRONYMS (continued)

LDEF Long Duration Exposure Facility

LDR Liquid Droplet Radiator
LeRC Lewis Research Center

LMSC Lockheed Missiles and Space Company

LSE Laboratory Support Equipment

LSF Laboratory Support Facility

MDAC McDonnell Douglas Astronautics Corporation

MIT Massachusetts Institute of Technology

MM Martin Marietta

MMPF Microgravity and Materials Processing Facility

MPA Multiple Payload Adapter

MRDB Mission Requirements Data Base

MSC Mobil Servicing Center

MSFC Marshall Space Flight Center

NASA National Aeronautics and Space Administration

NDT Non-Destructive Testing

OAST Office of Aeronautics and Space Technology

OMV Orbital Maneuvering Vehicle

OTV Orbital Transfer Vehicle

PI Principal Investigator

PIA Payload Interface Adapter

PMV Proximity Maneuvering Vehicle

PPS Payload Pointing System

RADC Rome Air Development Center

RF Radio Frequency

RME Radiation Measurements Experiment
RT&E Research, Technology and Engineering

SBR Space-Based Radar

SEM Scanning Electron Microscopy

SIA Station Interface Adapter

S/C Spacecraft

SRRL Space Robotics Research Laboratory

SS Space Station

LIST OF ACRONYMS (concluded)

TBD To Be Determined

TDM Technology Development Mission

TDMX Technology Development Mission Experiments

TES Thermal Energy Storage

UAH University of Alabama in Huntsville

USAF United States Air Force

VHSIC Very High Speed Integrated Circuit

VLBI Very Long Baseline Interferometer

VLSI Very Large Scale Integration

I. INTRODUCTION

Outfitting equipment will transform the basic accommodations of the Space Station into a functional laboratory in space in the same way that specialized instrumentation and analysis equipment transforms a building into a laboratory here on Earth. Requirements for specific outfitting items depend on the nature of user in-space research interests and vary from discipline to discipline. Since the Space Station will be shared by a number of user communities, it is important that the outfitting needs of each community be understood and planned for.

Considerable effort has been invested in establishing outfitting requirements for the life science and microgravity users. Similar attention had not been paid to outfitting for technology development users leading to a concern that requirements were being overlooked. Initial efforts addressing this concern included studies by Battelle¹ and General Research Corporation² that identified support equipment requirements at a generic level. The current study goes a step further by examining a broader range of technology missions [including some Department of Defense (DOD) concepts], by keying specific outfitting needs to individual missions, and by comparing identified needs with planned outfitting for other user classes.

Outfitting equipment includes common support equipment, subsystem augmentation equipment, and unique subsystems needed to enhance user productivity. It will be developed under the Space Station program to provide capabilities to meet requirements that are common to a number of users. Thus, accomplishing study objectives meant (1) determining for individual experiments what will be needed in the way of support or augmentation equipment, and (2) determining which of those needs are common to other missions.

The study approach began with a review of descriptive information on equipment, activities, and resource requirements for a set of 241 candidate technology missions arranged into seven technical themes. For each mission an equipment list was generated that included both support equipment and experiment equipment thought by nature to have multi-use potential. These lists were checked for commonality with equipment currently in planning (Laboratory Support Equipment, Laboratory Outfitting Subsystems, etc.) to identify by subtraction those needs that are not yet being addressed. The focus of the study was on these residual needs, and the outfitting issue still to be resolved is which of these items should be provided by the Space Station program as outfitting equipment and which should be developed as user-provided equipment. User demand will certainly be a factor in this decision, and the number of missions needing each item was tallied as a reflection of common-use potential.

The time phasing of technology outfitting requirements was also examined by organizing payload sets into flight scenarios. The intent was to identify potential planning issues relating to outfitting implementation. The approach used theme-oriented mission complements to provide a representative set of

outfitting requirements during the initial phases of Space Station operations. Mission selection considered Office of Aeronautics and Space Technology (OAST) planning, the Pathfinder and Civil Space Technology Initiative (CSTI) programs, and accommodation drivers. Mission timing reflected the desired start year and duration.

The Space Station RT&E (Research, Technology, and Engineering) Utilization Study is an initial step in a path that may lead ultimately to the development of additional outfitting equipment. It was intended as a systematic survey of requirements for the full range of technology development missions proposed for early Space Station, and an extensive list of potential outfitting items was compiled as a result. However, the current study was performed without the benefit of interaction with technology principal investigators (PIs). PI inputs will clearly play a vital role in carrying this effort to the next stage by refining and validating the outfitting needs identified herein and by establishing priorities and performance specifications for equipment development.

REFERENCES

- 1. <u>Space Station Technology Development Mission Analysis</u>, Battelle, Columbus Division for NASA/ Lewis Research Center, Contract NAS3-23895, August 15, 1986.
- 2. <u>Laboratory Services for RT&E and Microgravity Science and Applications Experiments on the Space Station Complex.</u> General Research Corporation for NASA/Office of Aeronautics and Space Technology, June 1987.

II. THE TECHNOLOGY DEVELOPMENT MISSION SET

This section describes the approach used to organize and characterize the technology mission set to drive out significant relationships and trends pertaining to Space Station outfitting.

A. Data Sources

The current study relied heavily on the results of preceding experiment definition efforts as presented in the set of reference documents listed in Appendix A. Within these documents varying levels of definition were found for a total of 241 candidate technology development missions (TDMs); they included concepts submitted by NASA in-house personnel, concepts developed under contract, and concepts from the DOD. Nearly all of these missions are covered to some degree in the following four documents:

- The Mission Requirements Data Base (MRDB) for TDMX payloads
- Proceedings of the Williamsburg workshop
- The Battelle experiment definition study report
- The Air Force Space Station Working Group report.

A profile of the mission set with respect to these sources is presented in Figure II-1. Many of the missions are described in additional detail in the other documents in Appendix A.

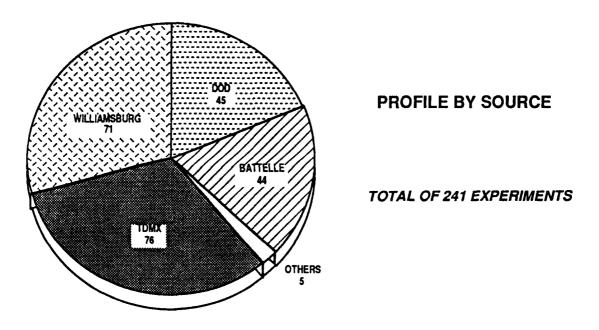


FIGURE II-1. SOURCES OF EXPERIMENT DEFINITION DATA

B. Representation of OAST Themes

At the time of the study the NASA Office of Aeronautics and Space Technology (OAST) classified technology development missions (TDMs) into seven themes. They are:

- Space Structure (Dynamics and Control)
- Fluid Management
- Space Environmental Effects
- Energy Systems and Thermal Management
- Automation and Robotics
- Information Systems
- In-Space Operations.

While the names are indicative of theme scope, definitions appearing in the Amended Program Solicitation for Industry and University In-Space Technology Experiments (issued October 24, 1986) were used where clarification was needed. This document is referred to informally as the "outreach" solicitation. Within the mission set all seven themes were well represented as indicated in Figure II-2.

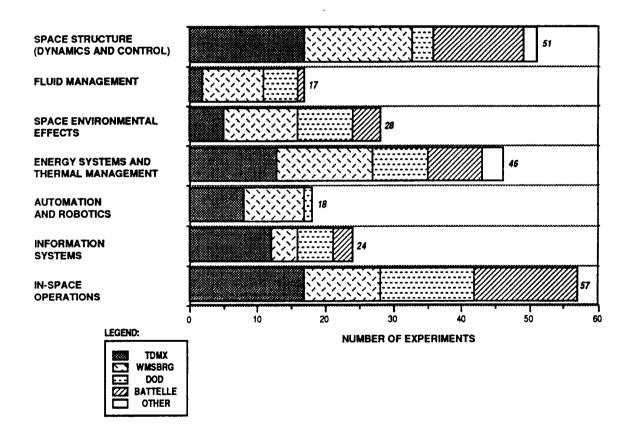


FIGURE II-2. PROFILE OF SEVEN TECHNOLOGY THEMES BY DATA SOURCE

C. Organizing the Mission Set

Grouping missions with similar or related in-space objectives was an early goal in the study, because similar missions should have common requirements for outfitting equipment. The following classification hierarchy was used to achieve this:

- Theme
- Subtheme (or area)
- Project
- Mission (or experiment).

A complete listing of the study mission set, presented in the context of this classification scheme, can be found in Appendix B.

For missions appearing in the preceedings of the Williamsburg conference the Williamsburg theme assignments were used as a point of departure. Minor adjustments were made based on theme definitions in the 1986 OAST "outreach" solicitation. Subthemes and projects were defined as appropriate.

Within this scheme each project was intended to address a single technology development issue or technology application. Project groups contained one or more missions as appropriate. Multiple missions within a project group are often closely related in their objectives and might be consolidated into a single mission or be conducted as a coordinated experiment sequence using a common testbed.

D. Mission Types

In evolving from initial discovery to end application a technology development progresses through several phases of maturity, and in-space experimentation may be beneficial or necessary at any point along the way. Significant differences typically exist from phase to phase in requirements for experiment hardware, accommodations, and outfitting. To account for such differences missions were classified as research-type, technology development-type, or demonstration-type. A similar classification of missions appears in Volume 8 of the Williamsburg proceedings, In-Space Operations.

A research-type mission involves basic or applied research that contributes to the understanding of in-space phenomena. It creates or expands the knowledge base required for designing hardware components that utilize or cope with the subject phenomena. Research-type activities tend to be result-driven and may require outfitting equipment for in-space analysis of results.

Technology development-type missions involve in-space testing of component prototypes and critical function demonstration to establish proof of concept. They often utilize a test bed configured to facilitate the changeout of components of alternative design.

Finally, demonstration-type missions involve the monitoring of end item performance to establish proof of maturity. Demonstration-type activities tend to involve assemblies configured as complete systems. Many of the demonstration missions were similar to what a hardware project would conduct as part of an advanced development program or as a preoperational checkout of a new space system.

NASA uses eight levels of technology maturity to provide an objective gauge of technology readiness (see, for example, the Battelle report, page 2-1). Table II-I lists these eight maturity levels and shows how they correspond to the three phases of the technology development cycle defined in the current study.

A profile of the mission set by type is presented in Figure II-3. A number of missions span two phases as indicated by the overlap regions. The "other" group contains four concepts that were judged not suitable as technology missions, two concepts that included research and demonstration activities, and one concept that could not be classified based on the information available.

A profile of the seven OAST themes by mission type is presented in Figure II-4. The differences in emphasis between themes merely reflects the role that in-space activities play in the technology development cycle for each theme. A strong research-phase emphasis is indicated for the Space Environmental Effects theme, while the Automation and Robotics and Information Systems themes are represented more heavily by demonstration-type missions.

TABLE II-1. CORRELATION BETWEEN EXPERIMENT TYPES AND NASA LEVELS OF TECHNOLOGY MATURITY

| EXPT. TYPE | LEVEL OF TECHNOLOGY MATURITY |
|---------------|--|
| R | Level 1 - Basic principles observed and reported Level 2 - Conceptual design formulated |
| т т т | Level 3 - Conceptual design tested analytically or experimentally Level 4 - Critical function/characteristic demonstration Level 5 - Component/brassboard tested in relevant environment Level 6 - Prototype/engineering model tested in relevant environment |
| D D | Level 7 - Engineering model tested in space Level 8 - Operations |

R = Research, T = Technology Development, D = Demonstration

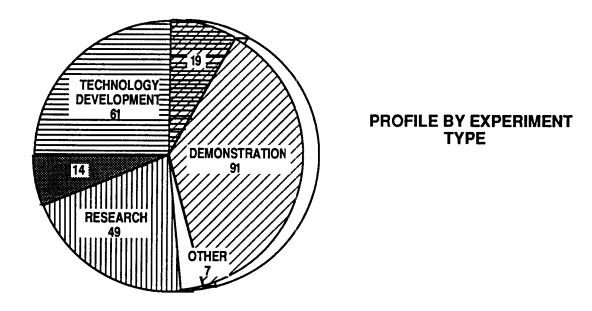


FIGURE II-3. PROFILE OF MISSION SET BY TYPE SHOWS HEAVY EMPHASIS ON DEMONSTRATION (PROOF OF MATURITY) EXPERIMENTS

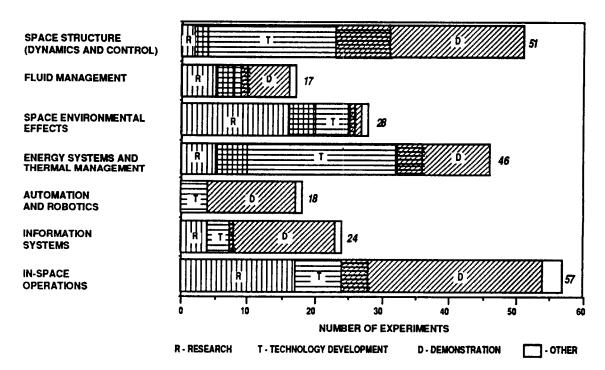


FIGURE II-4. PROFILE OF TECHNOLOGY THEMES BY EXPERIMENT TYPE SHOWS VARIATION IN EMPHASIS FROM THEME-TO-THEME.

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III. DEVELOPMENT OF OUTFITTING REQUIREMENTS

The primary output of the study is a list of outfitting equipment needed to support technology development missions on the Space Station. This list was developed in three steps: (1) identifying outfitting needs of individual missions, (2) establishing commonality with planned outfitting for microgravity and life sciences users, and (3) analyzing the residual needs for multi- use potential.

A. Identifying Outfitting Needs

The question of what outfitting equipment should be provided for technology development missions is not an easy one to answer. On a fundamental level the technical domain spanned by the set of technology development missions has tremendous breadth. As a result, the objectives, measurement methods, and experiment equipment that pertain to one segment of the technology mission set may have no relevance for other segments. Consider space structures and fluid management experiments as a case in point. On a more practical level there is simply a lack of explicit requirements definition for technology development missions at this stage of the Space Station program. As a result, the process of identifying outfitting needs required a liberal amount of interpretation based on an understanding of mission objectives and research methodologies.

The matter of information completeness and quality is addressed further here because it points out the need for additional emphasis on outfitting requirements in future mission definition efforts. To direct attention to the best information on each technology mission early in the study a formal assessment was made of the level of descriptive detail available in the resource documentation. A scale of 1-5, defined in Table III-1, was used to quantify the completeness of the information for each mission. Level "1" meant verbal description only while level "5" signified a complete description of the experiment system and associated support equipment commensurate with results of the Microgravity and Materials Processing Facility (MMPF) Study¹. This means that top-level physical characteristics and resource requirements

TABLE III-1. CHARACTERIZATION OF MISSION DESCRIPTIONS FOR COMPLETENESS.

- (1) Verbal description only
- (2) MRDB entry
- (3) Descriptive text/data plus equipment sketch
- (4) Full experiment description with support equipment listed
- (5) Full experiment description with support equipment characterized

were defined for the support equipment as well as the basic experiment equipment. A profile of technology missions by level of definition is presented in Figure III-1. In only a few cases were support equipment needs identified item-by-item (Level 4), and support equipment items were not characterized (Level 5) for any of the missions.

In reviewing the mission descriptions a broad view was adopted of what constituted outfitting equipment since clear guidelines did not exist. Outfitting candidates were considered to be any item not provided by the PI plus any items in the PI-provided experiment system that were deemed to have multi-use potential. They included the following:

- Key items of Payload Attachment Equipment (Payload Pointing System, Crew Support Station, etc.)
- Key items of standard subsystem equipment (video recorder, graphics terminal, etc.)
- Special systems and facilities [Orbital Maneuvering Vehicle (OMV), service hanger, Mobile Servicing Center, etc.]
- Experiment equipment with potential for general use.

For each of the 241 missions the descriptive information on activities and equipment was analyzed to establish potential outfitting needs. Mission-level equipment lists were developed and consolidated in a computerized data base that ultimately contained over 1700 entries. A commercially available data base management program was used to facilitate cataloging and processing of the outfitting needs data.

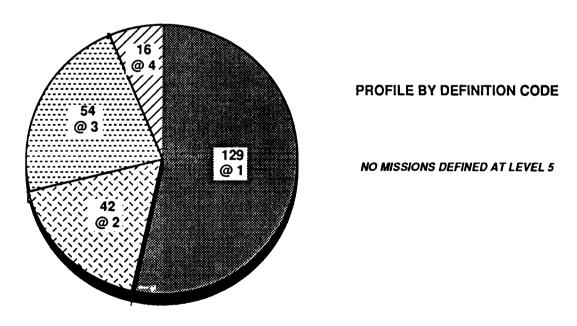


FIGURE III-1. PROFILE OF MISSION SET BY LEVEL OF DEFINITION SHOWS THAT SUPPORT EQUIPMENT NEEDS WERE NOT EXPLICITLY IDENTIFIED IN MOST CASES (LEVEL 4 OR 5).

Figure III-2 shows the equipment entries for a single mission. Each entry included the equipment item name, a category identifier, a mission activity phase, and an optional comment to explain the need and state special requirements as appropriate. The activity phase was included to provide traceability of outfitting needs to specific aspects of mission operations and was thought to have future value in validating study findings. The six activity phases recognized were:

- (1) Initial setup/assembly
- (2) Experiment operations
- (3) On-board quick-look analysis
- (4) Maintenance, servicing, reconfiguration
- (5) Deactivation/disassembly
- (6) On-board storage.

| | FLUIC | MAN (| AGEMEN | | | | | | | | | |
|----------------------------------|-------------------------------------|--------|-------------------|---|--|--|--|--|--|--|--|--|
| | Support Eq | uipme | nt Requir | rements | | | | | | | | |
| SUBTHEME: Spacecraft Fire Safety | | | | | | | | | | | | |
| MISSION CODE | EQUIPMENT ITEM | EQP | MISSION PHASES | SPECIAL REQUIREMENTS/ COMMENTS | | | | | | | | |
| | FLAME | SPREAD | MECHANISM | MS | | | | | | | | |
| FM-007 | Spacecraft Fire Safety Technology | | I | | | | | | | | | |
| | Camera locker | LSE | i 6 | For high-speed cinema camera | | | | | | | | |
| | Camera, high-speed cinema | | 2 | Milliken DBM4A or equivalent | | | | | | | | |
| | Cleaning equipment | LSE | 4 | Swabs, fluids, etc. | | | | | | | | |
| | Data recorder, digital | Std | 2,3 | | | | | | | | | |
| | Data terminal, graphics | Std | 2,3 | | | | | | | | | |
| | Film locker, cinema | | i 6 | Cinema film storage | | | | | | | | |
| | Gas chromatograph/mass spectrometer | | 3 6 | Analysis of gas combustion products | | | | | | | | |
| | Gas sampling bottles | | 6 | Store combustion gas samples for analysis/ transport | | | | | | | | |
| | Gas storage/supply, lab | LSS | 4,6 | O_2, N_2 | | | | | | | | |
| | Image intensifier | | 2 | Film and video images | | | | | | | | |
| | Interferometer, holographic | | 2 2 2 | | | | | | | | | |
| | Laser Doppler anemometer | | 2 | | | | | | | | | |
| | Photo processor unit | | 2,3 | Development of holographic plates | | | | | | | | |
| | Sample containers | | 6 | Storage/transport of experiment samples | | | | | | | | |
| | Storage locker, EM-shielded | LSE | 6 | Store video cassettes | | | | | | | | |
| | Storage, sample | LSS | 6 | | | | | | | | | |
| | Vacuum vent | LSS | 2,4 | ' | | | | | | | | |
| | Video | Std | 2 | | | | | | | | | |
| | Video recorder | Std | 2,3 | Observed asserts assertial ask and assert | | | | | | | | |
| | Waste disposal system | LSS | 6 | Charred sample material, ash and spent | | | | | | | | |
| | | | ! | cleaning materials | | | | | | | | |

<u>Mission Phases</u>: 1 - setup/assembly; 2 - experiment operations; 3 - quicklook analysis of results; 4 - maintenance, servicing, reconfiguration; 5 - deactivation/disassembly; 6 - on-oroit storage.

FIGURE III-2. EXTRACT FROM FLUID MANAGEMENT DATA BASE WHICH SHOWS LISTING OF OUTFITTING/MULTI-USE ITEMS FOR A SINGLE MISSION.

B. Commonality with Outfitting Needs of Other Users

Once compiled, the mission equipment needs were analyzed to determine which of the items relate to outfitting equipment already in planning. The list of such items used in this analysis is presented in Table III-2 and includes the following classes of equipment:

- Laboratory Support Equipment
- General Laboratory Support Facility
- Laboratory Outfitting Subsystems
- Attached Payload Accommodation Equipment
- Standard accommodation (subsystem) equipment.

TABLE III-2. LIST OF LSE AND OTHER STANDARD ITEMS CHECKED FOR COMMONALITY WITH TECHNOLOGY OUTFITTING NEEDS

Laboratory Support Equipment - LSE

Autoclave

Battery charger

Camera locker

Camera, 35 mm

Cleaning equipment Cutting/polishing system

Dosimeter, passive

Electrical conductivity probe

Etching equipment

Film locker

Fluid handling tools

Freeze dryer

Freezer

Freezer, cryogenic

Hand tools, general purpose

Incubator

Mass measurement device, micro

Mass measurement device, small

Microscope system

Multimeter, digital

Oscilloscope, digital recording

pH meter

Refrigerator

Specimen labelling tools

Storage locker, EM-shielded

Surgery/dissecting tools

Thermometer, digital

Ultraviolet sterilization unit

Washer/sanitizer, equipment

X-ray system

General Laboratory Support Facilities - LSF

Glovebox, life sciences

Glovebox, materials processing

Workbench, laboratory sciences

Laboratory Outfitting Subsystems - LSS

Acceleration monitor, lab

Chemical storage facility

Cleanup/decontamination equipment

Gas storage/supply, lab

Materials transport system

Storage, process materials

Storage, sample

Vacuum vent

Waste disposal system

Water service, lab grade

Attached Payload Accommodation

Equipment - PAE

Attitude Determination System (ADS)

Contamination Monitoring System (CMS)

Crew Support Station (CSS)

Deck Carrier

Multiple Payload Adapter (MPA)

Payload Interface Adapter (PIA)

Payload Pointing System (PPS)

Station Interface Adapter (SIA)

Standard Subsystem Equipment - Std

Airlock, hyperbaric

Data recorder, digital

Data terminal, graphics

Docking port

Hand tools, EVA general purpose

Mobile Servicing Center (MSC)

Storage, pressurized

Video

Video recorder

Video, external

Workstation, maintenance

The contract end item specification from the Space Station Work Package 1 solicitation was used as a reference for the lab support items. The Work Package 3 solicitation was referenced for attached payload accommodations. In Figure III-2 those items covered by current planning are identified by an appropriate entry in the "Equipment Category" column. The focus of the study, however, was on needs that are <u>not</u> being addressed by current planning--referred to here as residual needs.

C. New Outfitting Items for Technology Missions

The question to be resolved is "which of the residual needs should be met by the Space Station program and which should be met by the PIs themselves?" User demand and suitability are two factors that come into play in providing an answer.

With regard to user demand, the guiding philosophy is that multiple-use items qualify as outfitting candidates while experiment unique items should be provided by the experiment project. To identify the high demand items the mission equipment lists were consolidated at several levels, and the number of missions needing a given item of support equipment was tallied at each level. The resulting user counts are presented at the theme level in Appendix C, at the project level in Appendix D, and for the entire mission set in Appendix E. The demand profile for the entire set of residual equipment needs is reflected in Figure III-3. It suggests that mission count is not a strong descriminator in selecting outfitting candidates. This was not unexpected due to the diversity of technology research interests.

Possibly more important than user demand is how the support equipment items will interface with the rest of the mission apparatus. Here the guiding philosophy is that if the item can be left on orbit and used separately from the mission apparatus or attached/ detached as needed, then it is suitable as an outfitting item. If on the other hand the item is deeply imbedded or integrated in the mission apparatus, then it might better be developed as an experiment-provided item or offered for experiment use as part of a technology program standard inventory.

A short list of items that are the more likely prospects for new development is presented in Table III-3. The items and counts differ in several respects from what is shown in Appendix E. Specifically, the telerobotic and teleoperations workstations have been combined, as have the large and medium antenna positioners and the laser measurement unit and laser range sensor. Also, a proximity maneuvering unit is suggested instead of the OMV where a mobility platform for range tests is required.

REFERENCES

1. <u>Microgravity and Materials Processing Facility Study Data Release</u>, Teledyne Brown Engineering and Boeing Aerospace Company for NASA/George C. Marshall Space Flight Center, Contract NAS8-36122, February 1987.

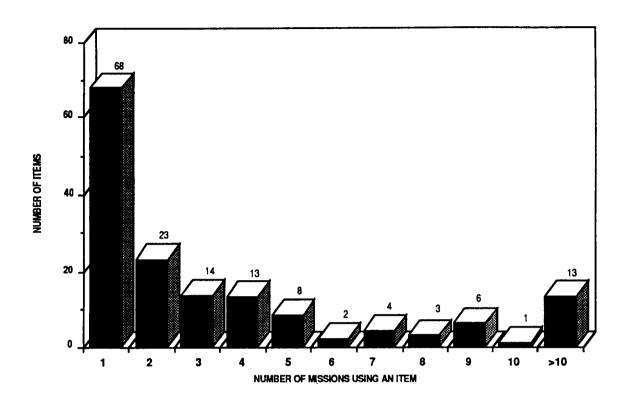


FIGURE III-3. EQUIPMENT DEMAND PROFILE SHOWS THAT FEWER THAN 20% OF THE CANDIDATE OUTFITTING ITEMS ARE ASSOCIATED WITH MORE THAN FIVE (5) MISSIONS

TABLE III-3. EQUIPMENT ITEMS WITH HIGH POTENTIAL AS NEW DEVELOPMENT CANDIDATES

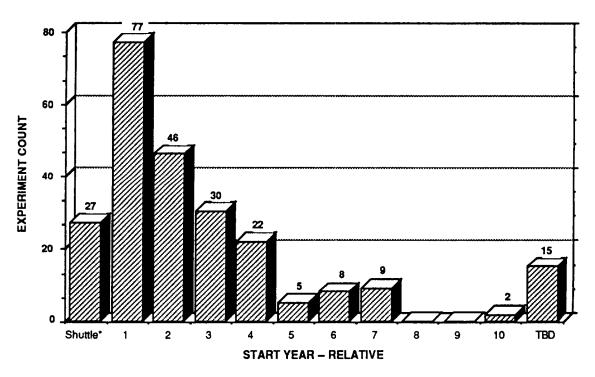
| | MISSION | |
|--|-------------|--|
| ITEM | COUNT | COMMENTS |
| Accelerometer package, external | 29 | Monitor disturbances at pointing/structure attachment base. |
| Sample containers | 19 | Mostly for exposure sample storage/transport. |
| Workstation, telerobotics/operations* | 17 | |
| Mass spectrometer | 14 | Environment (including plumes) monitoring/mapping. May be covered by contamination monitoring system. |
| Exposure tray | 13 | |
| Pointing mount, two-axis solar | 12 | Solar array and radiator pointing. Needs study. PPS is overkill and configured more for astronomy payloads. |
| Imaging radiometer | 11 | Broad applications for structures, photovoltaics, propulsion, and maintenance. |
| Propellant storage/transfer facility | 9 | Long-term. |
| Laser measurement unit* | 8 | Range/angle measurement for structural dynamics and range test support. |
| Plasma diagnostic package | 8 | Environment characterization, electric power/thruster interaction. |
| Camera, high speed cinema | 7 | Two-phase fluid and tribology applications. |
| Video, low light (external) | 7 | Plume diagnostics and possibly high voltage interactions. |
| Proximity maneuvering vehicle (PMV)* | 6 | Mobility platform for RF/laser range tests. |
| Antenna positioner* | 5 | Conventional antenna pointing system (pedestal and gimbals) for large/medium size antennas. Study PPS suitability as an alternative. |
| Reflectometer | 5 | Environmental effects measurements. |
| Tether tracking system | 5 | Long-term. |
| Transmitter/receiver, RF | 5 | Command/data link for portable and proximity mobile equipment. |
| Retroreflective targets | 3 | Support structural dynamics tests and maybe proximity operations. |
| Scanning electron microscope system | 3 | On-board materials analysis. |
| Radiation monitor | 2 | Measure cosmic ray flux in external environment. |
| Image intensifier | 1 | Low light observations for film/video recording. |
| * - Indicates items have been combined | relative to | |

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IV. OUTFITTING IMPLEMENTATION

Coordinating the time-phased development of outfitting equipment with the manifesting of individual experiments will be a major planning challenge. Strawman mission groups for theme-oriented laboratories were used in the current study as a vehicle for developing initial insights into potential planning issues. The missions were selected to be representative of theme goals and were organized into scenarios that reflected the start dates, durations, and accommodation modes requested in the reference materials. The time phasing of outfitting requirements simply tracks the resulting scenarios.

It was anticipated that the mission demand model, as reflected in the desired start dates, would exhibit significant growth with time in line with the anticipated evolutionary buildup of the Space Station. In reality, however, everyone wants to fly early. This trend, clearly evident in Figure IV-1, skews the time phasing of the identified outfitting requirements. While there is a need to replan the technology mission set into a coherent, evolutionary sequence to provide a firmer foundation for a variety of study purposes, such an effort was considered beyond the scope of the current study. Instead, mission scenarios were developed within the existing demand model and truncated in the out years as the mission count tapered off.



*Experiments proposed for the Shuttle but which might fly on the Space Station.

FIGURE IV-1. PROFILE OF EXPERIMENT SET BY START YEAR

A. Mission Selection and Scenario Development

Mission selection was an iterative process that took into consideration Office of Aeronautics and Space Technology (OAST) planning, NASA technology program goals, mission accommodation drivers, desired start year, and an assessment of feasibility and priorities. Level of definition was only a consideration where there was a choice between well-defined and poorly-defined missions. With regard to ongoing NASA technology programs, the set of candidate missions was checked for relevance to both the Pathfinder program and the Civil Space Technology Initiative (CSTI).

Although specific resource quotas were not employed, a goal of the selection process was to work within a modest envelope of Space Station accommodations. Thus, initial selections were reviewed and refined as necessary to avoid serious accommodation drivers. Likewise, further adjustments were necessary in some cases to minimize bunching near the start of Space Station operations.

The scenarios were intended to show an incremental buildup of support equipment for each theme. It was expected that as a result of this exercise, a core set of support equipment could be identified that would capture most of the requirements of the missions in the theme. Such core equipment might then constitute the outfitting for a theme-oriented laboratory such as a Fluid Management, Information Systems, or Space Structures Laboratory. However, even within the individual technology themes there is a considerable diversity of experiment objectives, and this diversity is reflected in turn in the outfitting scenarios. As a consequence, this endeavor was inconclusive.

The results of the mission selection and scenario development process are presented for each of the seven themes in the sections that follow along with findings regarding associated outfitting needs.

B. Space Structure (Dynamics and Control)

Mission selection, payload resource requirements, mission time phasing, and potential support equipment needs for the Space Structure (Dynamics and Control) theme are covered in the next four tables and/or figures. Table IV-1 presents the classification scheme developed for the Space Structure (Dynamics and Control) theme and shows how the missions were distributed among subthemes and projects. In this particular theme it is common for mission objectives to span multiple projects. In these cases the project assignment reflects the area of primary technical emphasis. The columns labeled pathfinder and CSTI, indicate where projects relate to these two OAST programs. Pathfinder covers lunar base and Mars mission technologies while CSTI focusses on specific systems technologies to augment the more general and longer-range Research and Technology Base program. The column labeled OAST indicates which project-level groups are represented in current planning for Space Station Phase I. Finally, the right-hand column of Table IV-1 identifies the individual missions selected for the theme complement. Representation

TABLE IV-1. SELECTION OF EXPERIMENTS FOR SPACE STRUCTURE (DYNAMICS AND CONTROL) RT&E FACILITY

| | | PATH- | Ī | | | SELECTED |
|------------------------------------|-------|--------|------|------|--|-----------------------|
| SUBTHEME/PROJECTS | COUNT | FINDER | CSTI | OAST | COMMENTS | EXPERIMENTS |
| Advanced Structures | | | | 9 | | |
| Assembly | 5 | 4 | | | Use normal EVA assembly operations to build experience base. | |
| Segmented Optics | 3 | | 4 | √ | Demonstrates technology base for future science and DoD missions. | TDMX2421 |
| Thin Film/Inflatable Structures | 5 | | | | Use Shuttle mission to establish feasibility. | |
| Trusses | 1 | | | | Evaluate in application context. | |
| Welding | 2 | 1 | | | Short duration. May be accomplished on a Shuttle mission. | |
| Mechanisms/Controls | | | | | | |
| Attitude Control | 2 | | | | Demonstrate/evaluate in application context. | |
| Pointing/Isolation | 3 | 1 | | | Potential user accommodation benefits. | TDMX2432 |
| Sensors/Actuators | 5 | | | | Evaluate in application context. | |
| Tribological Effects | 5 | | | | Contributes to technology base for dynamic machinery/structures. | SS-016 |
| Structural Dynamics | | | | | | |
| Antennas/Reflectors | 11 | | √ | √ | Coordinate with communication and sensor technology missions. | TDMX2071, TDMX2411 |
| Large Structures (General) | 3 | √ | √ | | Evaluate in application context. | |
| Space Station Dynamics | 3 | : | | | Significant experiment opportunity. Requires planning/preparation. | SS-017 |
| Thermal Design | _3 | | | | Combine with other structural dynamics experiments. | MS-14 |
| | 51 | | | | | |

of project-level groups in the complement involved judgements about alternatives for achieving project objectives including mission consolidation and use of the shuttle. A synopsis of the selection rationale is presented in the comments column.

Top-level payload characteristics and resource requirements for the selected missions are presented in Table IV-2. Mission equipment includes primarily attached payload elements with internal controls. However, mission SS-017, the Space Station Structural Characterization Experiment, uses a distributed network of payload elements and therefore does not fit the standard attached or pressurized payload mold.

TABLE IV-2. ACCOMMODATION REQUIREMENTS FOR SPACE STRUCTURE (DYNAMICS AND CONTROL) EXPERIMENTS

| | MISSION | START | EXPT | DEFN | DBL | ATTACH | WEIGH | (di) | PWR | ······································ |
|--|----------|-------|------|------|-----|--------|-------|------------|------|--|
| PROJECT/EXPERIMENTS | CODE | | | | | PORTS | | | (kW) | |
| Segmented Optics | | | | | | | | | | |
| Active Optic Technology | TDMX2421 | 1 | T/D | 3 | 1.8 | 1 | 4620 | 485/ 2m | 0.2 | Sun and Earth avoidance. LHe resupply. |
| Pointing/Isolation | | | | | | | | | | |
| Pointing and Isolation Devices | TDMX2432 | 1 | D | 4 | 0.1 | 1 | 3140 | | 0.3 | Mass includes pointed payload. Combine with TDMX2421. |
| Tribological Effects | | | | | | | | | | |
| Polymeric Materials for Space Mechanisms | SS-016 | 1 | R | 2 | | MPA | 13 | | 0.05 | Small payload. May use Multiple Payload Adapter (MPA). |
| Antennas/Reflectors (Dynamics) | | | | | | | | | | |
| Flight Dynamics Identification | TDMX2071 | 1 | R∕T | 3 | 1 | 1 | 584 | 1/yr | 0.7 | |
| Advanced Adaptive Control | TDMX2411 | 2 | Т | 3 | 1 | sh. | 595 | 1/yr | 1.4 | Uses residual equipment from TDMX2071. |
| Space Station Dynamics | | | | | | | | | | |
| SS Structural Characterization Experiment | SS-017 | 1 | D | 2 | | ٠ | TBD | | 2 | *Includes retroreflectors plus distributed network of sensors. |
| Thermal Design | | | | | | | | | | |
| Thermal Design of Composite Antenna Dish | MS-14 | 5 | Đ | 1 | | | | | | Include under TDMX2071/2411 |

An accommodation scenario for the selected mission complement is depicted in Figure IV-2. The time phasing has been adjusted slightly to minimize the envelope of requirements for rack space and external attachment. Potential outfitting needs for the initial years of this scenario are presented in Table IV-3. It includes items believed to have common-use potential plus key items of standard equipment. Certain standard items such as payload attachment equipment, racks, standard data processors, and keyboard/data display units were taken for granted and do not appear in the lists. Outfitting needs for other space structures projects can be found in Appendix D.

A significant number of the proposed missions in the Space Structure (Dynamics and Control) theme involve large test articles representative of segmented optics, antenna, and spacecraft applications. Since these structures will undoubtedly be expensive to launch and deploy, it is important that each test structure be exploited to the fullest. In this regard the Space Station itself, as the space program's largest structure, represents an important opportunity to pursue technology experiment objectives not only in structural dynamics but also in assembly and thermal design.

Several missions have been proposed that use the Space Station as a dynamics test article. However, the accommodation of dynamics measurement equipment is a matter of concern because it includes a multitude of distributed elements (retroreflectors, accelerometers, acoustic sensors, strain gauges, temperature sensors, etc.) that can more effectively be installed on the ground than through EVA

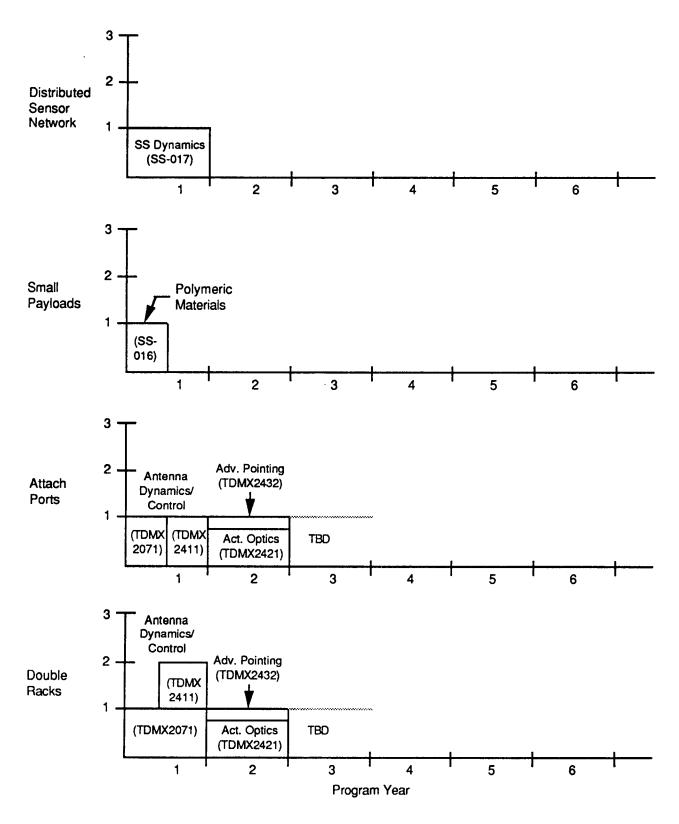


FIGURE IV-2. MISSION SCENARIO FOR SPACE STRUCTURE (DYNAMICS AND CONTROL) THEME

operations. It is imperative therefore that the sensor set needed for technology experimentation be defined at an early date so that every effort can be made to incorporate those sensors into the Space Station design as necessary. It is assumed that some level of instrumentation will be included to verify Space Station structural performance and monitor structural health status. The concern is that these "engineering" measurements may not be adequate to support technology research objectives and that it may not be feasible to install additional sensors once the Space Station is in orbit.

TABLE IV-3. OUTFITTING NEEDS FOR EARLY-YEAR SPACE STRUCTURE (DYNAMICS AND CONTROL) MISSIONS

| | PROGRAM YEAR 1 | | | | | | | | | | | | |
|-------------------------|--|--------------------------|---|------|---|------------|--|--|--|--|--|--|--|
| | ANTENNAS/REFLECTORS | | SPACE STATION DYNA | MICS | TRIBOLOGICAL EFFECTS | | | | | | | | |
| STATUS | ITEM | CAT | ITEM | CAT | ITEM | CAT | | | | | | | |
| Planned | Data recorder, digital Hand tools, EVA general purpose Video recorder Video, external | Std Std Std Std | Data recorder, digital | Std | Contamination monitor Data recorder, digital | PAE Std | | | | | | | |
| Common-Use Potential | Accelerometer package, external Cleaning materials, EVA Computer (VAX 11/780 equivalent) Laser measurement unit Proximity sensor | | Laser measurement unit Retroreflective targets Storage, unpressurized | | Mass spectrometer Radiometer | | | | | | | | |

C. Fluid Management

Following the pattern established in the previous section, mission selection, payload resource requirements, mission time phasing, and potential support equipment needs for the Fluid Management theme are addressed in the next four tables and/or figures. The mission classification scheme is presented in Table IV-4. The mission count numbers indicate that the primary in-space research emphasis for this theme lies in two areas: (1) understanding two-phase fluid phenomena and (2) demonstrating and evaluating cryogen storage technologies. Missions selected for scenario development (identified in the right-hand column) are broadly representative of the range of Fluid Management topics and include a mixture of internal and attached payloads. Top-level payload characteristics and accommodation requirements for the selected missions are presented in Table IV-5. The accommodation scenario is depicted in Figure IV-3.

Potential outfitting needs for the initial years of the scenario are presented in Table IV-6. The combustion and fluid behavior payload equipment will reside within the laboratory module and support research-type mission activities. Both fall within the scope of the MMPF study and an extensive list of outfitting requirements for experiment support can be found in the MMPF data base. The cryogen

TABLE IV-4. SELECTION OF EXPERIMENTS FOR FLUID MANAGEMENT RT&E FACILITY

| SUBTHEME/PROJECTS | COUNT | PATH- FINDER | CSTI | OAST | COMMENTS | SELECTED EXPERIMENTS |
|----------------------------|-------|-----------------|------|------|---|-------------------------|
| Fluid Behavior | | | | | | |
| Helium | 1 | | | å | Requires lab LHe service. Recommended flying on Spacelab. | |
| Liquid Streams | 1 | | | √ | Results needed for advanced radiator concepts | FM-004 |
| Two-Phase Fluids | 5 | | | . √* | Results in technology data bases for advanced two- phase systems | FM-003 |
| Fluid Storage/Transfer | | | | | | |
| Cryogens | 7 | √ | | | Chemical propulsion, life support, and lab support applications. Consider demonstrating in application context. | TDMX2311 |
| Cryogens Helium | 1 | | | | Needed for IR sensors and in-space research | FM-002 |
| Sensors/Gauges | 1 | | | | Consolidate with two-phase fluids experiments | |
| Spacecraft Fire Safety | | | | | | |
| Flame Spread Mechanisms | 그 | | | | Results in improved fire prevention/extinction knowledge for future manned systems | FM-007 |
| TOTAL | 17 | | | | | |

^{*}Preliminary manifesting

TABLE IV-5. ACCOMMODATION REQUIREMENTS FOR FLUID MANAGEMENT EXPERIMENTS

| PROJECT/EXPERIMENTS | MISSION | | EXPT | | | PORTS | | | PWR (kW) | |
|--|----------|-------------|----------|---|---|-------|-----------------------|-------------|-------------|--|
| Liquid Streams | | , , , , , , | <u> </u> | | | | | | | |
| Liquid Stream Space Technology | FM-004 | тво | R/T | 3 | | (1) | 1000 | TBD | 1.0 | Uses 60 ft by 3 ft flight tube |
| Iwo-Phase Fluids | | | | | | | | | | |
| Two-Phase Fluid Behavior and Management | FM-003 | 2 | R/T | 3 | 1 | | 440 | 110/ TBD | 1.3 | Low-g (10 ⁻⁴) |
| Cryogens | | | | | | | | | | |
| Long-Term Cryogenic Fluid Storage Phase I - Storage Phase II - Transfer Phase III - Refrigeration | TDMX2311 | 2 4 5 | D | 4 | | 1 | 4290 +950 +1760 | | 0.1 +2.5 | Low-g (10 ⁻³). Numbers reflect incre- mental buildup of modular system. |
| Cryogens - Helium | ŀ | | | | | | | | | |
| Helium Transfer in Space | FM-002 | 5 | R/D | 3 | | 1 | 7055 | TBD | 0.1 | |
| Flame Soread Mechanisms | | | | | | | | | | |
| Spacecraft Fire Safety Technology | FM-007 | 1 | R/T | 3 | 1 | | 440 | TBD | 2.0 | |

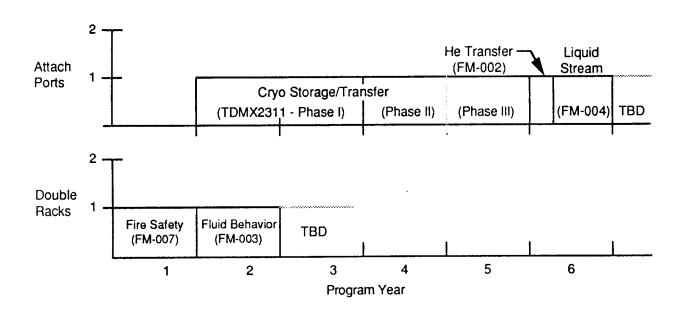


FIGURE IV-3. MISSION SCENARIO FOR FLUID MANAGEMENT THEME

TABLE IV-6. OUTFITTING NEEDS FOR EARLY-YEAR FLUID MANAGEMENT MISSIONS

| • | PR | OGRA | M YEAR 1 | | PROGRAM YEAR 2 | | |
|------------|--|------|---------------------------|-----|-----------------------------------|-----|--|
| | FLAME SPREAD MECHAN | SMS | TWO-PHASE FLUIDS | | CRYOGEN STORAGE/TRANSFER | | |
| STATUS | ITEM | CAT | ITEM | CAT | ITÉM | CAT | |
| Planned | Cleaning Equipment | LSE | | LSE | = | PAE | |
| | Gas storage/resupply | LSS | | LSE | | Std | |
| | Vacuum vent | LSS | | LSE | | Std | |
| | Waste disposal system | LSS | | LSE | | Î | |
| | Data recorder, digital | Std | Acceleration monitor, lab | LSS | | | |
| | Data terminal, graphics | Std | Chemical storage facility | LSS | | ļ | |
| | Video | Std | Vacuum vent | LSS | | i | |
| | Video recorder | Std | Video | Std | | ļ. | |
| | | | Video recorder | Std | | l | |
| Common-Use | Camera, high-speed cinema | | Camera, high-speed cinema | | Leak detector, H ₂ /He | | |
| Potential | Gas chromatograph/mass spectrometer | | Film magazines | | | | |
| | Gas sampling bottles | | | | | | |
| | Image intensifier Interferometer, holographic | | ; | | | | |
| | Laser Doppler anemometer | | | | | | |
| | Photo processor unit | | | | | | |
| | Specimen containers | | | | ' | 1 | |

storage/transfer payload, on the other hand, is a self contained system requiring minimal support for periodic reconfiguration and environmental monitoring. With regard to the items below the line in Table IV-6, the gas chromatograph/mass spectrometer, image intensifier, and high-speed cinema camera are the more likely candidates for outfitting additions. Combustion and fluid behavior experiments proposed for Spacelab relied heavily on high-speed cinema for recording observations. Today it might be possible to meet that need with a high quality video system.

In the way of additional comments, the liquid stream experiment was selected because of advanced radiator and other potential applications. However, this mission is not as well defined as the assigned definition code would suggest, and further definition and refinement will be necessary to achieve viability of the concept. There may also be a role for a precursor pressurized volume (rack-mounted) experiment to study droplet formation and collection before the attached payload described here or the liquid droplet radiator prototypes described later are flown. Finally, none of the mission concepts considered instrumenting fluid systems of the Space Station (including the logistics module) or other space systems. This may be a cost effective way of achieving some of the Fluid Management experiment objectives.

D. Space Environmental Effects

The need to validate predictive models of the Space Station environment and to establish the durability and performance of materials and electronics will create an emphasis on environmental effects experiments early in the Space Station program. The Space Environmental Effects theme includes 28 proposed missions distributed among project groups as indicated in Table IV-7. Missions selected for the strawman scenario are broadly representative of the range of theme interests with the exception of environmental effects on solid rocket motors.

The mission complement includes a mixture of internal and attached payloads. Top-level payload characteristics and accommodation requirements are presented in Table IV-8, and an implementation scenario for the selected missions is depicted in Figure IV-4. Two points are significant. The Mobile Servicing Center with its robotic arm should be an important support system for environment mapping. Secondly, environmental effects experiments typically have preferential mounting requirements with respect to one or more of three key directions -- ram, wake, or solar facing. Thus, mission TDMX2011 is shown as occupying three attachment ports.

TABLE IV-7. SELECTION OF EXPERIMENTS FOR SPACE ENVIRONMENTAL EFFECTS RT&E FACILITY

| | | PATH- | <u> </u> | | | SELECTED |
|------------------------------|----------------|------------------|----------|----------|---|---|
| SUBTHEME/PROJECTS | COUNT | FINDER | CSTI | OAST | COMMENTS | EXPERIMENTS |
| Environment Characterization | | | | | | |
| External Environment | 5 | | | å | Significant impact on operational ground rules and user research interests. | SE-017 |
| Internal Environment | 4 | | | V | Habitability impacts. Coordinate also with data system effects experiments. | AFSE-001, AFSE-002, SE-005, TDMX2521 |
| Environmental Effects | | | | | | |
| Coatings/Surface Effects | 7 | 1 - 1 - | | √* | Include in Space Station LDEF. | TDMX2011 |
| Data System Effects | 3 | ٧ | | å | Coordinate with internal environment radiation measurements. | TDMX2442, TDMX2443 |
| Facilities | 2 | | | | Includes "Wake Shield" and variable gravity facility. | SE-014 |
| Micro-meteroid Impacts | 2 | | | | Include in Space Station LDEF. | SS-010 |
| Solid Rocket Motors | 2 | | | | DoD interest. Accommodate on remote facility for safety reasons. | |
| Structural Materials | <u>3</u> 28 | | | | Include in Space Station LDEF. | AFSE-005 |

^{*}Preliminary manifesting

TABLE IV-8. ACCOMMODATION REQUIREMENTS FOR SPACE ENVIRONMENTAL EFFECTS EXPERIMENTS

| f | MISSION | START | EXPT | DEFN | DBL | ATTACH | WEIGHT | (Ib) | PWR | |
|---|----------|-------|------|------|-----|--------|--------|------------|------|---|
| PROJECT/EXPERIMENTS | CODE | YEAR | TYPE | CODE | | PORTS | | | (kW) | OTHER CONSIDERATIONS |
| External Environment | 1 1 | | | | | | | | | |
| Environmental Contamination Characteristics Experiment | SE-017 | 1 | R | 1 | | TBD | | | | Will likely use the MRMS as a probe positioner for environment mapping. |
| Internal Environment | | i | Ì | | | į | | | | |
| Radiation Measurements Experiment (RME) | AFSE-001 | 0 | R | 3 | ٠ | | 4 | | | *Portable units require storage only. |
| Heavy Ion and Neutron Environ- ments in S/C | AFSE-002 | 1 | R | 1 | TBD | | TBD | | TBD | |
| In-Situ Trace Contaminant Analysis Analysis | SE-005 | 1 | T | 1 | 0.5 | | 250 | | 1.5 | |
| Acoustics Control Technology | TDMX2521 | 1 | T/D | 3 | 0.2 | | 93 | | 0.1 | Mostly portable equipment. |
| Coatings/Surface Effects |] | | | 1 | | | | | | |
| Spacecraft Materials & Coatings | TDMX2011 | 1 | R/T | 4 | | 3 | 2138 | 170/ 3m | 0.5 | Space Station LDEF. Panel/tray assemblies attached in three locations (ram, wake, sun). |
| Data System Effects | | | | | | | | | | (ran, ware, san, |
| Transient Upset Phenomena - VLSI | TDMX2442 | 1 | Т | 4 | 0.2 | | 220 | 22/ 3m | 0.1 | |
| VHSIC Fault Tolerant Processor | TDMX2443 | 1 | Т | 4 | 0.1 | | 220 | 22/ 6m | 0.3 | |
| Facilities | | | | | | į | | 0111 | | |
| Space Ultra-Vacuum Facility: Wake Shield | SE-014 | 1 | D | 3 | | 1 | | | | Equipment characteristics TBD. |
| Micro-Meteroid Impacts | | | | | | | | | | |
| Micro-Meteorite Protection | SS-010 | 4 | R/T | 1 | | 1 | 440 | | | Consolidate with TDMX2011. |
| Structural Materials | | j | | | | | | | | į |
| Composite Durability in Space | AFSE-005 | 1 | R | 1 | | | | |] | Consolidate with TDMX2011. |

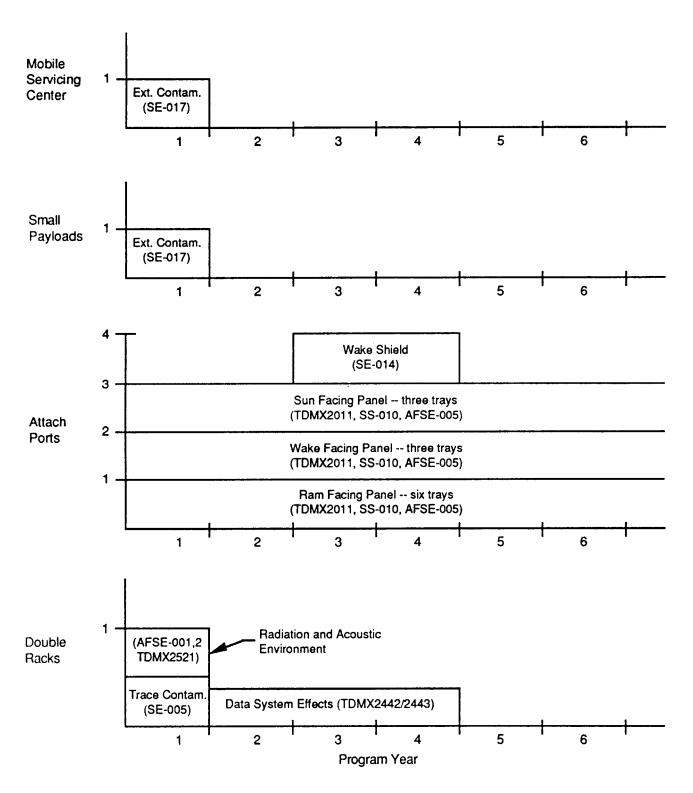


FIGURE IV-4. MISSION SCENARIO FOR SPACE ENVIRONMENTAL EFFECTS THEME

Potential outfitting needs for the Space Environmental Effects theme are listed in Table IV-9. A mass spectrometer is shown as a support item for both environment characterization and effects experiments. It is possible that this need is already covered by the contamination monitoring system.

The accommodation of exposure samples is a matter that may warrant additional study. The experiment system proposed for mission TDMX2011 uses three large panels that serve as a host structure for a number of exposure trays similar to those used on the Long Duration Exposure Facility (LDEF). This system uses little in the way of power and data resources but requires long-term attachment. For this reason an approach should be developed for accommodating exposure samples that doesn't put them in competition with major payloads for attachment and resource interfaces.

TABLE IV-9. OUTFITTING NEEDS FOR EARLY-YEAR SPACE ENVIRONMENTAL EFFECTS MISSIONS

| | PROGRAM YEAR 1 | | | | | | | | | |
|-------------------------|---|--------------------------|---|-----|---|---|--|--|--|--|
| | INTERNAL ENVIRONMEN | VT. | EXTERNAL ENVIRONMEN | ŧΤ | COATINGS/SURFACE EFFECTS | | | | | |
| STATUS | ITEM | CAT | ITEM | CAT | ITEM | CAT | | | | |
| Planned | Battery Charger Dosimeter, passive Storage locker, EM-shielded Data recorder, digital Storage, pressurized | LSE LSE Std Std | | Std | Camera locker Camera, 35 mm Film locker Microscope system Workbench, laboratory sciences Storage, sample Contamination monitor Data recorder, digital Hand tools, EVA general purpose | 1988 1988 1988 1988 1988 1988 1988 1988 | | | | |
| Common-Use Potential | Audiometer Noise dosemeter Noise monitor Power amplifier Radiation monitor, external Radiation monitor, internal Sample containers Sound level meter Tape recorder, audio | | Exposure tray Mass spectrometer Sample containers | | Exposure tray Mass spectrometer Sample containers Stress test machine | | | | | |

E. Energy Systems and Thermal Management

The mission classification scheme for the Energy Systems and Thermal Management theme is presented in Table IV-10. The major areas of interest include electrical power system, propulsion, and heat rejection technologies. Mission equipment for this theme involves primarily large test beds that facilitate the evaluation of advanced technology components and subsystems. Possibilities for consolidating and coordinating experiments are identified in the comments column.

TABLE IV-10. SELECTION OF EXPERIMENTS FOR ENERGY SYSTEMS AND THERMAL MANAGEMENT RT&E FACILITY

| | | PATH- | <u> </u> | | | SELECTED |
|--------------------------------------|-------|--------|----------|------|--|-------------|
| SUBTHEME/PROJECTS | COUNT | FINDER | CSTI | OAST | COMMENTS | EXPERIMENTS |
| Advanced Thermal Control | | | | | | |
| Liquid Droplet Radiators | 4 | | | | Coordinate with fluid behavior research | EP-6, EP-8 |
| Radiator Panel Technology | 3 | | √ | √ | | TDMX2132 |
| Thermal Design/Inter- facing | 2 | | | | Coordinate into thermal control test bed. | TDMX2565 |
| Two-Phase Systems | 4 | | | | | |
| Energy Conversion | | | | | | |
| Dynamic Conversion | 5 | 1 | ٧ | | Demonstrate as SS or platform supplemental power source. | TDMX2153 |
| Laser Systems | 3 | | | | Consider as evolutionary development. | |
| Photovoltaic Systems | 5 | | | | Demonstrate as SS or platform supplemental power source. | TDMX2152 |
| Solar Furnace Technol- ogy | 2 | | | | Consider as evolutionary development. | |
| Power Management and Distribution | | | | | | |
| Environmental Inter- action | 4 | | V | | Combine with photovoltaic/dynamic conversion experiments. | SE-001 |
| Megawatt Systems | 1 | l | | | Consider as evolutionary development. | |
| Propulsion | | | | | | |
| Advanced Propulsion Concepts | 3 | ٧ | | | Consider as evolutionary development or demonstrate/verify in application context. | |
| Contamination Effects | 4 | | | | Coordinate with low thrust experiments. | AFEN-001 |
| Low Thrust | _6 | 1 | | | Use SS for characterization and free-flyer for lifetime tests. | TDMX2321 |
| | 46 | | | | monino tosto. | |

Missions selected for the strawman complement are broadly representative of theme in-space research objectives. Top-level payload characteristics and accommodation requirements are presented in Table IV-11. Mission equipment is intended for either attached payload or coorbiting platform accommodation. No internal equipment is identified.

An implementation scenario for the selected missions is depicted in Figure IV-5. The solar power and radiator test experiments all require solar-inertial pointing. For the solar dynamic test bed this is achieved by placing the payload outboard of the alpha joint on the transverse boom to accommodate it as a growth power system element. The radiator test bed is shown as an attached payload, and a two-axis solar pointing mount would be required to maintain the radiator edge toward the sun. The photovoltaic test bed is shown accommodated on a coorbiting platform, and it is assumed that one- or two-axis gimballing would be built into the payload as required. However, a coorbiting platform may not be available during the early stages of the Space Station program, so configuration of this payload as a free-flyer is identified as an alternative.

TABLE IV-11. ACCOMMODATION REQUIREMENTS FOR ENERGY SYSTEMS AND THERMAL MANAGEMENT EXPERIMENTS

| | MISSION | START | FYDT | DEFN | DBL | ATTACH | WEIGH | IT (ib) | PWR | |
|--|----------|-------|------|------|-----|--------|-------|---------|----------|--|
| PROJECT/EXPERIMENTS | CODE | | | | | PORTS | | | (kW) | |
| Liquid Droplet Radiators | | | | | | | | | <u> </u> | |
| LDR Orifice and Jet Behavior | EP-6 | 2 | T/D | 1 | | 1 | | | | Equipment characteristics TBD. |
| Evaporation Loss Determinarion for LDRs | EP-8 | 2 | т | 1 | | Sh | | , | | Use same equipment as EP-6. |
| Radiator Panel Technology | | | | | | | | | | |
| Advanced Radiator Concepts | TDMX2132 | 5 | T | 4 | | 1 | 397 | | 0.75 | |
| Thermal Design/Interfacing | | | | | | ĺ | | | | |
| Thermal Interface Technology | TDMX2565 | 1 | D | 2 | | 1 | 1760 | | 2.5 | |
| Dynamic Conversion | | | | | | | | | | |
| Solar Dynamic Power Tests | TDMX2153 | 1 | D | 4 | | 1 | 2735 | 220/? | 1 | MRDB defines 20 kW _e system. |
| Photovoltaic Systems | | | | | | | | | | |
| Large Space Power Systems Technology | TDMX2152 | 2 | Т | 2 | | 1 | 1335 | 220/yr | • | *Generales own power. May be configured as a free-flyer. |
| Environmental Interaction (Elec.) | | | | | | | | | | |
| Environmental Interactions | SE-001 | 1 | R/T | 1 | | TBD | | | 1 | Consolidate with TDMX2152. |
| Contamination Effects (Propulsion) | | | j | | Ì | | | | | |
| Space-Based Contamination and Flow-Field Experiments | AFEN-001 | 1 | R | 1 | | | | | | Equipment characteristics TBD. |
| Low Thrust (Propulsion) | | | | | | | | | | |
| Low Acceleration Propulsion Technology | TDMX2321 | 2 | R/T | 2 | | 1 | 55 | | 1.5-5 | |

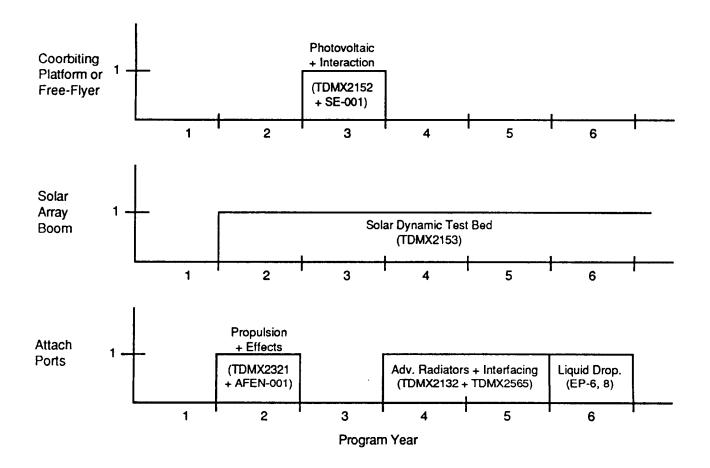


FIGURE IV-5. MISSION SCENARIO FOR ENERGY SYSTEMS AND THERMAL MANAGEMENT THEME

Potential outfitting needs for the initial years of the scenario are presented in Table IV-12. The equipment lists for both the low thrust and photovoltaic systems experiments contain several plasma diagnostic items. Also, it appears that an imaging radiometer may be useful for a number of applications such as observing exhaust plumes, monitoring temperature profiles of radiator panels, and monitoring photovoltaic arrays for hot spots.

TABLE IV-12. OUTFITTING NEEDS FOR EARLY-YEAR ENERGY SYSTEMS AND THERMAL MANAGEMENT MISSIONS

| | PR | OGRA | M YEAR 2 | | PROGRAM YEAR 3 | 3 |
|-------------------------|---|---|--|---|--|-------------------|
| | LOW THRUST AND CONTAMINATION EFFECTS | DYNAMIC CONVERSION |] | PHOTOVOLTIC SYSTEMS AND ENVIRONMENTAL INTERACTION | | |
| STATUS | ITEM | CAT | ITEM | CAT | ITEM | CAT |
| Planned | Microscope system Acceleration monitor, lab Contamination monitor Data recorder, digital Mobile Servicing Center (MSC) Video recorder | LSE LSS PAE Std Std Std Std | | PAE Std Std Std Std | Contamination monitor Data recorder, digital Hand tools, EVA general purpose Video recorder | PAE Std Std |
| Common-Use Potential | Accelerometer package, external Imaging radiometer Mass spectrometer Plasma diagnostic package Plasma ground Potential probe Reflectometer Sample containers | | Camera, 35 mm (EVA) Gas storage/transfer facility Imaging radiometer Pointing mount, two-axis solar Storage, unpressurized | | Exposure tray Imaging radiometer Magnetometer Mass spectrometer Plasma diagnostic package Sun sensor Video, low light (external) | |

F. Automation and Robotics

The mission classification scheme for the Automation and Robotics theme is presented in Table IV-13. After a review of experiment objectives only robotics missions were selected for the theme strawman complement. The evaluation of automation technologies in an operational context characteristically involves a host system, and it was felt that the primary outfitting impacts would be associated with the host systems and not the automation technologies per se. Top-level payload characteristics and accommodation requirements for the selected missions are presented in Table IV-14.

An implementation scenario is depicted in Figure IV-6. Little information was available on the lab robot. However, two double racks were assumed to be a reasonable allocation for storage and support for the lab robot during the first operational year. The Space Robotics Research Laboratory (SRRL) would be installed in the second operational year (delayed one year to minimize the rack space envelope) and require a double rack for a telerobotic workstation and one attachment port. The SRRL will serve as a host facility for a number of robotics experiments. Also in the second year, the OMV with the Flight Telerobotic Servicer would be used to accomplish the Materials Resupply mission.

Potential outfitting needs for the initial years of the scenario are presented in Table IV-15. It was assumed that the lab robot will be a largely self contained system. Also, a number of support items for external robotics may be provided as part of the SRRL.

TABLE IV-13. SELECTION OF EXPERIMENTS FOR AUTOMATION AND ROBOTICS RT&E FACILITY

| SUBTHEME/PROJECTS | COUNT | PATH- FINDER | сѕті | OAST | COMMENTS | SELECTED EXPERIMENTS |
|----------------------------------|-------|-----------------|----------|------|---|----------------------------------|
| Automation | | | | | | |
| Autonomous Control | 2 | √ | V | | Verify in application context using other test beds or operational systems as host. | |
| Rendezvous/Docking | 5 | 1 | | | Verify with Shuttle, OMV, or ELVs as available. | |
| Robotics | Ţ | | | | | : |
| Advanced Concepts | 1 | 1 | | | Long-term. Needs definition. | |
| Free-Flight Dynamics | 2 | 1 | | | Verify with OMV and FTS. | |
| Remote Maintenance/ Servicing | 2 | | ٧ | | Important capability for microgravity, astronomy, and remote sensing operations. | TDMX2563 |
| Teleoperation | _6 | 1 | 1 | å | Significant productivity/operations implications | AR-008, TDMX2473, TDMX2461 |
| TOTAL | 18 | | | | | 1 DIVINZ401 |

^{*}Preliminary manifesting

TABLE IV-14. ACCOMMODATION REQUIREMENTS FOR AUTOMATION AND ROBOTICS EXPERIMENTS

| <u> </u> | MISSION | START | | | | ATTACH | | | PWR | |
|--|----------|-------|------|------|-------|--------|------|------------|------|--|
| PROJECT/EXPERIMENTS | CODE | YEAR | TYPE | CODE | RACKS | PORTS | EXPT | LOG | (kW) | OTHER CONSIDERATIONS |
| Remote Maintenance/Servicing Materials Resupply | TDMX2563 | 2 | D | 2 | | | TBD | тво | | Uses OMV with FTS for remote changeout of material samples. |
| <u>Teleoperation</u> | | · | | | | | | | | |
| Robot for Science Laboratories | AR-008 | 0 | т | 1 | TBD | | 275 | | 0.1 | |
| Space Robotics Research Laboratory (SRRL) | TDMX2473 | 1 | N/A | 2 | 1 | 1 | 7000 | 770/ yr | 1.2 | SRRL facility hardware supports a number |
| Teleoperated Structure Assembly | TDMX2461 | 2 | D | 3 | | Shared | 5510 | | 2.8 | Uses SRRL telerobotic workstation. External hardware mounts on SRRL carrier deck. Coordinates with Mobile Servicing Center (MSC). |

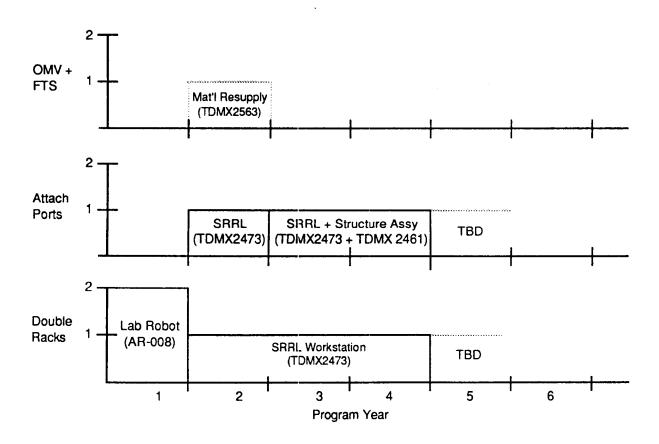


FIGURE IV-6. MISSION SCENARIO FOR AUTOMATION AND ROBOTICS EXPERIMENTS

TABLE IV-15. OUTFITTING NEEDS FOR EARLY-YEAR AUTOMATION AND ROBOTICS MISSIONS

| | PROGRAM YEAR 1 | | PRO | GRAN | A YEAR 2 | | | |
|-------------------------|--------------------------|-------------------------------|--|----------------------|---|---|--|--|
| | TELEOPERATION (LAB F | REMOTE MAINTENANCE/SERVICE | NG | TELEOPERATION (SRRL) | | | | |
| STATUS | ITEM | CAT | ITEM | CAT | ITEM | | | |
| Planned | Video Video recorder | Std Std | Data recorder, digital Video recorder | Std Std | Camera locker Camera, 35 mm Film locker Data recorder, digital Hand tools, EVA general purpose Mobile Servicing Center (MSC) Video recorder Video, external | LSE LSE LSE Std Std Std Std | | |
| Common-Use Potential | Workstation, telerobotic | | OMV (with Smart Front End) OMV support systems Storage, unpressurized Workstation, teleoperations | | (Accelerometer package, external) (Lighting, external) (Storage, unpressurized) (Video, external (SRRL)) Window, optical (Workstation, telerobotic) () Provided by SRRL | | | |

With regard to additional comments, the robotic activities will obviously be video intensive, and there is some concern about demands on the Space Station video system. Moreover, the question is raised as to whether some of the in-space objectives might be achieved by instrumenting the Flight Telerobotic Servicer and the robotic arm of the Mobile Servicing Center.

G. Information Systems

The mission classification scheme for Information Systems is presented in Table IV-16. This theme contained several one-of-a-kind missions as indicated by the project mission counts. Missions selected for the theme straw complement are broadly representative of theme objectives and include a mixture of internal, attached, and platform payloads. Top-level payload characteristics and accommodation requirements for the selected missions are presented in Table IV-17. While most of the numbers are reasonable, TDMX2264, a microwave radiometer, contains a major driver in the form of a 118 m antenna dish.

TABLE IV-16. SELECTION OF EXPERIMENTS FOR INFORMATION SYSTEMS RT&E FACILITY

| SUBTHEME/PROJECTS | COUNT | PATH- FINDER | CSTI | OAST | COMMENTS | SELECTED EXPERIMENTS |
|---------------------------|-------|-----------------|----------|----------|---|-------------------------|
| Communication and | COOKI | Theth | 0311 | UASI | WHINE IT IS | CAPENIMENTS |
| Tracking | | | i | | | |
| Antenna Performance | 2 | | | | Complementary experiments to large antenna deployment | TDMX2211 |
| Component Technologies | 1 | | | | Verify in application context | |
| Propagation | 1 | | | | Potential experiments of opportunity | SE-009 |
| Time Standards | 1 | | | √ | Verify in application context | |
| Tracking Deep Space | 3 | | | | Extend current laser satellite communications capability | TDMX2224 |
| Tracking Proximity | 2 | | | | Tions capability | 1 |
| Data Systems | | | | | | |
| Controls/Displays | 4 | | ٧ | | Potential productivity benefits. Combine with human factor experiments. | CH-1, CH-2 |
| Sensors | | | | | | |
| Defense | 1 | | | | 1 | |
| Electro-Optical Sensors | 4 | | | ۷٠ | Combine into conceptants also assumed | TDMX2262 |
| Lidars | 1 | | √ | 1 | Combine into sensor technology research facility | |
| Radars/Radiometers | 3 | | | V |) | TDMX2265, TDMX2264 |
| Radio Astronomy | _1 | | | | Assume operational system on platform/free-flyer | |
| TOTAL | 24 | İ | | l | | |

^{*}Preliminary manifesting

TABLE IV-17. ACCOMMODATION REQUIREMENTS FOR INFORMATION SYSTEMS EXPERIMENTS

| | MISSION | START | EVOT | DEEN | DBL | ATTACH | WEIGHT | (lb) | PWR | |
|---|----------|----------|------|------|-----|--------|--------|------|------|---|
| PROJECTS/EXPERIMENTS | CODE | | | | | PORTS | | | (kW) | OTHER CONSIDERATIONS |
| Antenna Performance | | | | | | | | | | |
| Multi-Ftn Space Antenna Ring Tech | TDMX2211 | 2 | т | 3 | 0.5 | 1 | 860 | TBD | 0.7 | Uses OMV as mobility platform for RF illuminator |
| Propagation | | | | | | | | | | |
| 40-105 GHz Propagation Experi- ments | SE-009 | 3 | R | 1 | | 1 | 880 | | 0.5 | Earth pointing |
| Tracking Deep Space | | | | | | | | | | |
| Space-Based Optical DSN Terminal | TDMX2224 | 2 | Т | 3 | | 1 | 440 | TBD | 1.0 | Uses OMV and Payload Pointing System |
| Controls/Displays | | | | | | | | | | |
| Physiological Control Systems in Low-g | CH-1 | 2 | D | 1 | TBD | | TBD | | | |
| Adv. Control/Display Concepts in Low-q | CH-2 | 7 | ۵ | 1 | TBD | | TBD | | | |
| Electro-Ootical Sensors | | <u> </u> | | | | | | | | |
| Manned Observations Techniques | TDMX2262 | 1 | T/D | 2 | TBD | 1 | TBD | 130/ | тво | Uses Payload Pointing System (PPS) |
| Radars/Radiometers | | | | | | | | | | |
| Satellite Doppler Meteorological Radar | TDMX2265 | 1 | D | 4 | | PP | 4940 | | 1.5 | Downscaled TDMX2265. Flies on Polar Platform. |
| Microwave Remote Sensing - Passive | TDMX2264 | 6 | D | 4 | | COP | 9040 | | 0.5 | 118m diameter antenna flies on co- orbiting platform |

An implementation scenario for the selected missions is depicted in Figure IV-7, and potential outfitting needs for the first two years of the scenario are presented in Table IV-18. The Electro-optical Sensors mission (Manned Observations) involves photographic activities using a hand-held camera as well as the control of pointed payloads mounted externally. For the Controls/Displays mission a set of support equipment was identified that would provide a programmed stimulus to the operator and would monitor operator response and physiological state for comparison with Earth-based experiments. It was assumed that the control unit would be a user-provided item. The deep space network (DSN) terminal experiment uses the OMV as a cooperative target.

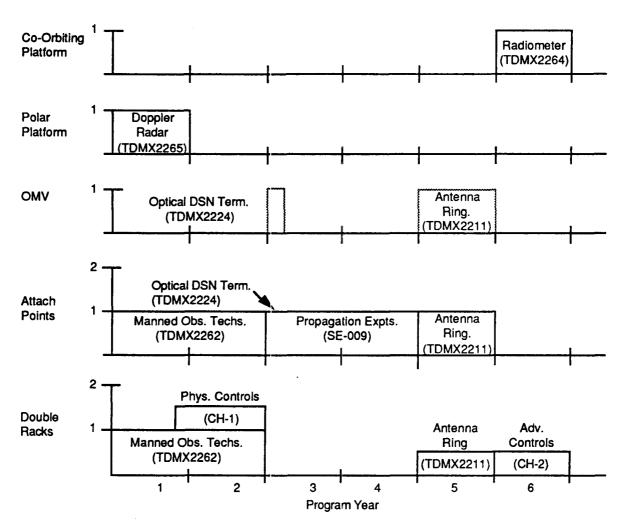


FIGURE IV-7. MISSION SCENARIO FOR INFORMATION SYSTEMS THEME

TABLE IV-8. OUTFITTING NEEDS FOR EARLY-YEAR INFORMATION SYSTEMS MISSIONS

| | PROGRAM YEAR 1 | | Pi | ROGR | AM YEAR 2 | | |
|-------------------------|--|------------|---|--------------------------|--|---------------------------------|--|
| | ELECTRO-OPTICAL SENSO | PRS | CONTROLS/DISPLAYS | | TRACKING DEEP SPACE | | |
| STATUS | ITEM | CAT | ITEM | CAT | ITEM | CAT | |
| Planned | Film locker Attitude Determination System (ADS) Contamination monitor Payload Pointing System (PPS) Data recorder, digital Video | PAE PAE | | LSE Std Std Std | Attitude Determination System Contamination monitor | LSE PAE PAE PAE Std | |
| Common-Use Potential | Battery storage Window, high-quality ວຊາ'cal | | Computer, graphics/experiment control Computer-video generator Data recorder, audio Graphics display, high resolution Physiological monitor Speech generator Tape recorder, audio Visual task generator | | Accelerometer package, external OMV OMV support systems Storage, unpressurized | | |

H. In-Space Operations

The In-Space Operations theme encompasses a highly diverse set of technologies as indicated by the mission classification scheme presented in Table IV-19. The missions selected for the strawman complement are representative of specific areas of the theme and, as it turned out, they consist entirely of pressurized volume (internal) payloads. Top-level payload characteristics and accommodation requirements for the selected missions are presented in Table IV-20.

An implementation scenario for the selected missions is depicted in Figure IV-8. Start years have been stretched in some cases to keep the experiment equipment within a four-rack envelope. Additional rack space would be required for support equipment.

Potential outfitting needs for the initial years of the scenario are presented in Table IV-21. Equipment sets representative of the other missions can be found in Appendix D. The semiconductor growth experiment overlaps microgravity research activities sponsored by other NASA organizations, and its outfitting needs are well covered by current outfitting plans. Likewise, the crew health experiment may need equipment that is a part of the Health Maintenance Facility, but the degree to which such equipment will be available for experiment use is not clear.

Table IV-21 illustrates very well the situation uncovered throughout the seven themes. Within focused areas of research (such as crew health, human factors, etc.) needs were identified for items that could be provided as common support equipment. In general, however, the need for such items is not widely shared either within the broad scope of the total mission set or within the more limited scope of the individual themes.

TABLE IV-19. SELECTION OF EXPERIMENTS FOR IN-SPACE OPERATIONS RT&E FACILITY

| TABLE IV-19. SELECT | TION (| | PERIN | ME:NTS | FOR IN-SPACE OPERATIONS RT& | E FACILITY |
|-----------------------------------|--------|-----------------|-------|--------|--|----------------------|
| SUBTHEME/PROJECTS | COUNT | PATH- FINDER | CSTI | OAST | COMMENTS | SELECTED EXPERIMENTS |
| Biomedical | 1 | 1 | | 1 | COMMITTE | EXPENIMENTS |
| Bends Avoidance/ Therapy | 3 | ٧ | | | Include in flight crew health research facility | |
| Diagnosis/Treatment | 1 | 4 | | | Improved capability for emergency treatment and long-duration health maintenance | TDMX2531 |
| Physiological Effects of Low-g | 4 | ٧ | | 1 | Include in flight crew health research facility | SO-007a |
| Human Factors | · | | | | | |
| Cognition | 4 | V | | | | CH-6 |
| Crew Productivity | 1 | √ | | | Consolidate into human factors research facility | |
| Interaction | 4 | 7 | ٧ | | , | СН-3 |
| Maintenance, Repair, and Test | | | | | | |
| <u>Test</u> | | | | | 1 | |
| Cleaning/Refurbishment | 3 | | | | | |
| Inspection/Test | 1 | | | | Do as checkout of operational maintenance/servicing systems | |
| Satellite Servicing | 4 | ٧. | | |) | |
| Material Processing | | | | | | |
| Composites | 2 | | | | | AFSO-005 |
| Crystal Growth | 2 | | | | Include in microgravity facility | TDMX2022 |
| Fluids | 4 | | - 1 | | | TDMX2024 |
| Materials Characteriza- tion | 1 | | | | Accomplish under individual experiments | |
| Process Technology | 4 | V | | | Re-examine need for in-space experiments | |
| Sample Handling/Storage | 1 | V | | | Do as checkout of operational system | İ |
| Solid Propellants | 2 | | | | Safety Concerns | |
| Systems/Facilities | 1 | | | - | | |
| CELSS | 4 | | | | Explore selected aspect of closed cycle | SS-1 |
| Manned Systems | 1 | 1 | | | Involves checkout of manned Mars capsule | |
| отv | 3 | | | | Consider as evolutionary development | |
| Reentry Systems | 2 | 1 | 1 | | May better be done from Shuttle/ELVs | ; |
| Technology Evaluation | 1 | | |]. | Accomplish within individual experiments | |
| Tethers | _5 | V | | | Significant accommodation impacts | ĺ |
| TOTAL | 57 | | | | | |

TABLE IV-20. ACCOMMODATION REQUIREMENTS FOR IN-SPACE OPERATIONS EXPERIMENTS

| | MISSION | START | | | | ATTACH | | | PWR | |
|--|----------|-------|------|------|-------|--------|------|------------|------|--------------------------|
| PROJECT/EXPERIMENTS | CODE | YEAR | TYPE | CODE | RACKS | PORTS | EXPT | LOG | (kW) | OTHER CONSIDERATIONS |
| Diagnosis/Treatment | | | | | | | | 1 | | |
| Surgery Technology Development | TDMX2531 | 3 | T/D | 2 | 2 | | 220 | TBD | 0.3 | |
| Physiological Effects of Low-o | | | | | | | | | | |
| Flight Crew Health | SO-007a | 1 | R | 1 | 3 | | 980 | TBD | 0.36 | |
| Cognition | | | | | | | | | | |
| Visual Space Perception | CH-6 | 1 | R | 1 | 1 | | TBD | | <0.5 | |
| Interaction | | | | | | | | | | |
| Eval. of Human Fine Motor Performance | CH-3 | 1 | R | 1 | 1 | | TBD | | <0.5 | |
| Composites | | | | | | | | | | |
| Space Fiber Production | AFSO-005 | 4 | Т | 1 | TBD | | тво | | | Microgravity environment |
| Crystal Growth | | | | | | | | | | |
| Growth of Comp. Semicond. Crystals | TDMX2022 | 1 | D | 2 | 1 | | 440 | 150/ m | 2.5 | Microgravity environment |
| Fluids | | | | | | | | | | |
| Electrophoresis Separation Technology | TDMX2024 | 1 | T/D | 4 | 1.5 | | 990 | 550/ 6m | 1.0 | Microgravity environment |
| CELSS | | | | | | | | | | |
| Plant Growth Chamber | SS-1 | 1 | Д | 1 | 2-3 | | TBD | TBD | 1-5 | |

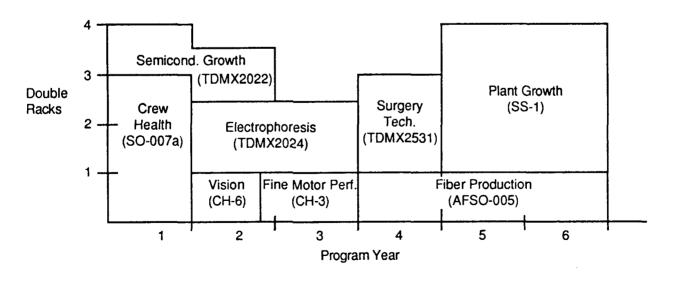


FIGURE IV-8. MISSION SCENARIO FOR IN-SPACE OPERATIONS

TABLE IV-21. OUTFITTING NEEDS FOR EARLY-YEAR IN-SPACE OPERATIONS MISSIONS

| | PROGRAM YEAR 1 | | PRO | GRAI | YEAR 2 | |
|-------------------------|---|-------------------|--|------|---|--------------------------|
| | CREW HEALTH | | SEMICONDUCTOR GROWT | | HUMAN FACTORS | |
| STATUS | ITEM | CAT | ITEM | CAT | ITEM | CAT |
| Planned | Freezer Refrigerator Data recorder, digital | LSE LSE Std | Cleaning equipment Cutting/polishing system Etching equipment Fluid handling tools Hand tools, general purpose Mass measurement device, small Microscope system Multimeter, digital X-ray system Glovebox, materials processing Workbench, laboratory sciences Acceleration monitor, lab Chemical storage facility Waste disposal system | LSE | Data recorder, digital Video Video recorder | LSE Std Std Std |
| Common-Use Potential | Amplifiers Blood sample kit Centrifuge Dynamometer Electrode impedance meter Ergometer Plethysmograph Tape recorder, audio Treadmill Urine sample kit | | Hall probe Optical pyrometer Video, high resolution | | Anechoic chamber Computer-video generator Data recorder, audio Electrode impedance meter Graphics display, high resolution Joystick Physiological monitor Speech generator Visual pulse generator Visual task generator | |

I. Cross-Theme Relationships in the Mission Set

The previous sections addressed theme-oriented mission groups as the basis for in-space laboratory facilities. However, there are complementary relationships among project-level technology thrusts that cut across theme boundaries, and the potential exists for defining coordinated RT&E facilities that accommodate multiple objectives. The more significant relationships as they pertain to the set of 241 missions in the study set are presented in Table IV-22.

TABLE IV-22. COMPLEMENTARY PROJECT OBJECTIVES MAY PROVIDE A BASIS FOR COORDINATED RT&E FACILITIES

| COORDINATED | | |
|--------------------|--------------------------------|--|
| RT&E FACILITY | RELATED PROJECT GROUPS | |
| Large Structures | Large Structures (General) | Space Structure (Dynamics and Control) |
| | Thermal Design | Space Structure (Dynamics and Control) |
| | Sensors/Actuators | Space Structure (Dynamics and Control) |
| | Assembly | Space Structure (Dynamics and Control) |
| | Teleoperations | Automation and Robotics |
| | Structural Materials | Space Environmental Effects |
| Large Antennas | Antennas/Reflectors | Space Structure (Dynamics and Control) |
| | Sensors/Actuators | Space Structure (Dynamics and Control) |
| | Thermal Design | Space Structure (Dynamics and Control) |
| | Antennas Performance | Information Systems |
| | Radars/Radiometers | Information Systems |
| | Radio Astronomy | Information Systems |
| Segmented Optics | Segmented Optics | Space Structure (Dynamics and Control) |
| | Antennas/Reflectors | Space Structure (Dynamics and Control) |
| 1 | Assembly | Space Structure (Dynamics and Control) |
| | Thermal Design | Space Structure (Dynamics and Control) |
| | Pointing/Isolation | Space Structure (Dynamics and Control) |
| | Cryogens-Helium | Fluid Management |
| Solar Thermal | Antennas/Reflectors | Space Structure (Dynamics and Control) |
| | Dynamic Conversion | Energy Systems and Thermal Management |
| | Solar Furnace Technology | Energy Systems and Thermal Management |
| Controls and Human | Controls/Displays | Information Systems |
| Factors | Cognition | In-Space Operations |
| | Interaction | In-Space Operations |
| | Physiological Effects of Low-g | In-Space Operations |
| | Autonomous Control | Automation and Robotics |
| Thermal Control | Radiator Panel Technology | Energy Systems and Thermal Management |
| | Thermal Design/Interfacing | Energy Systems and Thermal Management |
| | Two-Phase Systems | Energy Systems and Thermal Management |
| Spacecraft Systems | Assembly | Space Structure (Dynamics and Control) |
| | Attitude Control | Space Structure (Dynamics and Control) |
| | Satellite Servicing | In-Space Operations |
| | Photovoltaic Systems | Energy Systems and Thermal Management |
| | Low Thrust | Energy Systems and Thermal Management |
| Electric Power/ | Photovoltaic Systems | Energy Systems and Thermal Management |
| Propulsion | Environmental Interaction | Energy Systems and Thermal Management |
| | Low Thrust | Energy Systems and Thermal Management |
| | Contamination Effects | Energy Systems and Thermal Management |

V. CONCLUSIONS

Descriptive materials on a set of 241 mission concepts have been reviewed to establish preliminary Space Station outfitting requirements for technology development. These missions cover, in a representative way, the full range of in-space technology development activities envisioned for the early years of Space Station operations and include both pressurized-volume and attached payloads. Identified requirements were compared with outfitting plans for the life sciences and microgravity user communities and the following conclusions were drawn:

- The great majority of accommodation requirements for technology payloads are captured by Space Station standard accommodations and current outfitting plans.
- A number of potential outfitting additions were identified; however, inputs from technology PIs are essential to refine and validate these findings and to establish priorities and performance specifications for equipment development.
- While the Space Station must support all types of technology missions, technology payload
 planning should emphasize research- and development-phase missions and de-emphasize
 demonstration-phase missions. The latter can be sponsored by major system projects as part
 of advanced development and operational checkout activities.
- Some experiment objectives may be achieved by taking advantage of the Space Station itself as a test article of opportunity. If suitably instrumented, it could be an important source of data on structural dynamics. Likewise, the MSC and fluid systems (including the logistics module) may provide useful data points on robotics and fluid management technologies.
- The mission set contains several distributed experiment systems, and a recommended approach for accommodating such payloads needs to be developed. Several other accommodation issues were raised relating to exposure samples, solar-pointed payloads (solar arrays, radiator test panels, etc.), and robotics.
- A number of research interests could benefit from the consolidation of objectives around special-purpose research facilities (e.g., Space Station LDEF, a Human Factors Research Facility, etc.)
- The scope of the technology mission set overlaps microgravity and life sciences (especially health maintenance) research interests.
- Some experiment concepts are becoming outdated due to continued progress in NASA and DOD technology programs.

In response to these conclusions several recommendations are made for follow-up actions in support of NASA planning for technology payload development and Space Station utilization.

• Develop and maintain a technology mission model that reflects a realistic and appropriate role for in-space research, test, and evaluation. Such a mission model can play an important role as a point of reference for a variety of study and planning activities. Toward this end it is

recommended that the technology thrusts be focused and prioritized taking into account future system needs, DOD and commercially sponsored developments, and NASA organizational charters. Likewise, it is recommended that applied research and component technology missions be emphasized and that mission start years reflect a supportable time phasing.

- Update and refine individual mission concepts to provide the necessary definition data for accommodation studies. This effort should consolidate experiment objectives as appropriate, identify needed support equipment, consider opportunities to use the Space Station itself as a test object, and address conceptually the packaging of payload equipment for delivery to orbit.
- Perform accommodation studies to identify, explore, and resolve mission accommodation issues. Such studies should address the complete mission cycle.
- Involve technology PIs in validating and refining the outfitting equipment needs identified in the current study.

APPENDIX A. Reference Documents for Mission Requirements

A set of 37 government-furnished report volumes constituted the primary source of descriptive information on technology development mission characteristics and requirements. Each volume was assigned a log number that was used for reference purposes during the course of the study. Reports printed in multiple volumes such as the proceedings of the Williamsburg workshop were assigned multiple log numbers to facilitate requirements traceability. The volumes are listed here in log-number sequence.

- 1. Space Station Experiment Definition: Liquid Droplet Radiator Test Bed, Sverdrup Technology Inc. for NASA/Lewis Research Center, Task order No. 5405-03, Revised January 24, 1986.
- 2. <u>Concept Definition for Space Station Technology Development Experiments</u>, Experiment Definition, NASA CR-178153, Research Triangle Institute for NASA/Langley Research Center, Contract NAS1-17639, April 1986.
- 3. Conceptual Definition of a Technology Development Mission for Advanced Solar Dynamic Power Systems, NASA CR-179482, Sverdrup Technology, Inc. for NASA/Lewis Research Center, Contract NAS3-24105, July 1986.
- 4. Concept Definition for Space Station Technology Development Experiments, Preliminary Mission Concept Development, RTI/3042/08-01F, Research Triangle Institute for NASA/ Langley Research Center, Contract NAS1-17639, September 1986.
- 5. <u>Mission Requirements Data Base Data Diagnostic Report</u>, JSC- 20798, NASA/Johnson Space Center, March 1987.
- 6. <u>Planning Guide for In-Space Technology Experiments Using the National Space Station Complex</u>, Executive Summary, General Research Corporation for NASA/Office of Aeronautics and Space Technology (Code RS), Contract NASW-4138, First Edition 1986.
- 7. Planning Guide for In-Space Technology Experiments Using the National Space Station Complex, General Research Corporation for NASA/Office of Aeronautics and Space Technology (Code RS), Contract NASW-4138, First Edition 1986.
- 8. <u>Space Station Technology Development Mission Analysis</u>, Battelle, Columbus Division for NASA/Lewis Research Center, Contract NAS3- 23895, August 15, 1986.
- 9. <u>Space Station Technology Development Mission Experiment Definition Study, Final Report, JPL D-2395, NASA/Jet Propulsion Laboratory, October 1985.</u>
- 10. <u>Space Station Structural Performance Experiment</u>, Task 5 Final Report, Boeing Aerospace Company for NASA/Langley Research Center, Contract NAS1-18224, August 29, 1986.
- 11. <u>IOC Model Technology Experiments Evaluation</u>, Task 4 Final Report, NASA TM-100656, Boeing Aerospace Company for NASA/Langley Research Center, Contract NAS1-18224, January 30, 1987.

- 12. <u>In-Space Research, Technology and Engineering (RT&E) Workshop</u>, Volume 1: Executive Summary, NASA/Langley Research Center and NASA/Office of Aeronautics and Space Technology, October 1985.
- 13. <u>In-Space Research, Technology and Engineering (RT&E) Workshop, Volume 2: Space Structure (Dynamics and Control), NASA/Langley Research Center and NASA/Office of Aeronautics and Space Technology, October 1985.</u>
- 14. <u>In-Space Research, Technology and Engineering (RT&E) Workshop</u>, Volume 3: Fluid Management, NASA/Langley Research Center and NASA/Office of Aeronautics and Space Technology, October 1985.
- 15. <u>In-Space Research, Technology and Engineering (RT&E) Workshop,</u> Volume 4: Space Environmental Effects, NASA/Langley Research Center and NASA/Office of Aeronautics and Space Technology, October 1985.
- 16. <u>In-Space Research, Technology and Engineering (RT&E) Workshop</u>, Volume 5: Energy Systems and Thermal Management, NASA/Langley Research Center and NASA/Office of Aeronautics and Space Technology, October 1985.
- 17. <u>In-Space Research, Technology and Engineering (RT&E) Workshop</u>, Volume 6: Information Systems, NASA/Langley Research Center and NASA/Office of Aeronautics and Space Technology, October 1985.
- 18. <u>In-Space Research, Technology and Engineering (RT&E) Workshop</u>, Volume 7: Automation and Robotics, NASA/Langley Research Center and NASA/Office of Aeronautics and Space Technology, October 1985.
- 19. <u>In-Space Research. Technology and Engineering (RT&E) Workshop</u>, Volume 8: In-Space Operations, NASA/Langley Research Center and NASA/Office of Aeronautics and Space Technology, October 1985.
- 20. <u>TDMX2066 Large Inflatable/Rigidized Structures</u>, Final Review, Wyle Laboratories for NASA/Marshall Space Flight Center, Contract NAS8-36410, August 22, 1986.
- 21. <u>Conceptual Definition On-Orbit Generic Maintenance Test-Bed</u>, Phase V Summary Report Presentation, Rockwell International for NASA/Kennedy Space Center, Contract NAS10-11095, January 9, 1987.
- 22. <u>Space Transportation System Maintenance Technology Study</u>, Phase IV Summary Report, KLO-86-004, Rockwell International for NASA/Kennedy Space Center, Contract NAS10-11095, May 30, 1986.
- 23. Advanced Photovoltaic Test Bed Study, Technical Presentation to NASA's Technology Development Advocacy Group (TAG), Ford Aerospace & Communications Corporation for NASA/Lewis Research Center, Contract NAS3-24664, July 14, 1986.
- 24. <u>LDR Structural Experiment Definition</u>, Task 6 Final Report, NASA TM-10018, Boeing Aerospace Company for NASA/Langley Research Center, Contract NAS1-18224, January 30, 1987.

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APPENDIX B. TECHNOLOGY MISSION SET

The technology mission set is presented here grouped by theme, subtheme, and project according to the classification scheme described in Section II.C. Missions included in the January 1987 edition of the Mission Requirements Data Base (MRDB) are identified by an asterisk.

Each mission was assigned a code that served as a key entry in the computerized data base. Codes from the MRDB, the Battelle report, and other sources were used where available. Otherwise one was invented. The invented codes are recognizable by a three-digit numerical string and include an alphabetic prefix that, in general, identifies the theme. Air Force missions were assigned codes that begin with 'AF'. A lower case alphabetic suffix was used to indicate either multiple phases of a mission or subsidiary experiments. These additional entries were not included in the total mission count.

With regard to the other columns, TDMX mission names were entered exactly as they appear in the MRDB. Other mission/experiment names were abbreviated to fit within the selected character count (40 characters). The research, development, and demonstration mission types described in Section II.D are represented by R, T, and D, respectively. Where the type identifier appears in parentheses, a mission type was inferred based on the system description presented. Finally, the year is the requested start year relative to Space Station initial operation. Year 0 signifies a possible shuttle/Spacelab flight in advance of Space Station.

SPACE STRUCTURE (DYNAMICS AND CONTROL)

SUBTHEME: Advanced Structures

| MSN | | | MSN | |
|--------------------|--|--------------------|------|----|
| CODE | MISSION_NAME | ORG | TYPE | ΥR |
| Assembly | | | | |
| SS-008 | EVA Large Structure Assembly | MDAC-HB | D | 0 |
| * TDMX2061 | Large Space Structures | NASA/MSFC | D | 1 |
| * TDMX2062 | Space Station Modifications | NASA/MSFC | D | 1 |
| * TDMX2063 | On Orbit Spacecraft Assy/Test | NASA/MSFC | T/D | 2 |
| SS-012 | Large Deployable Reflector SS Impact | LMSC/ARC | D | 6 |
| Seamented Opt | ics | | | |
| * TDMX2421 | Active Optic Technology | NASA/ARC | T/D | 1 |
| SS-004 | Precision Optical System Assembly | BAC-Seattle | D | 3 |
| SS-013 | TDM for Large Deployable Reflector | Kodak/ARC | D | 4 |
| Thin Film/Inflatal | ole Structures | | | : |
| AFSO-004 | Thin Film Deployment Feasibility Expt. | AFRPL/XRX | T | 2 |
| AFSO-006 | Bubble Structure Technology | AFRPL/XRX | R/T | 2 |
| MS-13 | Injection Molding of Structural Elements | Battelle | T | 3 |
| SS-014 | Structural Concepts Research Facility | MIT | T | 3 |
| * TDMX2066 | Inflatable/Rigidizable Struc. Ele | NASA/MSFC | D | 4 |
| Trusses | | | | |
| MS-12 | Space Frame Pyramid Stiffening | Battelle | D | 3 |
| <u>Weldina</u> | | | | |
| SO-006 | On-Orbit Welding | MM-Michoud | D | 0 |
| | - | Aero. | | |
| * TDMX2065 | Ion Beam Cold Welding | NASA/LeRC | Ð | 1 |
| TDMX2581c | Electron Beam Welding Experiment | NASA/KSC | D | 4 |

SPACE STRUCTURE (DYNAMICS AND CONTROL)

SUBTHEME: Mechanisms/Controls

| MSN | | | MSN | - |
|-------------------------|--|-----------|------|----|
| CODE | MISSION NAME | ORG | TYPE | ΥR |
| Attitude Control | | | | |
| SS-005 | Attitude Control and Energy Experiment | NASA/GSFC | T | 1 |
| • TDMX2431 | Advanced Control Device Tech | NASA/LaRC | D | 3 |
| Pointing/Isolation | 1 | | | |
| * TDMX2432 | Pointing and Isolation Devices | NASA/LaRC | D | 1 |
| AR-002 | Astrometric Telescope Auto. Operation | NASA/ARC | (D) | 3 |
| SS-6 | Acceleration Reduction Chamber | Battelle | T/D | 4 |
| Sensors/Actuato | <u>rs</u> . | | | |
| SS-001 | Fiber Optic Sensors in Space Appl. | MDAC-HB | D | 1 |
| * TDMX2072 | S/C Strain and Acoustic Sensors | NASA/LaRC | D | 1 |
| AFSS-001 | Sensor/Actuator Interactions | AFRPL/XRX | T | 2 |
| MS-11 | Adv. Mechanisms and Control System Comp. | Battelle | Т | 4 |
| MS-15 | Appl. of Al/Expert Sys. for Struc. Mon. | Battelle | D | 4 |
| Tribological Effec | its | | | |
| EP-3 | Solid Film Lubri. of Bearings and Joints | Battelle | T | 1 |
| EP-4 | Dyn. of Rotating Mach. During Maneuvers | Battelle | Τ | 1 |
| EP-5 | Oil Lubrication of Bearings and Joints | Battelle | T | 1 |
| SS-016 | Polymeric Materials for Space Mechanisms | NASA/LeRC | R | 1 |
| SS-011 | Environ. Influence on Struc. Dynamics | MIT | R | 3 |

SPACE STRUCTURE (DYNAMICS AND CONTROL)

SUBTHEME: Structural Dynamics

| MSN CODE | MISSION NAME | ORG | MSN TYPE | YR |
|------------------------------|--|-----------|-------------|--------|
| Antennas/Reflec | tors | | | |
| SS-002 | Control of Flexible Structures | NASA/LaRC | Т | 0 |
| TDMX2071 | Flight Dynamics Identification | NASA/JPL | R/T | 1 |
| TDMX2111 | Deploy Large Solar Concentrator | NASA/LaRC | D | 1 |
| SS-009 | Large Space Reflectors Flt Expts on SS | NASA/JPL | T | 2 |
| SS-018 | Large Space Antenna (Reflectors) | | T | 2 |
| TDMX2411 | Advanced Adaptive Control | NA\$A/JPL | T | 2 |
| TDMX2412 | Distributed Control Experiment | NASA/JPL | T/D | 2 |
| SS-015 | Large Space Structures Disturb. Supress. | NASA/JPL | T/D | 3 |
| * TDMX2413 | Dynamic Disturbance Experiment | NASA/JPL | T/D | 3 |
| EP-10 | Shape Control for Solar Concentrator | Battelle | T/D | 4 |
| * TDMX2064 | Advanced Antenna Assy/Perform. | NASA/MSFC | D | 6 |
| Large Structures | (General) | | | |
| MS-8 | Dynamic Behavior of Structures in Space | Battelle | Т | 1 |
| SS-007 | In-Space Actively Controlled Structures | NASA/GSFC | T | 1 |
| MS-5 | Damping Response of Struc. Element Matls | Battelle | T | 4 |
| Space Station Dv | namics | | | |
| SS-017 | SS Structural Characterization Expt. | NASA/LaRC | D | 1 ' |
| * TDMX2073 | Adv. Struct. Dyn/Controls | NASA/LaRC | T/D | 1 |
| TDMX2414 | Advanced Controls | NASA/LaRC | Τ | 1 |
| Thermal Design | | | | ì |
| Thermal Design | Thomas Decreases of Christians in Conse | Dattalla | ~ | |
| MS-9 | Thermal Response of Structures in Space | Battelle | Ţ |] |
| * TDMX2422 | Thermal Shape Control Thermal Position of Composite Antenna Dieb | NASA/LaRC | T D | 1 5 |
| MS-14 | Therm. Design of Composite Antenna Dish | Battelle | ע | 3 |

FLUID MANAGEMENT

SUBTHEME: Fluid Behavior

| MSN CODE | MISSION NAME | ORG | MSN TYPE | YR |
|--------------------------|--|----------------|-------------|-----|
| Helium FM-009 | Quantized Vortex Structure in SfHe | NASA/JPL | R | 1 |
| Liquid Streams FM-004 | Liquid Stream Space Technology Facility | Univ. So. Cal. | R/T | TBD |
| Two-Phase Fluid | <u>is</u> | | | |
| AFFM-001 | Two-Phase Fluids for Heat Transport Sys. | AFWAL/POOC | R | 0 |
| FM-010 | Liquid-Vapor Flow in Microgravity | GDC/JSC | R | 0 |
| EP-1 | Evaporation and Condensation Phenomena | Battelle | R | 1 |
| AFEN-002 | Two-Phase Fluid Heat Transfer Correl. | AFWAL/FI | R | 2 |
| FM-003 | Two-Phase Fluid Behavior and Management | NASA/LeRC | R/T | 2 |

SUBTHEME: Fluid Storage/Transfer

| MSN CODE | MISSION NAME | ORG | MSN TYPE | ΥR |
|------------------------------|--|--------------------|-------------|----|
| Cryogens | | | | |
| FM-005 | Cryogenic Fluid Management Facility | NASA/LeRC | T/D | 0 |
| AFFM-003 | Sorption Compressor Refrigeration Sys. | AFWAL/FI | D | 2 |
| FM-001 | Long-Term Cryo. Storage Facility Demo. | GDC/MSFC | D | 2 |
| • TDMX2311 | Long-Term Cryogenic Fluid Storage | NASA/LeRC | Ď | 2 |
| TDMX2572 | Cryo Prop Transfer/Stor/Relig | NASA/MSFC | D | 2 |
| AFFM-004 | Magnetic Refrig. Space Flight Validation | AFWAL/FI | D | 3 |
| AFFM-002 | Passive/Active Cooling for Cryo. | AFRPL/XRX | D | 4 |
| Cryogens Heli | um | | | |
| FM-002 | Helium Transfer in Space | NASA/ARC | R/D | 5 |
| Sensors/Gauge | e | | | |
| FM-008 | Ultrasonic Fluid Measurement | Worcester Poly. | Т | 0 |

SUBTHEME: Spacecraft Fire Safety

| Flame Spread | Mechanisms | | | |
|--------------|-----------------------------------|-----------|-----|---|
| FM-007 | Spacecraft Fire Safety Technology | NASA/LeRC | R/T | 1 |

SPACE ENVIRONMENTAL EFFECTS

SUBTHEME: Environment Characterization

| MSN CODE | MISSION NAME | ORG | MSN TYPE | YR |
|------------------------------|--|-----------|-------------|-----|
| External Environ | nment | | | |
| AFSE-006 | Gas Chromatograph | AFGL/XO | R | 1 |
| SE-017 | Environmental Contam Characteristics Exp | NASA/GSFC | R | 1 |
| SS-5 | Real-Time Monitoring of SS Environment | Battelle | R | 1 |
| SE-004 | Collision-Free Plasma Experiment | NASA/LeRC | R | 4 |
| AFSE-007 | Gaseous Environment Monitor (GEM) | AFGL/XO | R | TBD |
| Internal Environ | ment | | | |
| AFSE-001 | Radiation Measurements Experiment (RME) | AFTAC | R | 0 |
| AFSE-002 | Heavy Ion & Neutron Environments in S/C | USAF/AMD | R | 1 |
| SE-005 | In-Situ Trace Contaminant Analysis | NASA/LaRC | Τ | 1 |
| TDMX2521 | Acoustics Control Technology | NASA/LaRC | T/D | 1 |

SUBTHEME: Environmental Effects

| Coatings/Surfac SE-006 SE-008 SE-002 * TDMX2011 SE-003 AFSE-003 AFSE-004 | e Effects Adv. Solar Concentrator Materials Expt. Atomic Oxygen Effects Experiment Spacecraft Glow and Erosion Spacecraft Materials & Coatings Effects of Space Exposure on Materials Contamination Effects and Control Expt. Space Environmental Effects | NASA/LeRC NASA/JSC Vanderbilt U. NASA/LaRC NASA/LeRC AFWAL/ML/P AFWAL/ML/P | R/T R R R/T R R/T R | 0 0 1 1 2 TBD TBD |
|---|---|--|---------------------------------------|-------------------------------------|
| Data System Eff | ects | | | |
| • TDMX2441 • TDMX2442 • TDMX2443 | Microelectronics Data Syst Expt Transient Upset Phenomena - VLSI VHSIC Fault Tolerant Processor | NASA/JPL NASA/LaRC NASA/LaRC | T T T | 1 1 1 |
| Facilities | • | | | |
| SE-014 SE-019 | Space Ultra-Vacuum Facility: Wake Shield Variable Gravity Experiment Facility | UAH NASA/JSC | D N/A ¹ | 1 6 |
| Micro-meteoroid | Impacts | | | |
| MS-2 SS-010 | Effects of Hypervelocity Impact Micro-Meteorite Protection | Battelle MIT | R R/T | 2 4 |
| Solid Rocket Mo | tors | | | |
| AFSO-010 AFSO-011 | Solid Propellant Reliability in Space Solid Propellant Motor Exposure Study | AFRPL/XRX AFRPL/XRX | R T | 1 |
| Structural Materia | als | | | |
| AFSE-005 | Composite Durability in Space | AFRPL/XRX | R | 1 |
| MS-10 MS-1 | Environmental Exposure Data Collection Service Life Estimation | Battelle Battelle | R R | 1 3 |
| TDMX2581b | Strut NDT Baseline Evaluation | NASA/KSC | R | 3 |

^{1.} Not appropriate as a TDM

ENERGY SYSTEMS AND THERMAL MANAGEMENT

SUBTHEME: Advanced Thermal Control

| MSN CODE | MISSION NAME | ORG | MSN Type | YR |
|------------------|--|------------|-------------|-------------|
| Liquid Droplet R | adiators | | | |
| EP-6 | LDR Orifice and Jet Behavior | Battelle | T/D | 2 |
| EP-7 | LDR Jet Trajectory and Collection System | Battelle | T | 2 2 2 |
| EP-8 | Evaporation Loss Determination For LDR's | Battelle | T | 2 |
| EP-9 | Radiation Effectiveness of LDR's | Battelle | T | 2 |
| Radiator Panel | Technology | | | |
| AFEN-004 | Survivable Lightweight Radiator Panel | AFWAL/FI | T/D | 2 |
| * TDMX2132 | Advanced Radiator Concepts | NASA/LeRC | T | 2 5 7 |
| * TDMX2131 | Radiator Technology | NASA/MSFC | D | 7 |
| Thermal Design | (Interfacing | | | |
| MS-4 | Therm. Design of Space System | Battelle | T | 1 |
| + TDM//0505 | Components | NAOA #4050 | _ | _ |
| * TDMX2565 | Thermal Interface Technology | NASA/MSFC | D | ۱ ۱ |
| Two-Phase Syst | rems | | | |
| EN-001 | Thermal Management | NASA/LeRC | R/T | 0 |
| EN-013 | Flow Boiling Thermal Management | | R/T | 1 |
| EP-11 | Heat Pipe Perf. and Reliability in Low-G | Battelle | Т | 1 |
| EP-2 | Perf. of Two-Phase Thermodynamic Systems | Battelle | D | 4 |

SUBTHEME: Energy Conversion

| MSN | MICCION NAME | 0.00 | MSN | V.5 |
|------------------------------|--|----------------|------|-----|
| CODE | MISSION NAME | ORG | TYPE | YR |
| Dynamic Conver | | | | |
| AFEN-003 | Thermal Energy Storage (TES) Flight Test | AFWAL/POOC | T/D | 0 |
| SE-026 | Adv. Power Sys. Thermal Energy Storage | NASA/LeRC | T | 0 |
| SE-027 | Energy Storage for Solar Dyn. Power Sys. | Sunstrand | Τ | 0 |
| TDMX2153 | Solar Dynamic Power Tests | NASA/LeRC | D | 1 |
| FM-006 | Two-Phase Fluid Mgt. for Liquid Metals | NASA/LeRC | Т | TBD |
| Laser Systems | | | | |
| EN-006 | Nuclear Pumped Lasers | U of Illinois | R | 1 |
| • TDMX2121 | Test Solar Pumped Lasers | NASA/LaRC | T | 1 |
| • TDMX2122 | Laser-to-Electric Conversion | NASA/LaRC | D | 2 |
| Photovoltaic Sys | tems | | | |
| EN-002 | Large Photovoltaic Power System Demo. | NASA/LeRC | Т | 2 |
| EN-005 | Solar Array Blanket Zero-G Foldup Expt. | LMSC | Т | 2 |
| SE-028 | Advanced Power System Test Bed | Ford Aerospace | Т | 2 |
| * TDMX2151 | Solar Array/Energy Storage Tech. | NASA/MSFC | Ť | 2 |
| * TDMX2152 | Large Space Power Systems Tech | NASA/LeRC | Т | 2 |
| Solar Furnace Te | echnology | | | |
| EN-004 | Direct Solar Thermal Furnace Technology | NASA/LeRC | Т | 4 |
| SS-7 | Solar Furnace For Metals Refining | Battelle | Ď | 4 |

ENERGY SYSTEMS AND THERMAL MANAGEMENT

SUBTHEME: Power Management and Distribution

| MSN Code | MISSION NAME | ORG | MSN Type | ΥR |
|-----------------|---------------------------------------|-----------|-------------|----|
| Environmental I | nteraction | | <u> </u> | |
| SE-012 | Voltage Op. Limit Tests Shuttle Expt. | NASA/LeRC | R | 0 |
| EN-014 | Environmental Interaction Experiment | | R/T | 1 |
| SE-001 | Environmental Interactions | NASA/LeRC | R/T | 1 |
| • TDMX2512 | High Voltage in Space Plasma | NASA/JSC | T/D | 1 |
| Megawatt Syste | ms | | | |
| * TDMX2154 | Megawatt Power Distribution | NASA/LeRC | Т | 3 |

SUBTHEME: Propulsion

| | · · · · · · · · · · · · · · · · · · · | | | |
|-----------------|--|------------|-----|-----|
| Advanced Propu | ulsion Concepts | | | |
| * TDMX2322 | Laser Propulsion | NASA-LaRC/ | Т | 2 |
| | | MSFC | | _ |
| AFSO-012 | High Area Ratio Nozzle Tests in Space | AFRPL/XRX | т | 3 |
| | | — | ņ | 3 |
| AFEN-005 | High Performance Space Booster | AFRPL/XRX | U | 4 |
| Contamination E | Effects | | | |
| AFEN-001 | Space-Based Contam. and Flowfield Expts. | AFRPL/XRX | R | 1 |
| SE-011 | Plume Properties Measurements Experiment | NASA/LeRC | R | 1 |
| • TDMX2511 | Space Power System Environ. Int. | NASA/LeRC | ¥ | 2 |
| | | | | _ |
| SE-015 | Radiation from Attitude Control Jets | UAH | R | TBD |
| Low Thrust | | | | |
| SO-005 | Ion Auxiliary Propulsion System | NASA/LeRC | D | 0 |
| AFSO-017 | Low Thrust Propulsion Experiment | AFSD/YEZ | Ď | 1 |
| SO-001 | Controlled Thrust Propulsion Technology | NASA/LeRC | Ť | i |
| * TDMX2321 | Low Acceleration Propulsion Technology | NASA/LeRC | R/T | 2 |
| AFSO-014 | Electric Prop. Test Platform | AFRPL/XRX | Т | 3 |
| AFSO-015 | Solar Thermal Propulsion System | AFRPL/XRX | Ď | 4 |

AUTOMATION AND ROBOTICS

SUBTHEME: Automation

| MSN CODE | MISSION NAME | ORG | MSN Type | YR |
|------------------------------|--|------------|-------------|----|
| Autonomous Co | ontrol | | | |
| TDMX2472 | Advanced Automation Technology | NASA/GSFC | D | 1 |
| AR-009 | Space Power Systems A&R Space Expts. | NASA/LeRC | D | 6 |
| Rendezvous/Do | ockina | | | |
| AR-001 | Advanced Autopilot for Spacecraft | Draper Lab | D | 0 |
| AR-007 | Near-Term Teleoperator Maneuvering Expt. | MIT | T | 0 |
| SS-006 | Berthing and Docking Sensor | NASA/JSC | D | 0 |
| AFAR-001 | Autonomous Rendezvous and Docking System | AFRPL/XRX | D | 4 |
| AR-003 | Berthing/Docking Mechanisms and Control | NASA/JPL | D | 4 |

SUBTHEME: Robotics

| Advanced Concepts | | | | | |
|------------------------------|--|-----------|-----|----|--|
| AR-010 | Space Spider Crane | NASA/LaRC | D | 19 | |
| | | | | | |
| Free-Flight Dyn | <u>amics</u> | | | | |
| AR-004 | Dyn. of Retargeting/Maneuvering Large SS | NASA/JPL | D | 2 | |
| TDMX2433 | Dynamic Stabilization FF Robot | NASA/JPL | Т | 6 | |
| | | | | | |
| | nance/Servicing | | | | |
| * TDMX2563 | Materials Resupply | NASA/MSFC | D | 2 | |
| * TDMX2464 | Autonomous Servicing Robot | NASA/JPL | D | 5 | |
| Teleoperation | | | | | |
| AR-005 | Flt vs. Gnd Command of Service Robot | GE | Т | 0 | |
| AR-008 | Robot for Science Laboratories | NASA/GSFC | Ť | Ö | |
| * TDMX2462 | Dextrous Teleoperator Technology | NASA/JPL | D | 1 | |
| TDMX2473 | Space Robotics Research Laboratory | NASA/JPL | N/A | 1 | |
| • TDMX2461 | Teleoperated Structure Assembly | NASA/JPL | D | 2 | |
| * TDMX2463 | Autonomous Robotic Maint Demo | NASA/JPL | D | 3 | |

INFORMATION SYSTEMS

SUBTHEME: Communication and Tracking

| MSN CODE | MISSION NAME | ORG | MSN Type | YR | |
|--------------------|---------------------------------------|-----------|-------------|----|--|
| Antenna Perforn | nance | | | | |
| * TDMX2211 | Multi-Ftn Space Antenna Rng Tech | NASA/JPL | Т | 2 | |
| • TDMX2212 | Multi Antenna Beam Patterns | NASA/JPL | T | 3 | |
| Component Tec | hnologies | | | | |
| IS-001 | High-Voltage Traveling Wave Tube Amp. | NASA/LeRC | D | 3 | |
| Propagation | | | | İ | |
| SE-009 | 40-105 GHz Propagation Experiments | NASA/LeRC | R | 3 | |
| Time Standards | | | | | |
| • TDMX2223 | Maser Precision Time Generation | NASA/JPL | D | 2 | |
| Trackina – Deep | Space | | | | |
| * TDMX2224 | Space-Based Optical DSN Terminal | NASA/JPL | Т | 2 | |
| * TDMX2266 | Spacecraft Optical Rng Determin. | NASA/JPL | Ď | 4 | |
| * TDMX2267 | Optical Spatial Tracking S/Craft | NASA/JPL | D | 4 | |
| Tracking Proximity | | | | | |
| AFIS-003 | Proximity Traffic Control Studies | AFWAL/FI | R | 2 | |
| * TDMX2221 | Laser Comm & Tracking Develop. | NASA/JPL | Ď | 3 | |

SUBTHEME: Data Systems

| Controls/Displa | <u>ys</u> | | | |
|-----------------|---|----------|---|---|
| AFIS-002 | Visually-Coupled Remote Control System | USAF/AMD | D | 2 |
| CH-1 | Physiological Control Systems in Low-g | Battelle | D | 2 |
| CH-2 | Adv. Control/Display Concepts in Low-g | Battelle | D | 7 |
| CH-7 | Eval. of 3-D Holographic Control System | Battelle | D | 7 |

INFORMATION SYSTEMS

SUBTHEME: Sensors

| MSN Code | MISSION NAME | ORG | MSN Type | YR |
|---|---|---|-----------------------------------|------------------|
| <u>Defense</u> AFIS-001 | W-Sensor Trial Experiment | AFSD/YEZ | D | 0 |
| Electro-Optical S AFIS-005 • TDMX2262 AFIS-006 • TDMX2261 | ensors Ultraviolet Remote Sensor Manned Observations Techniques Plume Observables Optical Laboratory Sensor Systems Technology Exp'mt | AFGL/XO NASA/JSC AFRPL/XRX NASA/LaRC | R T/D R N/A ¹ | 1 1 2 3 |
| Lidars TDMX2263 Radars/Radiome | CO2 Doppler Lidar Wind Sensor | NASA/LaRC | D | 2 |
| AFIS-004 • TDMX2265 • TDMX2264 | Space Based Radar (SBR) Satellite Doppler Meteorol Radar Microwave Remote Sensing-Passive | RADC/OCSA NASA/LaRC NASA/LaRC | D D D | 1 1 6 |
| Radio Astronomy IS-002 | Advanced Orbiting VLBI Technology on SS | NASA/JPL | D | 5 |

^{1.} Not appropriate as a TDM

SUBTHEME: Blomedical

| MSN CODE | MISSION NAME | ORG | MSN Type | YR |
|------------------|--|----------|-------------|-----|
| Bends Avoidan | ce/Therapy | | | |
| AFSO-018 | Zero-G Denitrogenation Study | USAF/AMD | R | 0 |
| AFSO-020 | Spaceflight Bends Therapy | USAF/AMD | Т | TBD |
| AFSO-021 | Bends Warning Device | USAF/AMD | TBD | TBD |
| Diagnosis/Treat | ment | | | |
| • TDMX2531 | Surgery Technology Development | NASA/JSC | T/D | 3 |
| Physiological Ef | fects of Low-G | | | |
| AFSO-019 | Body Segmental Fluid Shifts in Low-g | USAF/AMD | R | 0 |
| AFSO-022 | Foot Forces and Press. Patterns | USAF/AMD | R | 0 |
| SO-007a | Flight Crew Health | LMSC | R | 1 |
| • TDMX2532 | Medical Experiments Technology | NASA/JSC | R | 1 |
| CH-8 | Metabolic Workload Measurements in Low-g | Battelle | R | 3 |

SUBTHEME: Human Factors

| Cognition CH-6 AFSO-023 CH-4 AFSO-025 | Visual Space Perception Military Crew Cognition/Decision Making Time Perception and Estimation Long-Term Visual Performance in Space | Battelle USAF/AMD Battelle USAF/AMD | R R R | 1 2 3 TBD |
|---|--|--|-------------|--------------------|
| Crew Productivi | tv | | | |
| SO-007 | Manned System Experiments | LMSC | R/D | 1 |
| SO-007b | IVA Crew Operations Productivity | LMSC | D | 1 |
| SO-007c | EVA Operations Demonstration | LMSC | D | 2 |
| Interaction | | | | |
| CH-3 | Eval. of Human Fine Motor Performance | Battelle | R | 1 |
| CH-5 | Human Orientation Perception | Battelle | R | 1 [|
| • TDMX2471 | Human/Machine Interface Workload | NASA/JPL | R | 2 |
| AFSO-024 | Target Acquisition and Tracking | USAF/AMD | R | TBD |

SUBTHEME: Maintenance, Repair, and Test

| MSN CODE | MISSION NAME | ORG | MSN TYPE | YR |
|------------------------------|--|----------------|-------------|-----|
| Cleaning/Refurb | ishment | | | |
| SE-007 | On-Orbit Contamination Control | GE-Space Div. | D | 0 |
| TDMX2564 | Coatings Maintenance Technology | NASA/MSFC | D | 1 |
| MS-3 | Development and Refurb. of Adv. Coatings | Battelle | T | 4 |
| TDMX2581g | Laser Cleaning Demonstration Experiment | NASA/KSC | D | TBD |
| Inspection/Test | | | | |
| TDMX2581 | Systems Operational Maint, Tech. | NASA/KSC | D | 2 |
| TDMX2581a | Video Probe Experiment | NASA/KSC | D | .4 |
| TDMX2581d | On-Orbit Checkout Equipment | NASA/KSC | D | 4 |
| TDMX2581e | Gas Leak Detection Experiment | NASA/KSC | D | 4 |
| TDMX2581f | Real-Time Digital Radiography Experiment | NASA/KSC | D | TBD |
| Satellite Servicin | <u>a</u> | | | |
| SO-003 | Automatic Satellite Checkout Equipment | Rockwell Int'l | D | 0 |
| AFSO-013 | Verif. Testing of Resupply Components | AFRPL/XRX | T/D | 1 |
| TDMX2561 | Satellite Servicing and Refurb. | NASA/MSFC | D | 1 |
| * TDMX2562 | Satellite Maintenance and Repair | NASA/MSFC | D | 2 |

SUBTHEME: Material Processing

| MSN CODE | MISSION NAME | ORG | MSN TYPE | YR |
|------------------------------|--|----------------|-------------|-----|
| Composites | | | | |
| AFSO-005 | Space Fiber Production | AFRPL/XRX | Т | 4 |
| AFSO-007 | Space Wound Composite Manufacturing | AFRPL/XRX | Ť | TBD |
| | opaco manadaming | | | |
| Crystal Growth | | | | |
| • TDMX2022 | Growth of Comp Semicond Crystals | NASA/LaRC | D | 1 |
| TDMX2023 | Growth of Thin Single Crys Wafer | NASA/LaRC | R | 1 |
| | 3 • 7 • | | | |
| Fluids | | | | |
| MS-7 | Containerless Processing of Liquids | Battelle | Т | 1 |
| SE-010 | Electrophoresis in Space | NASA/JSC | D | 1 |
| SO-011 | Bioreactor Technology in Space | NASA/JSC | D | 1 |
| TDMX2024 | Electrophoresis Separation Tech. | NASA/JSC | T/D | 1 |
| | · | | | |
| Materials Charac | terization | | | |
| * TDMX2021 | Man/Machine Mix Investigations | NASA/JSC | D | 1 |
| | | | | |
| Process Techno | | | | |
| MS-6 | Spent Materials Utilization | Battelle | D | 7 |
| SS-10 | Processing Systems for Lunar Materials | Battelle | D | 10 |
| SE-013 | High Temp Controlled Reactions in S.E.M. | Mcrscpy Res. | R | TBD |
| | | Labs | _ | ~ |
| SO-009 | Fluidized Bed Behavior in Low-G | Carbotek, Inc. | R | TBD |
| Commis Handlins | (Storogo | | | |
| Sample Handling | | Datalla | _ | [|
| SS-3 | Isolation of Extraterrestrial Materials | Battelle | D | 7 |
| Solid Propollanta | | | | |
| Solid Propellants | | A EDDL (VDV | _ | |
| AFSO-009 | Synthesis of Novel Solid Propellants | AFRPL/XRX | R | 3 7 |
| AFSO-008 | Space-based Solid Propellant Motor Mfg. | AFRPL/XRX | T | / |

SUBTHEME: Systems/Facilities

| MSN CODE | MISSION NAME | ORG | MSN TYPE | YR |
|-----------------|--|------------|------------------|--------|
| CELSS | · · · · · · · · · · · · · · · · · · · | | | |
| SS-1 | Plant Growth Chamber | Battelle | D | 1 |
| SS-2 | Aerobic Digestor | Battelle | D | 7 |
| SS-4 | Algae-Based Food Production System | Battelle | Т | 7 7 |
| SS-8 | Microbial/Chemosynthetic Food Sources | Battelle | D | 7 |
| Manned Systems | 5 | | | |
| SS-9 | Manned Mars Capsule Prototype | Battelle | D | 10 |
| <u>VTO</u> | | | | |
| • TDMX2571 | OTV/Payload Interfacing/Transfer | NASA/MSFC | D | 3 3 |
| • TDMX2573 | OTV Docking and Berthing | NASA/MSFC | D | 3 |
| * TDMX2574 | OTV Maintenance Technology | NASA/MSFC | D | 3 |
| Reentry Systems | | | | |
| AFSO-002 | Maneuverable Reentry Research Vehicle | AFWAL/FI | T/D | 2 |
| AFSO-001 | Escape and Recovery Experiments on SS | AFWAL/FIER | D | 4 |
| Technology Eval | uation | | | |
| SO-004 | Space Test and Evaluation Facility | Wyle Labs. | N/A ¹ | |
| <u>Tethers</u> | | | | |
| * TDMX2541 | Tethered Electrodynamic Power Gn | NASA/MSFC | (D) | 3 |
| * TDMX2542 | Tethered Constellation | NASA/MSFC | (D) | 3 |
| * TDMX2544 | Tethered Fluid Storage/Transfer | NASA/MSFC | (D) | 3 |
| SO-010 | Shuttle Deorbit/OTV Boost Using a Tether | NASA/MSFC | (D) | 6 |
| * TDMX2543 | Tethered Transportation | NASA/MSFC_ | (D) | 6 |

^{1.} Not appropriate as a TDM

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APPENDIX C. OUTFITTING NEEDS CONSOLIDATED BY TECHNOLOGY THEME

This section contains a list of support equipment items for each of the seven technology themes. The count is a tally of the number of missions in the theme that were identified as needing an item. It is presented as an indicator user demand. The categories of items currently in planning are identified in Table III-2.

OUTFITTING NEEDS FOR SPACE STRUCTURE (DYNAMICS AND CONTROL) THEME (Sheet 1 of 2)

| EQUIPMENT ITEM | EQUIP CAT | MISSION COUNT |
|--|------------|------------------|
| Camera locker | LSE | 4 |
| Camera, 35 mm | LSE | 3 |
| Cleaning equipment | LSE | 3 5 |
| Film locker | LSE | 8 |
| Hand tools, general purpose | LSE | 3 |
| Microscope system | LSE | 8 3 2 |
| Oscilloscope, digital recording | LSE | 1 |
| Storage locker, EM-shielded | LSE | 8 |
| Glovebox, materials processing | LSF | 0 |
| Workbench, laboratory sciences | LSF | 2 |
| Acceleration monitor, lab | LSS | 3 |
| Chemical storage facility | LSS | 3 |
| Gas storage/supply, lab | LSS | 3 |
| Storage, sample | LSS | 2 |
| | LSS | 2 |
| Vacuum vent Waste disposal system | LSS | 0 |
| Attitude Determination System (ADS) | PAE | 233322656 |
| Contamination monitor | PAE | 9 |
| | PAE | 3 |
| Payload Pointing System (PPS) | | 3 36 |
| Data recorder, digital Hand tools, EVA general purpose | Std Std | 20 |
| Mobile Servicing Center (MSC) | Std | 16 |
| | Std | 5 |
| Storage, pressurized Video | Std Std | 6 |
| Video recorder | Std | 16 |
| Video, external | Std | 20 |
| Workstation, maintenance | Std | 1 |
| Accelerometer package, external | Old | 15 |
| Antenna positioner, medium | | 1 |
| Assembly platform | | 3 |
| Battery charger, external | | 2 |
| Camera locker, cinema | | 3 |
| Camera, 35 mm (EVA) | | 2 3 2 3 |
| Camera, high speed cinema | | 3 |
| Cleaning materials, EVA | | 4 |
| Computer | | 4 |
| Cryogen storage/transfer facility | | 1 |
| Cryogen storage/transfer facility, LHe | | , |
| Film magazines | | 2 3 |
| Frequency analyzer | | 1 |
| Gas storage/transfer facility | | 1 |
| Imaging radiometer | | 2 |
| Inaging radiometer Inertial reference unit | | 1 |
| Laser measurement unit | | 5 |
| Lighting, external | | 5 8 |
| Mass spectrometer | | 1 |
| OMV | | |
| OMV support systems | | 3 3 |
| Orbit transfer vehicle, low thrust | | 1 |
| Pointing mount, two-axis solar | | |
| Propellant storage/transfer facility | | |
| Proximity sensor | | 4 |
| Radiometer | | 2 |
| Reflectometer | | 4 |
| i renectonietei | | |

OUTFITTING NEEDS FOR SPACE STRUCTURE (DYNAMICS AND CONTROL) THEME (Sheet 2 of 2)

| EQUIPMENT ITEM | EQUIP CAT | MISSION COUNT |
|-------------------------------------|-----------|---------------|
| Retroreflective targets | | 3 |
| Sample containers | | 1 |
| Space Station Construction Platform | | 1 |
| Storage, unpressurized | | 19 |
| Stress test machine | | 2 |
| Sun sensor | | 3 |
| Transmitter/receiver, RF | | 1 |
| Truss extension arm | | 1 |
| Vacuum chamber | | 3 |
| | | |
| | | 310 |

OUTFITTING NEEDS FOR FLUID MANAGEMENT THEME

| EQUIPMENT ITEM | EQUIP CAT | MISSION COUNT | |
|---|-----------|---------------|--|
| Camera locker | LSE | 3 | |
| Camera, 35 mm | LSE | 2 | |
| Cleaning equipment | LSE | 1 | |
| Film locker | LSE | 3 | |
| Fluid handling tools | LSE | 4 | |
| Storage locker, EM-shielded | LSE | 5 | |
| Acceleration monitor, lab | LSS | 4 | |
| Chemical storage facility | LSS | 4 | |
| Gas storage/supply, lab | LSS | 1 | |
| Storage, sample | LSS | 1 | |
| Vacuum vent | LSS | 6 | |
| Waste disposal system | LSS | 1 | |
| Contamination monitor | PAE | 3 | |
| Data recorder, digital | Std | 5 | |
| Data terminal, graphics | Std | 1 | |
| Film locker, cinema | Std | 1 | |
| Hand tools, EVA general purpose | Std | 1 | |
| Video | Std | 6 | |
| Video recorder | Std | 6 | |
| Video, external | Std | 1 | |
| Camera, cinema | | 3 | |
| Camera, high speed cinema | | 3 | |
| Cryo storage/transfer facility, lab LHe | | 1 | |
| Film locker, cinema | | 4 | |
| Film magazines | | 2 | |
| Gas chromatograph/mass spectrometer | | 1 | |
| Gas sampling bottles | | 1 | |
| Image intensifier | | 1 | |
| Interferometer, holographic | | 1 | |
| Laser Doppler anemometer | | 1 | |
| Leak detector, He | | 1 | |
| Leak detector, propellant | | 3 | |
| Photo processor unit | | 1 | |
| Sample containers | | 1 | |
| | | | |
| | | 83 | |

OUTFITTING NEEDS FOR SPACE ENVIRONMENTAL EFFECTS THEME

| EQUIPMENT ITEM | EQUIP CAT | MISSION COUNT |
|---------------------------------------|-----------|---------------|
| Battery charger | LSE | 2 |
| Camera locker | LSE | 6 |
| Camera, 35 mm | LSE | 7 |
| Dosimeter, passive | LSE | 1 |
| Film locker | LSE | 6 |
| Hand tools, general purpose | LSE | 2 |
| Microscope system | LSE | 7 |
| Multimeter, digital | LSE | 1 |
| Storage locker, EM-shielded | LSE | 1 1 |
| Workbench, laboratory sciences | LSF | 6 |
| Acceleration monitor, lab | LSS | l ĭ l |
| Storage, sample | LSS | ż |
| Vacuum vent | LSS | 1 |
| Attitude Determination System (ADS) | PAE | i |
| Contamination monitor | PAE | 10 |
| Data recorder, digital | Std | 19 |
| Hand tools, EVA general purpose | Std | 7 |
| Mobile Servicing Center (MSC) | Std | 6 |
| MRMS | Std | 1 |
| Storage, pressurized | Std | 5 |
| Accelerometer package, external | 0.0 | 1 1 |
| Audiometer | | 1 |
| Battery charger, external | | 4 |
| Bi-directional reflectance instrument | | |
| Exposure tray | | 10 |
| Imaging radiometer | | 10 |
| Magnetometer | • | 4 |
| Mass spectrometer | | 8 |
| Noise dosemeter | | • |
| Noise monitor | | 4 |
| Optical disk drive | | 1 |
| Plasma diagnostic package | | 2 |
| Power amplifier | | 1 |
| Radiation monitor | | 2 |
| Radiation monitor, EM | | 1 |
| Radiation monitor, Livi | | 2 |
| Radiometer | | 4 |
| Reflectometer | | 2 |
| Retarding potential analyzer | | 1 |
| Sample containers | | 8 |
| Solid Rocket Motor Research Facility | | 2 |
| Sound level meter | | 1 |
| Spectrophotometer | | 2 |
| Storage, unpressurized | l | 2 |
| Stress test machine | ļ | 2 |
| Sun sensor | | 1 |
| Tape recorder, audio | 1 | i |
| Transmitter/receiver, RF | İ | 2 |
| Ultrasonic test unit | | 2 |
| Video, low light (external) | İ | 1 |
| Workstation, teleoperator | | |
| | | i I |
| X-ray unit | | ' 1 |
| | | 160 |
| | | 160 |

OUTFITTING NEEDS FOR ENERGY SYSTEMS AND THERMAL MANAGEMENT THEME

| EQUIPMENT ITEM | EQUIP CAT | MISSION COUNT | |
|---------------------------------------|-----------|---------------|--|
| Camera locker | LSE | 3 | |
| Camera, 35 mm | LSE | 3 | |
| Film locker | LSE | 3 | |
| Fluid handling tools | LSE | 1 | |
| Hand tools, general purpose | LSE | 1 | |
| Microscope system | LSE | 2 | |
| Storage locker, EM-shielded | LSE | 6 | |
| Acceleration monitor, lab | LSS | 2 | |
| Chemical storage facility | LSS | 1 | |
| Storage, sample | LSS | 2 | |
| Vacuum vent | LSS | 1 | |
| Attitude Determination System (ADS) | PAE | 9 | |
| Contamination monitor | PAE | 23 | |
| Data recorder, digital | Std | 38 | |
| Hand tools, EVA general purpose | Std | 14 | |
| Mobile Servicing Center (MSC) | Std | 6 | |
| Storage, pressurized | Std | 1 | |
| Video | Std | 1 | |
| Video recorder | Std | 15 | |
| Video, external | Std | 12 | |
| Accelerometer package, external | • | 3 | |
| Assembly platform | | 1 | |
| Camera, 35 mm (EVA) | | 2 | |
| Camera, high speed cinema | | 1 | |
| Computer, experiment control | | 1 | |
| Data recorder, digital | | 1 | |
| Exposure tray | | 1 | |
| Film locker, cinema | | 1 | |
| Film magazines | | 1 | |
| Gas storage/transfer facility | | 1 | |
| Imaging radiometer | | 8 | |
| Lighting, external | | 1 | |
| Magnetometer | | 1 | |
| Mass spectrometer | | 5 | |
| Plasma diagnostic package | | 6 | |
| Plasma diagnostic probe | | 1 | |
| Plasma ground | | 11 | |
| Pointing mount, two-axis solar | | 10 | |
| Potential probe | | 5 | |
| Propellant storage/transfer facility | | 3 | |
| Radiometer | | 3 | |
| Reflectometer | | 1 | |
| Sample containers | | 1 | |
| Spectrophotometer, imaging (external) | | 1 | |
| Storage, unpressurized | | 9 | |
| Sun sensor | | 4 | |
| Tether system | | 1 | |
| Transmitter/receiver, RF | | 1 | |
| Video, low light (external) | | 6 | |
| | | | |
| | | 235 | |

OUTFITTING NEEDS FOR AUTOMATION AND ROBOTICS THEME

| EQUIPMENT ITEM | EQUIP CAT | MISSION COUNT | |
|--------------------------------------|-----------|---------------|--|
| Camera locker | LSE | 6 | |
| Camera, 35 mm | LSE | 6 | |
| Film locker | LSE | 7 | |
| Storage locker, EM-shielded | LSE | 13 | |
| Data recorder, digital | Std | 12 | |
| Data terminal | Std | 1 | |
| Hand tools, EVA general purpose | Std | 6 | |
| Mobile Servicing Center (MSC) | Std | 2 | |
| Video | Std | 2 | |
| Video recorder | Std | 14 | |
| Video, external | Std | 6 | |
| Accelerometer package, external | | 2 | |
| Assembly bay | | 1 | |
| Camera, cinema | | 1 | |
| Computer, Al | | 1 | |
| Docking assembly | | 1 | |
| Lighting, external | | 4 | |
| Manned Maneuvering Unit (MMU) with | | | |
| FSS | | 1 | |
| OMV | | 4 | |
| OMV (with Smart Front End) | | 1 | |
| OMV support systems | | 5 | |
| Pointing mount, two-axis solar | | 1 | |
| Propellant storage/transfer facility | | 2 | |
| Range sensor, laser | | 1 | |
| Range sensor, radar | | 1 | |
| Rendezvous radar | | 1 | |
| Shroud, cover | ' | 1 | |
| Storage, unpressurized | | 19 | |
| Video, external (SRRL) | | 5 | |
| Window, viewing | 1 | 6 | |
| Workstation, teleoperator | l | 5 | |
| Workstation, telerobotic | | 8 | |
| | ļ | 146 | |
| | | 146 | |

OUTFITTING NEEDS FOR INFORMATION SYSTEMS THEME

| EQUIPMENT ITEM | EQUIP CAT | MISSION COUNT |
|--|--|--|
| Film locker Storage locker, EM-shielded Chemical storage facility Vacuum vent Attitude Determination System (ADS) Contamination monitor Payload Pointing System (PPS) Data recorder, digital Hand tools, EVA general purpose Mobile Servicing Center (MSC) Storage, pressurized Video Video recorder Video, external Accelerometer package, external Airlock, scientific Antenna positioner, large Antenna positioner, medium Battery storage Calibration/servicing | EQUIP CAT LSE LSS LSS PAE PAE PAE Std Std Std Std Std Std Std Std Std | MISSION COUNT 1 8 1 1 10 10 6 18 3 2 6 9 5 3 8 1 1 1 1 1 |
| Battery storage Calibration/servicing Cleaning equipment, optics Computer, graphics/experiment control Computer-video generator Cryogen storage/transfer facility Data recorder, digital Frequency standard, hydrogen maser Global Positioning System (GPS) Graphics display, high resolution Isolator, mechanical OMV OMV support systems Physiological monitor Range sensor, laser Speech generator Storage, unpressurized Tape recorder, audio Test instruments, electronic | | 1 1 1 3 3 2 3 1 2 3 3 6 6 4 2 4 3 4 1 1 |
| Tools, optical alignment Visual task generator Window, high-quality optical Workbench, optical | | 3 2 1 156 |

OUTFITTING NEEDS FOR IN-SPACE OPERATIONS THEME (Sheet 1 of 3)

| EQUIPMENT ITEM | EQUIP CAT | MISSION COUNT |
|-----------------------------------|-----------|------------------|
| Autoclave | LSE | 6 |
| Battery charger | LSE | 3 |
| Camera locker | LSE | 9 |
| Camera, 35 mm | LSE | 10 |
| Cleaning equipment | LSE | 14 |
| Cutting/polishing system | LSE | 3 |
| Dosimeter, passive | LSE | 1 |
| Electrical conductivity probe | LSE | 1 |
| Etching equipment | LSE | 5 |
| Film locker | LSE | 10 |
| Fluid handling tools | LSE | 13 |
| Freeze dryer | LSE | 1 |
| Freezer | LSE | 11 |
| Freezer, cryogenic | LSE | 2 |
| Hand tools, general purpose | LSE | 14 |
| Incubator | LSE | 4 |
| Mass measurement device, small | LSE | 7 |
| Microscope system | LSE | 15 |
| Multimeter, digital | LSE | 5 |
| pH meter | LSE | 8 |
| Refrigerator | LSE | 11 |
| Storage locker, EM-shielded | LSE | 16 |
| Surgery/dissecting tools | LSE | 1 1 |
| Thermometer, digital | LSE | |
| Ultraviolet sterilization unit | LSE | 3 |
| Washer/sanitizer, equipment | LSE | ٠ د |
| X-ray system | LSE | 2 3 5 3 |
| Glovebox, materials processing | LSF | 13 |
| Workbench, laboratory sciences | LSF | 14 |
| Acceleration monitor, lab | LSS | 7 |
| Chemical storage facility | LSS | 16 |
| Cleanup/decontamination equipment | LSS | 2 |
| Gas storage/supply, lab | LSS | 7 |
| Materials transport system | LSS | 1 |
| Storage, process materials | LSS | 5 |
| Storage, sample | LSS | 4 |
| Vacuum vent | LSS | 2 |
| Waste disposal system | LSS | 20 |
| Water service, lab grade | LSS | 10 |
| Contamination monitor | PAE | 4 |
| Airlock, hyperbaric | Std | 1 1 |
| Data recorder, digital | Std | 33 |
| Docking port | Std | 2 |
| Hand tools, EVA general purpose | Std | 8 |
| Mobile Servicing Center (MSC) | Std | 7 |
| Storage, pressurized | Std | 17 |
| Storage, unpressurized | Std | 3 |
| Video | Std | 22 |
| Video recorder | Std | 21 |
| Video, external | Std | 14 |
| Workstation, maintenance | Std | 2 |
| Workstation, MSC telerobotic | Std | 5 |
| Airlock, scientific | Şiü | 1 |
| Amplifiers | | 2 |
| Vinhinigia | | 4 |

OUTFITTING NEEDS FOR IN-SPACE OPERATIONS THEME (Sheet 2 of 3)

| EQUIPMENT ITEM | EQUIP CAT | MISSION COUNT | |
|---|------------|---------------|--|
| Anechoic chamber | 22011 07.1 | 4 | |
| Animal holding facility | | 2 | |
| Battery charger, external | | 1 | |
| Berthing system, OTV | | 3 | |
| Blood sample kit | | 2 | |
| Centrifuge | ı | 4 | |
| Centrifuge, refrigerated | | 3 | |
| Cleaning equipment, optics | | 1 | |
| Computer, parallel processor | | 1 | |
| Computer, process control | | 2 | |
| Computer-video generator | | 4 | |
| Counter | | 1 | |
| Cryogen storage/transfer facility, LHe | | 1 | |
| Digital word generator | | 1 | |
| Docking system | | 2 | |
| Dummy payload | | 1 | |
| Dynamometer | | 2 | |
| Electrical stimulation pulse generator | | 1 | |
| Electrical test/checkout equipment | | 1 | |
| Electrode impedance meter | | 9 | |
| EMU | | 2 | |
| Ergometer | | 2 | |
| Exposure tray | | 2 | |
| Gas chromatograph/mass spectrometer | | 4 | |
| Gas storage/transfer facility | | 1 | |
| Graphics display, high resolution | | 6 | |
| Hall probe | | 2 | |
| Hand tools, laboratory | | 2 | |
| Hand wash facility | | 1 | |
| Joystick | | 1 4 | |
| Leak detector, propellant Lighting, external | | 7 | |
| Logic analyzer | | 1 | |
| Manned Maneuvering Unit (MMU) | | <u> </u> | |
| Mixing facilities | | <u> </u> | |
| OMV | | 5 | |
| OMV support systems | | 5 | |
| Optical pyrometer | | 1 | |
| OTV | | i i | |
| Physiological monitor | | 8 | |
| Plethysmograph | | 1 | |
| Power supply, programmable | | 1 | |
| Propellant storage/transfer facility | | 3 | |
| Reflectometer | | 1 | |
| Respiratory monitoring system | | 1 | |
| RF power meter | | 1 | |
| Sample containers | | 8 | |
| Satellite Servicing Facility | | 3 | |
| Scanning electron microscope system | | 3 | |
| Servicing/maintenance hangar | | 3 | |
| Solid Rocket Motor Research Facility | | 2 | |
| Spectrum analyzer | | 1 | |
| Speech generator | | 6 | |
| Spirometer | | 1 | |
| Sterilization facility | | 1 | |

OUTFITTING NEEDS FOR IN-SPACE OPERATIONS THEME (Sheet 3 of 3)

| EQUIPMENT ITEM | EQUIP CAT | MISSION COUNT | |
|------------------------------|-----------|---------------|--|
| Storage, isolation | | 1 | |
| Storage, pressurized | | 1 | |
| Storage, unpressurized | | 9 | |
| Tape recorder, audio | | 12 | |
| Temperature monitor, ambient | | 1 | |
| Tether alignment system | | 2 | |
| Tether tracking system | | 5 | |
| Tethered pointing system | 1 | 1 | |
| Transmitter/receiver | | 1 | |
| Transmitter/receiver, RF | | 1 | |
| Treadmill | | 1 | |
| Urine sample kit | 1 | 2 | |
| Video, high resolution | | 4 | |
| Visual pulse generator | | 2 | |
| Visual task generator | | 6 | |
| Waveform digitizer | | 1 | |
| Workstation, teleoperator | | 2 | |
| Workstation, telerobotic | | 1 | |
| | | | |
| | | 618 | |

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APPENDIX D. OUTFITTING NEEDS CONSOLIDATED AT THE PROJECT LEVEL

This section contains a list of support equipment items grouped by project for each of the seven technology themes. Within the classification scheme used to organize the mission data, a project group contains one or more missions that address a single technology development issue or technology application. Multiple missions within a project group are closely related in their objectives and in most cases could benefit from the same set of support equipment. As stated previously, the mission count for each item is interpreted as a measure of user demand.

SPACE STRUCTURE (DYNAMICS AND CONTROL) Equipment Count by Project

SUBTHEME: Advanced Structures

| SUBTHEME: Advanced Structu | res | |
|--|--|---------------------------|
| EQUIPMENT ITEM | EQP CAT | MSN COUNT |
| Assembly Storage locker, EM-shielded Contamination monitor Data recorder, digital Hand tools, EVA general purpose Mobile Servicing Center (MSC) Video recorder Video, external Accelerometer package, external Assembly platform Cryogen storage/transfer facility, LHe Gas storage/transfer facility Lighting, external OMV OMV support systems Propellant storage/transfer facility Storage, unpressurized | LSE PAE Std Std Std Std | 4225555511115115 |
| Segmented Optics Attitude Determination System (ADS) Contamination monitor Payload Pointing System (PPS) Data recorder, digital Hand tools, EVA general purpose Mobile Servicing Center (MSC) Video Video recorder Video, external Accelerometer package, external Assembly platform Cryogen storage/transfer facility Cryogen storage/transfer facility, LHe Imaging radiometer Lighting, external Storage, unpressurized | PAE PAE Std Std Std Std Std Std | 2 3 2 1 3 2 1 1 1 1 1 1 3 |

SUBTHEME: Advanced Structures (cont'd)

| | EQP | MSN |
|---|------------|------------------|
| EQUIPMENT ITEM | CAT | COUNT |
| Thin Film/Inflatable Structures | | |
| Camera locker | LSE | 223223232233 |
| Camera, 35 mm | LSE | 2 |
| Cleaning equipment | LSE | 3 |
| Film locker | LSE | 2 |
| Microscope system | LSE | 2 |
| Storage locker, EM-shielded | LSE | 3 |
| Glovebox, materials processing | LSF | 2 |
| Chemical storage facility | LSS | 3 |
| Gas storage/supply, lab | LSS | 2 |
| Storage, sample | LSS | 2 |
| Vacuum vent | LSS | 3 |
| Waste disposal system | LSS | 3 |
| Data recorder, digital | Std | 1 |
| Hand tools, EVA general purpose | Std | 1 |
| Mobile Servicing Center (MSC) | Std | 1 |
| Storage, pressurized | Std | 1 |
| Video | Std | 1 |
| Video recorder | Std | 4 |
| Video, external | Std | 3 |
| OMV | | 1 |
| OMV support systems | | 1 |
| Reflectometer Sample containers | 1 | |
| • | | 1 |
| Storage, unpressurized Stress test machine | | 3 |
| Siless lest machine | | 2 |
| Trusses | | |
| Data recorder, digital | Std | 1 |
| Hand tools, EVA general purpose | Std | 1 |
| Mobile Servicing Center (MSC) | Std | 1 |
| Video, external | Std | 1 |
| Accelerometer package, external | | 1 |
| Storage, unpressurized | | 1 |
| Welding | | |
| = | ارددا | |
| Camera locker Film locker | LSE | 1 |
| | LSE | 2 |
| Storage locker, EM-shielded Contamination monitor | LSE PAE | 1 |
| | | |
| Storage, pressurized Video recorder | Std | 1 2 1 2 |
| Video, external | Std | 2 |
| • | Std | 2 |
| Battery charger, external Camera, 35 mm (EVA) | | 1 |
| Storage, unpressurized | | 4 |
| otorage, unpressunzed | | ۷ |

SPACE STRUCTURE (DYNAMICS AND CONTROL) Equipment Count by Project

SUBTHEME: Mechanisms/Controls

| JOBINEME. | Mechanishis/Com | | |
|--|--|--|----------------------------|
| | DUPMENT ITEM | EQP CAT | MSN COUNT |
| Attitude Con Acceleration me Attitude Determ Data recorder, o | onitor, lab nination System (ADS) | LSS PAE Std | 1 1 2 |
| Contamination Payload Pointir Data recorder, o Video | onitor, lab nination System (ADS) monitor ng System (PPS) | LSS PAE PAE PAE Std Std | 1 1 1 3 1 2 |
| Sensors/Active Camera locker Camera, 35 mm Film locker Hand tools, ger Oscilloscope, d Data recorder, of Hand tools, EV Mobile Servicing Workstation, ma Frequency anal Sun sensor | neral purpose igital recording digital A general purpose g Center (MSC) aintenance | LSE LSE LSE LSE LSE SE SE SE SE SE SE SE SE SE SE SE SE S | 1 1 1 5 1 1 1 1 1 |
| Acceleration mo Vacuum vent Waste disposal Contamination r Data recorder, d Storage, pressu Video | ment neral purpose poratory sciences ponitor, lab system monitor ligital urized package, external cinema peed cinema | LSE LSE LSF LSS LSS PAE Std Std | 232313215331333113 |

SUBTHEME: Structural Dynamics

| SUBTHEME: Structural Dynami | CS | |
|--|--|--|
| EQUIPMENT ITEM | EQP | MSN |
| Antennas/Reflectors | | |
| Antennas/Reflectors Attitude Determination System (ADS) Contamination monitor Data recorder, digital Hand tools, EVA general purpose Mobile Servicing Center (MSC) Video recorder Video, external Accelerometer package, external Assembly platform Cleaning materials, EVA Computer Laser measurement unit Lighting, external OMV | PAE PAE Std Std Std Std | 2 1 8 7 3 3 7 5 1 4 4 4 4 2 |
| OMV support systems Orbit transfer vehicle, low thrust Pointing mount, two-axis solar Proximity sensor Space Station Construction Platform Storage, unpressurized Truss extension arm | | 1 1 4 1 3 1 |
| Large Structures (General) Data recorder, digital Hand tools, EVA general purpose Mobile Servicing Center (MSC) Accelerometer package, external Radiometer Storage, unpressurized | Std Std Std | 2 1 1 1 1 |
| Space Station Dynamics Data recorder, digital Mobile Servicing Center (MSC) Video recorder Video, external Accelerometer package, external Battery charger, external Inertial reference unit Laser measurement unit Retroreflective targets Storage, unpressurized Transmitter/receiver, RF | Std Std Std Std | 3 2 1 1 2 1 1 1 3 1 |
| Thermal Design Data recorder, digital Hand tools, EVA general purpose Antenna positioner, medium Imaging radiometer Sun sensor | Std Std | 3 1 1 1 2 |

FLUID MANAGEMENT Equipment Count by Project

SUBTHEME: Fluid Behavior

| SUBTREME. FIGIU Dellavior | | |
|---|---|------------------|
| EQUIPMENT ITEM | EQP CAT | COUNT |
| Hellum Storage locker, EM-shielded Vacuum vent Video Video recorder Camera, cinema Cryo storage/transfer facility, lab LHe | LSE LSS Std Std | 1 1 1 1 |
| Llquid Streams Storage locker, EM-shielded Video Video recorder | LSE Std Std | 1 1 1 |
| Two-Phase Fluids Camera locker Camera, 35 mm Film locker Fluid handling tools Storage locker, EM-shielded Acceleration monitor, lab Chemical storage facility Vacuum vent Data recorder, digital Film locker, cinema Video Video recorder Camera, cinema Camera, high speed cinema Film locker, cinema Film magazines | LSE LSE LSE LSS LSS Std Std Std Std | 2234234421332232 |

SUBTHEME: Spacecraft Fire Safety

| EQUIPMENT ITEM | EQP CAT | MSN COUNT |
|-----------------------------|------------|--------------|
| Flame Spread Mechanisms | | - |
| Camera locker | LSE | 1 |
| Cleaning equipment | LSE | 1 |
| Storage locker, EM-shielded | LSE | 1 |
| Gas storage/supply, lab | LSS | 1 |
| Storage, sample | LSS | 1 |
| Vacuum vent | LSS | 1] |
| Waste disposal system | LSS | 1 |
| Data recorder, digital | Std | 1 |
| Data terminal, graphics | Std | 1 |
| Video | Std | 1 |
| Video recorder | Std | 1 |
| Camera, high speed cinema | | 1] |
| Film locker, cinema | | 1 |
| Gas chromatograph/mass | | |
| spectrometer | | 1 |
| Gas sampling bottles | | 1 |
| Image intensifier | l | 1 |
| Interferometer, holographic | ì | 1 |
| Laser Doppler anemometer | | 1 |
| Photo processor unit | | 1 |
| Sample containers | | 1 |

SUBTHEME: Fluid Storage/Transfer

| EQUIPMENT ITEM | EQP CAT | MSN COUNT |
|---|--------------------------|-----------------------|
| Cryogens Contamination monitor Data recorder, digital Hand tools, EVA general purpose Video, external Leak detector, propellant | PAE Std Std Std | 3 2 1 1 3 |
| Cryogens Hellum Leak detector, He | | 1 |
| Sensors/Gauges Acceleration monitor, lab | LSS | 1 |

SPACE ENVIRONMENTAL EFFECTS Equipment Count by Project

SUBTHEME: Environment Characterization

| CHAITCHIE. CHAITCHINER CHAI | EQP | MSN |
|--|-----|--|
| EQUIPMENT ITEM | CAT | COUNT |
| External Environment | | 1 |
| Acceleration monitor, lab | LSS | 1 |
| Attitude Determination System (ADS) | PAE | 1 |
| Contamination monitor | PAE | 2 4 |
| Data recorder, digital | Std | 4 |
| Mobile Servicing Center (MSC) | Std | 3 |
| Accelerometer package, external | | 1 |
| Exposure tray | | 2 |
| Imaging radiometer |] |] |
| Magnetometer Mass spectrometer | 1 | 1 |
| Mass spectrometer Radiation monitor | | 4 |
| Radiation monitor, EM | | |
| Retarding potential analyzer | | 4 |
| Sample containers | | |
| Sun sensor | | 3 1 2 1 1 2 1 1 1 1 |
| Video, low light (external) | | i |
| The second secon | | - |
| Internal Environment | | |
| Battery charger | LSE | 2 |
| Dosimeter, passive | LSE | 2 1 1 |
| Storage locker, EM-shielded | LSE | 1 |
| Data recorder, digital | Std | 2 |
| Storage, pressurized | Std | 2 2 1 |
| Audiometer | | 1 |
| Noise dosemeter | l 1 | 1 |
| Noise monitor | i l | 1 |
| Power amplifier |]] | 1 |
| Radiation monitor |] | 1 |
| Radiation monitor, internal | | 1 |
| Sample containers | |] |
| Sound level meter | | 1 |
| Tape recorder, audio | | I |

| SUBTHEME: Environmental Ef | fects | |
|---|--|------------------------|
| EQUIPMENT ITEM | EQP | MSN |
| Coatings/Surface Effects Camera locker Camera, 35 mm Film locker Microscope system Multimeter, digital Workbench, laboratory sciences Storage, sample Vacuum vent Contamination monitor Data recorder, digital Hand tools, EVA general purpose Mobile Servicing Center (MSC) Bi-directional reflectance instrument Exposure tray Mass spectrometer Radiometer Reflectometer Sample containers Spectrophotometer Stress test machine Transmitter/receiver, RF Ultrasonic test unit | LSE LSE LSE LSS LSS PAID SID | 2222131155311351242111 |
| Data System Effects Data recorder, digital Hand tools, EVA general purpose Mobile Servicing Center (MSC) Storage, pressurized Optical disk drive Radiation monitor, internal Storage, unpressurized | Std Std Std Std | 3 1 2 1 1 |
| Facilities Data recorder, digital Hand tools, EVA general purpose Battery charger, external Transmitter/receiver, RF | Std Std | 1 1 1 |

SPACE ENVIRONMENTAL EFFECTS Equipment Count by Project

SUBTHEME: Environmental Effects (cont'd)

| SUBTHEME: Environmental | | |
|--|---|--------------------|
| EQUIPMENT ITEM | EQP | MSN |
| Micro-meteoroid impacts Camera locker Camera, 35 mm Film locker Hand tools, general purpose Microscope system Workbench, laboratory sciences Storage, sample Exposure tray | LSE LSE LSE LSE LSF LSS | 2 2 2 1 2 1 1 2 |
| Solid Rocket Motors Contamination monitor Data recorder, digital Solid Rocket Motor Research Facili Plasma diagnostic package Radiometer Ultrasonic test unit Workstation, teleoperator X-ray unit | PAE Std | 2222111 |
| Structural Materials Camera locker Camera, 35 mm Film locker Hand tools, general purpose Microscope system Workbench, laboratory sciences Contamination monitor Data recorder, digital Hand tools, EVA general purpose Mobile Servicing Center (MSC) MRMS Storage, pressurized Exposure tray Mass spectrometer Radiometer Sample containers Storage, unpressurized Stress test machine | LSE LSE LSE LSF PAE Std Std Std Std | 232132122111311211 |

ENERGY SYSTEMS AND THERMAL MANAGEMENT Equipment Count by Project

SUBTHEME: Advanced Thermal Control

| SUBTHEME: | Advanced Th | <u>erma</u> | | |
|--|--|-------------|---|---|
| E | QUIPMENT ITEM | | EQP CAT | MSN COUNT |
| Liquid Drop | let Radiators | | | |
| Storage locker | r, EM-shielded nination System (a monitor digital r | ADS) | LSE PAE PAE Std Std Std | 2 3 4 4 2 2 4 |
| | t, two-axis solar | | | 4 2 |
| Storage locker Attitude Deterr Contamination Data recorder, Hand tools, E\ Mobile Servicir Video recorder Video, externa Plasma ground | nination System (A monitor digital /A general purpos ng Center (MSC) (I I I, two-axis solar | ADS) | LSE PAE PAE Std Std Std Std | 2 2 2 3 2 1 2 1 2 1 |
| Hand tools, ge Contamination Data recorder, | monitor digital 'A general purpos urized I | | LSE PAE Std Std Std Std Std | 1 1 2 2 1 1 1 2 |
| Two-Phase Camera locker Camera, 35 mn Film locker Fluid handling Storage locker Acceleration m Chemical stora Vacuum vent Data recorder, Video Video recorder Camera, high s Film locker, cine Film magazines Imaging radiom | tools , EM-shielded onitor, lab ge facility digital peed cinema | | LSE LSE LSE LSS LSS LSS Std Std Std | 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 |

SUBTHEME: Energy Conversion

| SUBTHEME: Energy Conversion | | |
|---|--|--------------------------------------|
| EQUIPMENT ITEM | EQP CAT | MSN COUNT |
| Dynamic Conversion Camera locker Film locker Contamination monitor Data recorder, digital Hand tools, EVA general purpose Video recorder Video, external Camera, 35 mm (EVA) Gas storage/transfer facility Imaging radiometer Pointing mount, two-axis solar Storage, unpressurized | LSE LSE PAT Std Std Std | 1115111111 |
| Laser Systems Contamination monitor Data recorder, digital Hand tools, EVA general purpose Video, external Camera, 35 mm (EVA) Storage, unpressurized | PAE Std Std Std | 2 2 1 2 1 2 |
| Photovoltaic Systems Contamination monitor Data recorder, digital Hand tools, EVA general purpose Video recorder Video, external Imaging radiometer Pointing mount, two-axis solar Sun sensor Video, low light (external) | PAE Std Std Std Std | 1 3 2 2 1 1 1 1 |
| Solar Furnace Technology Storage, sample Attitude Determination System (ADS) Contamination monitor Data recorder, digital Imaging radiometer Pointing mount, two-axis solar | LSS PAE PAE Std | 2 2 2 2 2 2 |

ENERGY SYSTEMS AND THERMAL MANAGEMENT Equipment Count by Project

SUBTHEME: Power Management and Distribution

| Distribution | EOP | MSN |
|-------------------------------------|-----|------------------|
| EQUIPMENT ITEM | CAT | COUNT |
| Environmental Interaction | | |
| Camera locker | LSE | 1 |
| Camera, 35 mm | LSE | 1 |
| Film locker | LSE | 1 |
| Microscope system | LSE | 1 |
| Attitude determination system (ADS) | PAE | 1 2 2 2 |
| Contamination monitor | PAE | 2 |
| Data recorder, digital | Std | 2 |
| Hand tools, EVA general purpose | Std | 1 |
| Mobile Servicing Center (MSC) | Std | 1 |
| Video recorder | Std | 1 |
| Computer, experiment control | | 1 |
| Data recorder, digital | | 1 |
| Exposure tray | . 1 | 1 |
| Magnetometer | | 1 |
| Mass spectrometer | | 1 3 |
| Plasma diagnostic package | | 1 |
| Plasma ground | 1 | 1 |
| Storage, unpressurized Sun sensor | | 2 |
| Video, low light (external) | | 2 2 |
| Video, low light (external) | | _ |
| Megawatt Systems | | |
| Contamination monitor | PAE | 1 |
| Data recorder, digital | Std | 1 |
| Video recorder | Std | 1 |
| Plasma diagnostic probe | | 1 |
| Video, low light (external) | | 1 |

SUBTHEME: Propulsion

| | EQP | MSN |
|---|-----|---------------------------------|
| EQUIPMENT ITEM | CAT | COUNT |
| Advanced Propulsion Concepts | | |
| Camera, 35 mm | LŞE | 1 |
| Data recorder, digital | Std | |
| Hand tools, EVA general purpose | Std | 2 |
| Video, external | Std | 2 2 1 |
| Accelerometer package, external | | 1 |
| Propellant storage/transfer facility | | 1 |
| Spectrophotometer, imaging | | |
| (external) | | 1 |
| Storage, unpressurized | | 1 |
| Contamination Effects | | |
| Microscope system | LSE | 1 |
| Storage locker, EM-shielded | LSE | 1 |
| Contamination monitor | PAE | 2 |
| Data recorder, digital | Std | 4 |
| Hand tools, EVA general purpose | Std | 1 |
| Mobile Servicing Center (MSC) | Std | 2 3 2 2 |
| Video recorder | Std | 3 |
| Imaging radiometer | | 2 |
| Mass spectrometer | | 2 |
| Reflectometer | i | 1 |
| Sample containers | | 1 |
| Sun sensor Video, low light (external) | 1 | 2 |
| vided, low light (external) | | ۷ |
| Low Thrust | i | |
| Acceleration monitor, lab | LSS | 1 |
| Contamination monitor | PAE | 5 |
| Data recorder, digital | Std | 6 |
| Hand tools, EVA general purpose | Std | 2 |
| Mobile Servicing Center (MSC) | Std | 2 |
| Video recorder | Std | 1 |
| Video, external | Std | 2 |
| Accelerometer package, external |] | |
| Assembly platform | 1 | 1 |
| Imaging radiometer | [| 1 |
| Lighting, external | | 1 |
| Mass spectrometer | | 2 3 5 5 2 1 1 |
| Plasma diagnostic package | | ے |
| Plasma ground Potential probe | | ב ב |
| Propellant storage/transfer facility | [| 2 |
| Storage, unpressurized | | 1 |
| Tether system | | |
| Transmitter/receiver, RF | | - 1 |
| | | |

AUTOMATION AND ROBOTICS Equipment Count by Project

SUBTHEME: Automation

| SOSTILME. Automation | | |
|--|------------|------------------|
| EQUIPMENT ITEM | EQP CAT | MSN COUNT |
| Autonomous Control | | |
| Data recorder, digital | Std | 1 |
| Data terminal | Std | ; |
| | Std | |
| Mobile Servicing Center (MSC) | Siu | |
| Computer, Al | | |
| Pointing mount, two-axis solar | |] |
| Storage, unpressurized | | 1 |
| Rendezvous/Docking | | |
| Film locker | LSE | 1 |
| Storage locker, EM-shielded | LSE | 2 |
| Data recorder, digital | Std | 2 2 3 3 |
| Video recorder | Std | 3 |
| Video, external | Std | 3 |
| Accelerometer package, external | | 1 |
| Camera, cinema | | 4 |
| | | • |
| Manned Maneuvering Unit (MMU) with FSS | | 1 |
| OMV | : | 1 |
| OMV support systems | | i |
| Propellant storage/transfer facility | i | 1 |
| Range sensor, laser | 1 | 4 |
| Range sensor, radar | i | 4 |
| Rendezvous radar | | ; |
| | | 2 |
| Storage, unpressurized | | 2 2 |
| Workstation, teleoperator | | 2 |

SUBTHEME: Robotics

| SUBTREME: HODOLICS | FAN | UCU |
|---|------------|-----------------------|
| EQUIPMENT ITEM | EQP CAT | MSN |
| Advanced Concepts | | |
| Storage locker, EM-shielded | LSE | 1 |
| Data recorder, digital | Std | 1 |
| Video recorder | Std | 1 |
| Video, external | Std | 1 |
| Storage, unpressurized | | 1 |
| Workstation, telerobotic | | ' |
| Free-Flight Dynamics | | |
| Camera locker | LSE | 1 |
| Camera, 35 mm | LSE | 1 |
| Film locker | LSE | 1 |
| Storage locker, EM-shielded | LSE | 2 |
| Data recorder, digital | Std | 2 |
| Hand tools, EVA general purpose | Std | 2 1 2 1 |
| Video recorder | Std Std | 4 |
| Video, external Assembly bay | اعادا | 1 |
| Docking assembly | | 1 |
| Lighting, external | | i |
| OMV | | 1 |
| OMV support systems | | 1 |
| Propellant storage/transfer facility | | 1 |
| Storage, unpressurized | | 3 |
| Video, external (SRRL) | | 1 |
| Window, viewing | | 1 |
| Workstation, teleoperator | | 1 |
| Workstation, telerobotic | | 1 |
| Remote Maintenance/Servicing | | |
| Camera locker | LSE | 1 |
| Camera, 35 mm | LSE | 1 |
| Film locker | LSE | 1 |
| Storage locker, EM-shielded | LSE | 2 2 |
| Data recorder, digital | Std Std | 1 |
| Hand tools, EVA general purpose Video recorder | Std | 2 |
| Lighting, external | Siu | 1 |
| OMV | | 1 |
| OMV (with Smart Front End) | | 1 |
| OMV support systems | | 1 2 3 1 1 |
| Storage, unpressurized | | 3 |
| Video, external (SRRL) | | 1 |
| Window, viewing | | 1 |
| Workstation, teleoperator | | 1 |
| Workstation, telerobotic | | 1 |

AUTOMATION AND ROBOTICS Equipment Count by Project

SUBTHEME: Robotics (continued)

INFORMATION SYSTEMS Equipment Count by Project

SUBTHEME: Communication and Tracking

| SUBTHEME: Communication as | | |
|--|------------|----------------------------|
| EQUIDATIN TEM | EOP | MSN |
| EQUIPMENT ITEM | CAT | COUNT |
| Antenna Performance Storage locker, EM-shielded Data recorder, digital | LSE Std | 2 |
| Hand tools, EVA general purpose | Std | 2 |
| Mobile Servicing Center (MSC) | Std | 1 |
| Video, external | Std | 2 |
| Accelerometer package, external | | 2 |
| Antenna positioner, large | | 2 |
| Isolator, mechanical OMV | - | 1 2 2 2 2 2 |
| OMV support systems | | 2 |
| Range sensor, laser | | 2 |
| Storage, unpressurized | | 2 2 |
| | | |
| Component Technologies | | |
| Contamination monitor Data recorder, digital | PAE Std | 1 |
| Video, external | Std | 1 |
| Vioco, external | | ' |
| Propagation | | |
| Antenna positioner, medium | | 1 |
| Time Standards | | |
| Time Standards Data recorder, digital | Std | 1 |
| Data recorder, digital | 310 | ' |
| Tracking Deep Space | | |
| Storage locker, EM-shielded | LSE | 3 |
| Attitude Determination System (ADS) | PAE | 3 |
| Contamination monitor | PAE | 3 |
| Payload Pointing System (PPS) Data recorder, digital | PAE Std | 2 |
| Accelerometer package, external | Sia | 3 |
| Global Positioning System (GPS) | | 2 |
| OMV | | 3 3 3 2 3 3 2 3 3 |
| OMV support systems | | |
| Storage, unpressurized | | 1 |
| Tracking Proximity | | |
| Storage locker, EM-shielded | LSE | 1 |
| Contamination monitor | PAE | _ i |
| Data recorder, digital | Std | 1 |
| Hand tools, EVA general purpose | Std | 1 |
| OMV | | 1 |
| OMV support systems | | 1 |

SUBTHEME: Data Systems

| EQUIPMENT ITEM | EQP CAT | MSN COUNT |
|---------------------------------------|------------|--------------|
| Controls/Displays | | |
| Data recorder, digital | Std | 4 |
| Storage, pressurized | Std | 3 |
| Video | Std | 4 |
| Video recorder | Std | 4 |
| Computer, graphics/experiment control | | 3 |
| Computer-video generator | | 3 |
| Graphics display, high resolution | | 3 |
| Physiological monitor | | 4 |
| Speech generator | | 4 |
| Tape recorder, audio | | 4 |
| Visual task generator | | 3 |

INFORMATION SYSTEMS Equipment Count by Project

| SUBTHEME: Sensors | | |
|---|---|-----------------------------------|
| EQUIPMENT ITEM | EQP | MSN |
| Defense (Requirements TBD) | | |
| Electro-Optical Sensors Film locker Storage locker, EM-shielded Chemical storage facility Vacuum vent Attitude Determination System (ADS) Contamination monitor Payload Pointing System (PPS) Data recorder, digital Storage, pressurized Video Video recorder Accelerometer package, external Airlock, scientific Battery storage Calibration/servicing Cleaning equipment, optics Cryogen storage/transfer facility Window, high-quality optical Workbench, optical | LSE LSS LSS PAE PAE Std Std | 1 1 1 4 4 4 4 2 4 1 1 1 1 1 1 2 1 |
| Lidars Storage locker, EM-shielded Attitude Determination System (ADS) Contamination monitor Data recorder, digital Storage, pressurized Video Accelerometer package, external Cryogen storage/transfer facility Test instruments, electronic Tools, optical alignment | LSE PAE PAE Std Std Std | 111111111 |
| Radars/Radiometers Attitude Determination System (ADS) Data recorder, digital Mobile Servicing Center (MSC) Data recorder, digital | PAE Std Std | 1 1 1 2 |
| Radio Astronomy Attitude Determination System (ADS) Accelerometer package, external Antenna positioner, large Data recorder, digital Frequency standard, hydrogen maser Isolator, mechanical | PAE | 1 1 1 1 1 |

SUBTHEME: Biomedical

| SUBTHEME: Blomedical | FOO | Ucu |
|---|------------|------------------|
| EQUIPMENT ITEM | EQP CAT | MSN |
| Bends Avoidance/Therapy | | |
| Gas storage/supply, lab | LSS | 2 |
| Airlock, hyperbaric | Std | 1 |
| Data recorder, digital | Std | 1 |
| EMU | | 1 |
| Gas chromatograph/mass | i | |
| spectrometer | | 1 |
| Spirometer | l | 1 |
| Sterilization facility | | 1 |
| Storage, pressurized | | 1 |
| Diagnosis/Treatment | | |
| Autoclave | LSE | 1 |
| Cleaning equipment | LSE | 1 |
| Surgery/dissecting tools | LSE | 1 |
| Ultraviolet sterilization unit | LSE | 1 |
| Washer/sanitizer, equipment | LSE | 1 |
| Waste disposal system | LSS | 1 |
| Data recorder, digital | Std | 1 |
| Video | Std | 1 |
| Video recorder | Std | 1 |
| Animal holding facility | | 1 |
| Hand wash facility | | 1 |
| Physiological Effects of Low-G | | |
| Battery charger | LSE | 2 |
| Dosimeter, passive | LSE | 1 |
| Freezer | LSE | 2 1 2 1 |
| Hand tools, general purpose | LSE | 1 |
| Refrigerator | LSE | 2 |
| Storage locker, EM-shielded Chemical storage facility | LSE LSS | 1 |
| Waste disposal system | LSS | 1 |
| Data recorder, digital | Std | 3 |
| Storage, pressurized | Std | 3 3 |
| Video | Std | 1 |
| Video recorder | Std | 1 |
| Amplifiers | | 2 |
| Animal holding facility | | 1 |
| Blood sample kit | | 2 |
| Centrifuge | | 2 2 2 2 2 2 |
| Dynamometer | | 2 |
| Electrode impedance meter | | 2 |
| Ergometer | | 2 |
| Gas chromatograph/mass | | |
| spectrometer Plathysmograph | | 1 |
| Plethysmograph | | 1 |
| Respiratory monitoring system Tape recorder, audio | i | ا ہ |
| Temperature monitor, ambient | | 3 1 |
| Treadmill | | 1 |
| Urine sample kit | | 2 |
| | | |

SUBTHEME: Human Factors

| SUBTHEME: Human Factors | EQP | IRN |
|--|-----|-----------------|
| EQUIPMENT ITEM | CAT | MSN |
| Cognition | | |
| Storage locker, EM-shielded | LSE | 4 |
| Data recorder, digital | Std | 4 |
| Storage, pressurized | Std | 1 |
| Video | Std | 4 |
| Video recorder | Std | 4 |
| Anechoic chamber | | 2 |
| Computer-video generator | | 1 |
| Electrical stimulation pulse generator | | 1 |
| Electrode impedance meter | | 4 |
| Graphics display, high resolution | | 3 |
| Physiological monitor | | 4 |
| Speech generator | | 3 4 |
| Tape recorder, audio | | 4 |
| Visual pulse generator | | 2 3 |
| Visual task generator | | 3 |
| Crew Productivity | | |
| Cleanup/decontamination equipment | LSS | 1 |
| Waste disposal system | LSS | 1 |
| Storage, pressurized | Std | 1 |
| Video | Std | 1 |
| Video, external | Std | 1 |
| Lighting, external | | 1 |
| Storage, unpressurized | | 1 |
| Interaction | | |
| Storage locker, EM-shielded | LSE | 3 |
| Data recorder, digital | Std | 4 |
| Storage, pressurized | Std | 3 |
| Video | Std | 3 |
| Video recorder | Std | 3 |
| Anechoic chamber | | 2 |
| Computer, parallel processor | · • | 1 |
| Computer-video generator | | 3 |
| Electrode impedance meter | 1 | 3 |
| Graphics display, high resolution | 1 | 343332133313333 |
| Joystick | | 1 |
| Physiological monitor | | 3 |
| Speech generator | | 3 |
| Tape recorder, audio | l | 3 |
| Visual task generator | | 3 |
| Workstation, telerobotic | | 1 |

SUBTHEME: Maintenance, Repair, and Test

| | E E ASA | Hell |
|--------------------------------|----------|----------------------------|
| EQUIPMENT ITEM | CAT | MSN |
| Cleaning/Refurbishment | | |
| Camera locker | LSE | 2 |
| Carnera, 35 mm | LSE | 2 |
| Film locker | LSE | 2 2 2 2 1 |
| Microscope system | LSE | 2 |
| Storage locker, EM-shielded | LSE | 2 |
| Workbench, laboratory sciences | LSF | 1 |
| Chemical Storage Facility | LSS | 1 |
| Storage, process materials | LSS | 1 |
| Waste disposal system | LSS | 1 |
| Contamination monitor | PAE | 1 |
| Data recorder, digital | Std | 1 |
| Mobile Servicing Center (MSC) | Std | 2 |
| Video recorder | Std | 2 |
| Video, external | Std | 2 2 3 |
| Airlock, scientific | | 1 |
| Battery charger, external | | 1 2 |
| Exposure tray | | 2 |
| Gas storage/transfer facility | <u> </u> | 1 |
| Reflectometer | | |
| Sample containers | j | 1 |
| Storage, unpressurized | | 2 |
| Workstation, teleoperator | | 1 |
| inspection/Test | | |
| Battery charger | LSE | 1 |
| Multimeter, digital | LSE | 1 |
| Storage locker, EM-shielded | LSE | 3 |
| Data recorder, digital | Std | 2 |
| Storage, pressurized | Std | 3 |
| Storage, unpressurized | Std | 1 |
| Video | Std | 2 |
| Video recorder | Std | 3 2 3 1 2 2 |
| Counter | | |
| Digital word generator | i | 1 1 |
| Logic analyzer | | |
| Power supply, programmable | | 1 |
| RF power meter | , | 1 |
| Spectrum analyzer | | |
| Storage, unpressurized | | 1 |
| Transmitter/receiver, RF | | 1 |
| Waveform digitizer | | 1 |

SUBTHEME: Maintenance, Repair, and Test (continued)

| EQUIPMENT ITEM | EQP | MSN |
|--------------------------------------|-----|-------|
| EQUIPMENT ITEM | CAT | COUNT |
| Satellite Servicing | | |
| Contamination monitor | PAE | 2 |
| Data recorder, digital | Std | 2 |
| Hand tools, EVA general purpose | Std | 3 |
| Mobile Servicing Center (MSC) | Std | 2 |
| Storage, pressurized | Std | 1 |
| Storage, unpressurized | Std | 1 |
| Video, external | Std | 2 |
| Workstation, MSC telerobotic | Std | 2 |
| Docking system | | 1 |
| EMU | | 1 |
| Leak detector, propellant | | 2 |
| Lighting, external | | 2 |
| Manned Maneuvering Unit (MMU) | | 1 |
| OMV | | 2 |
| OMV support systems | | 2 |
| Propellant storage/transfer facility | 1 | 2 |
| Satellite Servicing Facility | | 2 |
| Storage, unpressurized | | 1 |

SUBTHEME: Material Processing

| ſ | EQUIPMENT ITEM | EQP | MSN |
|----|--|------------|---|
| ŀ | Composites | - | CONT |
| | Autoclave | LSE | 1 |
| | Camera locker | LSE | ¦ |
| | Camera, 35 mm | LSE | ; |
| | Cleaning equipment | LSE | 2 |
| | Film locker | LSE | 1 |
| | Hand tools, general purpose | LSE | غ ا |
| | Mass measurement device, small | LSE | 1 2 1 2 1 2 2 2 1 |
| | Microscope system | LSE | 2 |
| | Glovebox, materials processing | LSF | 1 |
| I | Workbench, laboratory sciences | LSF | 2 |
| ı | Acceleration monitor, lab | LSS | 1 |
| | Chemical storage facility | LSS | 2 |
| | Materials transport system | LSS | 1 |
| | Storage, process materials | LSS | 2 |
| | Waste disposal system | LSS | 2 |
| | Video | Std | 2 |
| Ľ | Mixing facilities | | |
| ľ | Scanning electron microscope system | | 1 |
| 19 | Crystal Growth | | |
| | Cleaning equipment | LSE | 2 |
| | Cutting/polishing system | LSE | 1 |
| | Etching equipment | LSE | 2 |
| | Fluid handling tools | LSE | 2 |
| | Hand tools, general purpose | LSE | 2 |
| | Mass measurement device, small | LSE | 2 |
| | Microscope system | LSE | 2 |
| | Multimeter, digital | LSE | 2 |
| | X-ray system | LSE | 2 |
| | Glovebox, materials processing | LSF | 2 |
| ı | Workbench, laboratory sciences Acceleration monitor, lab | LSF LSS | 2 |
| | Chemical storage facility | LSS | 1 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 |
| | Storage, sample | LSS | 9 |
| | Waste disposal system | LSS | 2 |
| | Data recorder, digital | Std | 1 |
| | Storage, pressurized | Std | 1 |
| | Hall probe | "." | 2 |
| | Optical pyrometer | | 1 |
| ١ | /ideo, high resolution | | 1 2 |

| SUBTHEME: Material Processing | | |
|---|---|--|
| FOLIPMENT ITEM | EQP | MSN |
| EQUIPMENT ITEM Fluids Autoclave Camera locker Camera, 35 mm Cleaning equipment Film locker Fluid handling tools Freezer | LSE LSE LSE LSE LSE LSE LSE | 3 3 3 4 3 4 |
| Freezer, cryogenic Hand tools, general purpose Incubator Microscope system Multimeter, digital pH meter Refrigerator Storage locker, EM-shielded Thermometer, digital Ultraviolet sterilization unit | LSE LSE LSE LSE LSE LSE LSE | 2 4 3 1 2 3 4 1 2 1 5 |
| Glovebox, materials processing Workbench, laboratory sciences Acceleration monitor, lab Chemical storage facility Waste disposal system Water service, lab grade Data recorder, digital Storage, pressurized Video Video recorder | LSF LSS LSS LSS LSS Std Std Std Std | 4 3 |
| Workstation, maintenance Centrifuge Centrifuge, refrigerated Computer, process control Hand tools, laboratory Sample containers Tape recorder, audio Video, high resolution | Std | 4 4 5 1 3 2 3 2 2 1 2 1 2 1 2 1 |

SUBTHEME: Material Processing (cont'd)

| | SUBTHEME: Material Processi | | |
|---|--|------------|-----------------------|
| ļ | EQUIPMENT ITEM | EQP | MSN |
| Ì | Materials Characterization | CAI | COUNT |
| 1 | | ا محا | |
| | Cleaning equipment | LSE | 1 |
| | Cutting/polishing system | LSE | 1 |
| ı | Electrical conductivity probe | LSE | 1 |
| l | Etching equipment | LSE | 1 |
| 1 | Fluid handling tools Hand tools, general purpose | LSE | 1 |
| 1 | Mass measurement device, small | LSE | 1 |
| į | Microscope system | LSE | 1 |
| 1 | X-ray system | LSE | 1 |
| | Glovebox, materials processing | LSF | 1 |
| | Workbench, laboratory sciences | LSF | 1 |
| Ì | Acceleration monitor, lab | LSS | 1 |
| ı | Chemical storage facility | LSS | 1 |
| ı | Cleanup/decontamination equipment | LSS | 1 |
| 1 | Gas storage/supply, lab | LSS | 1 |
| Į | Waste disposal system | LSS | 1 |
| I | Scanning electron microscope system | | 1 |
| l | Video, high resolution | | 1 |
| ۱ | Process Technology | | |
| ı | Camera locker | LSE | 1 |
| I | Camera, 35 mm | LSE | 2 2 |
| ı | Cleaning equipment | LSE | 2 |
| J | Cutting/polishing system | LSE | 1 |
| ı | Etching equipment | LSE | 1 2 |
| ı | Film locker Fluid handling tools | LSE LSE | 1 |
| ł | Hand tools, general purpose | LSE | 2 |
| 1 | Incubator | LSE | 1 |
| ı | Mass measurement device, small | LSE | i |
| l | Microscope system | LSE | i |
| I | Storage locker, EM-shielded | LSE | 2 |
| ı | Glovebox, materials processing | LSF | 2 |
| l | Workbench, laboratory sciences | LSF | 3 |
| I | Chemical storage facility | LSS | 1 |
| 1 | Storage, process materials | LSS | 2 3 1 2 2 |
| I | Storage, sample | LSS | 2 |
| I | Vacuum vent | LSS | 1 |
| | Waste disposal system | LSS | 2 2 3 2 1 |
| ١ | Data recorder, digital | Std | 2 |
| | Video | Std | 3 |
| | Video recorder | Std | 2 |
| | Sample containers | |]] |
| | Scanning electron microscope system | | |
| Į | Storage, isolation | | 1 |

| 300 | INEME: | material | P! | ocessing | Cont | \mathbf{u}_{j} | |
|-----|--------|----------|----|----------|---------|------------------|---|
| | | | | T FO | P 1 1/4 | SN | • |

| EQUIPMENT ITEM | EQP | MSN |
|--|------------|-------------|
| Sample Handling/Storage | | |
| Autoclave | LSE | 1 |
| Camera locker | LSE | 1 |
| Camera, 35 mm | LSE | |
| Cleaning equipment | LSE | 1 |
| Etching equipment | LSE | 1 |
| Film locker | LSE | 1 |
| Fluid handling tools | LSE | 1 |
| Freeze dryer | LSE | |
| Freezer | LSE LSE | 1 |
| Hand tools, general purpose | LSE | 1 |
| Microscope system | LSE | 1 |
| pH meter | LSE | 1 1 |
| Refrigerator | LSE | 1 |
| Ultraviolet sterilization unit | LSE | 1 |
| Glovebox, materials processing | LSF | 1 |
| Workbench, laboratory sciences | LSF | 1 |
| Chemical storage facility | LSS |]] |
| Vacuum vent | LSS | 1 1 |
| Waste disposal system Water service, lab grade | LSS | 1 1 1 1 1 |
| Data recorder, digital | Std | 1 |
| Centrifuge, refrigerated | Sid | 1 |
| Gas chromatograph/mass | | ' |
| spectrometer | | 1 |
| Sample containers | | 1 |
| - Carripio Contamoro | | · |
| Solid Propellants | | |
| Camera locker | LSE | 1 |
| Camera, 35 mm | LSE | 1 |
| Film locker | LSE | 1 |
| Microscope system | LSE | 1 |
| Data recorder, digital | Std | 1 |
| Video | Std | 1 |
| Video recorder | Std | 1 2 1 |
| Solid Rocket Motor Research Facility | ĺĺ | 2 |
| Sample containers | | |
| Workstation, teleoperator | | 1 |

SUBTHEME: Systems/Facilities

| SUBTHEME: Systems/Facilities | | 1/211 |
|--|--|---|
| EQUIPMENT ITEM | EQP CAT | COUNT |
| CELSS | 771 | 300111 |
| Cleaning equipment Fluid handling tools Freezer Mass measurement device, small Microscope system pH meter Refrigerator Washer/sanitizer, equipment Glovebox, materials processing Chemical storage facility Gas storage/supply, lab Waste disposal system Water service, lab grade Data recorder, digital Centrifuge, refrigerated Gas chromatograph/mass spectrometer Sample containers | LSE LSE LSE LSE LSE LSS LSS LSS LSS LSS | 1 4 4 2 4 4 4 4 4 4 4 1 1 3 4 4 4 4 1 3 4 4 4 4 |
| Manned Systems Hand tools, general purpose Data recorder, digital Docking port Video Video Video recorder Electrical test/checkout equipment Physiological monitor | LSE Std Std Std Std | 1 1 1 1 1 |
| OTY Data recorder, digital Hand tools, EVA general purpose Mobile Servicing Center (MSC) Video, external Workstation, MSC telerobotic Berthing system, OTV Dummy payload Leak detector, propellant Lighting, external OMV OMV support systems Propellant storage/transfer facility Servicing/maintenance hangar Storage, unpressurized | Std Std Std Std Std | 22333212211112 |

SUBTHEME: Systems/Facilities (cont'd)

| | EQP | MSN |
|---|--|---------------------------------|
| EQUIPMENT ITEM | CAT | COUNT |
| Reentry Systems Data recorder, digital Docking port Docking system OMV OMV support systems Servicing/maintenance hangar Storage, unpressurized | Std Std | 1 1 1 1 1 2 2 |
| <u>Technology Evaluation</u> (Requirements TBD) | | |
| Tethers Contamination monitor Data recorder, digital Hand tools, EVA general purpose Storage, pressurized Storage, unpressurized Video Video recorder Video, external Berthing system, OTV Cleaning equipment, optics Cryogen storage/transfer facility, LHe Lighting, external OMV OMV support systems OTV Satellite Servicing Facility Tether alignment system Tethered pointing system Tethered pointing system Transmitter/receiver | PAE Std Std Std Std Std | 1131111511121111251 |

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APPENDIX E. New Development Candidates for TDM Outfitting

This section contains two versions of a list of potential outfitting items -- one sorted by mission count and the other sorted alphabetically. For each mission a list of outfitting equipment needs was generated that included outfitting items requested in the mission descriptions, support items thought to be of benefit where none were identified, key items of Space Station accommodation equipment, and items of experiment equipment thought to have multi- use potential. These mission-level equipment lists were consolidated into a master list. The list presented here is what is left after subtracting from the master list those items known to be in planning. As such, it represents outfitting needs for technology development missions that are not already being met.

EQUIPMENT ITEMS WITH COMMON-USE POTENTIAL BY DESCENDING COUNT (Sheet 1 of 2)

| | ITEM | MISSION |
|---|--------------------------------------|-------------|
| ı | Storage, unpressurized | 61 |
| İ | Accelerometer package, external | 29 |
| 1 | Lighting, external | 20 |
| | OMV support systems | 19 |
| | Sample containers | 19 |
| | OMV | 18 |
| | Tape recorder, audio | 17 |
| ļ | Mass spectrometer | 14 |
| ı | Exposure tray | 13 |
| | Physiological monitor | 12 |
| | Pointing mount, two-axis solar | 12 |
| | Imaging radiometer | 11 |
| i | Plasma ground | 11 |
| | Speech generator | 10 |
| | Electrode impedance meter | 9 |
| | Graphics display, high resolution | 9 |
| | Propellant storage/transfer facility | 9 |
| ļ | Radiometer | 9 |
| | Visual task generator | 9 |
| | Workstation, telerobotic | 9 |
| | Plasma diagnostic package | 8 |
| | Sun sensor | 8 |
| | Workstation, teleoperator | 8 |
| | Camera, high speed cinema | 7 |
| | Computer-video generator | 7 7 |
| | Leak detector, propellant | 7 |
| ı | Video, low light (external) | 6 |
| ı | Film magazines Window, viewing | 6 |
| | Film locker, cinema | 5 |
| | Gas chromatograph/mass spectrometer | 5 |
| | Laser measurement unit | 5 |
| | Potential probe | 5 5 5 |
| 1 | Reflectometer | 5 |
| 1 | Tether tracking system | 5 |
| | Transmitter/receiver, RF | 5 5 |
| | Video, external (SRRL) | 5 |
| 1 | Anechoic chamber | 4 |
| | Assembly platform | 4 |
| İ | Battery charger, external | 4 |
| ı | Camera, 35 mm (EVA) | 4 |
| | Camera, cinema | 4 |
| | Centrifuge | 4 |
| | Cleaning materials, EVA | 4 |
| | Computer (VAX 11/780 or equivalent) | 4 |
| | Data recorder, digital | 4 |
| | Proximity sensor | 4 |
| | Solid Rocket Motor Research Facility | 4 |
| | Stress test machine | 4 |
| | Video, high resolution | 4 |
| | Antenna positioner, large | 3 |
| | Berthing system, OTV | 3 |

| | 111001011 |
|--|---|
| ITEM | MISSION COUNT |
| Camera locker, cinema | 3 |
| | 3 |
| Centrifuge, refrigerated | 3 3 |
| Computer, graphics/experiment control Cryogen storage/transfer facility |) 3 |
| Cryogen storage/transfer facility, LHe | 3 |
| Gas storage/transfer facility | 3 |
| Isolator, mechanical | 3 |
| Range sensor, laser | 3 |
| Retroreflective targets | 3 |
| Satellite Servicing Facility | 3 |
| Scanning electron microscope system | 3 |
| Servicing/maintenance hangar | 3 |
| Vacuum chamber | 3 |
| Airlock, scientific | 333333333222222222222222222222222222222 |
| Amplifiers | 2 |
| Animal holding facility | 2 |
| Antenna positioner, medium | 2 |
| Blood sample kit | 2 |
| Cleaning equipment, optics | 5 |
| Computer, process control | 2 |
| Docking system | 2 |
| Dynamometer | 2 |
| EMU | 5 |
| ai . | 5 |
| Ergometer Global Positioning System (GPS) | 5 |
| Hall probe | 2 |
| Hand tools, laboratory | 2 |
| Magnetometer | 2 |
| Radiation monitor | 2 |
| Radiation monitor, internal | 2 |
| Spectrophotometer | 2 |
| Tether alignment system | 2 |
| Ultrasonic test unit | 2 |
| Urine sample kit | 2 |
| Visual pulse generator | 2 |
| Window, high-quality optical | 2 |
| Assembly bay | 1 |
| Audiometer | 1 |
| ! | 1 |
| Battery storage Bi-directional reflectance instrument | |
| Calibration/servicing equipmentoptical | 4 |
| Computer, Al | 1 |
| Computer, Ail Computer, experiment control | 1 |
| Computer, parallel processor | 1 |
| Counter | 1 |
| Cryo storage/transfer facility, lab LHe | ; |
| Digital word generator | |
| Docking assembly | |
| Dummy payload | |
| Electrical stimulation pulse generator | 1 |
| Electrical test/checkout equipment | 1 |
| Frequency analyzer | 1 |
| 1 requerity analyzer | ' |

EQUIPMENT ITEMS WITH COMMON-USE POTENTIAL BY DESCENDING COUNT (Sheet 2 of 2)

| | MISSION |
|------------------------------------|---------|
| ITEM | COUNT |
| Frequency standard, hydrogen maser | 1 |
| Gas sampling bottles | 1 |
| Hand wash facility | 1 |
| Image intensifier | 1 |
| Inertial reference unit | 1 |
| Interferometer, holographic | 1 |
| Joystick | 1 |
| Laser Doppler anemometer | 1 |
| Leak detector, He | 1 |
| Logic analyzer | 1 |
| Manned Maneuvering Unit (MMU) | 1 |
| Manned Maneuvering Unit (MMU) with | |
| FSS | 1 |
| Mixing facilities | 1 |
| Noise dosemeter | 1 |
| Noise monitor | 1 |
| OMV (with Smart Front End) | 1 |
| Optical disk drive | 1 |
| Optical pyrometer | 1 |
| Orbit transfer vehicle, low thrust | 1 |
| OTV | 1 1 |
| Photo processor unit | 1 |
| Plasma diagnostic probe |] 1 |
| Plethysmograph | 1 |
| Power amplifier | 1 |
| Power supply, programmable | 1 |

| ITEM | MISSION |
|---------------------------------------|---------|
| | COUNT |
| Radiation monitor, EM | |
| Range sensor, radar |] |
| Rendezvous radar |] |
| Respiratory monitoring system |] |
| Retarding potential analyzer | 1 |
| RF power meter | 1 |
| Shroud, cover | 1 |
| Sound level meter | 1 |
| Space Station Construction Platform | 1 |
| Spectrophotometer, imaging (external) | 1 |
| Spectrum analyzer | 1 |
| Spirometer | [1 |
| Sterilization facility | 1 |
| Storage, isolation | 1 |
| Storage, pressurized | 1 |
| Temperature monitor, ambient | 1 |
| Test instruments, electronic | 1 |
| Tether system | [1 |
| Tethered pointing system | 1 |
| Tools, optical alignment | 1 |
| Transmitter/receiver | 1 |
| Treadmill | 1 |
| Truss extension arm | 1 |
| Waveform digitizer | 1 |
| Workbench, optical | 1 |
| X-ray unit | 1 |

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ALPHABETIC LISTING OF EQUIPMENT ITEMS WITH COMMON-USE POTENTIAL (Sheet 1 of 2)

| | ITEM | MISSION COUNT |
|---|---|---------------------------------------|
| | Accelerometer package, external | 29 |
| | Airlock, scientific | 2 |
| | Amplifiers | 2 |
| | Anechoic chamber | 4 |
| | Animal holding facility | 2 |
| | Antenna positioner, large | 2 3 2 1 |
| | Antenna positioner, medium | 2 |
| | Assembly bay | 1 |
| | Assembly platform | 4 |
| | Audiometer | 4 |
| ı | Battery charger, external | 4 |
| | Battery storage Berthing system, OTV | 1 |
| | Bi-directional reflectance instrument | 3 1 |
| ı | Blood sample kit | |
| | Calibration/servicing | 2 1 |
| 1 | Camera locker, cinema | 3 |
| 1 | Camera, 35 mm (EVA) | 4 |
| 1 | Camera, cinema | 4 |
| | Camera, high speed cinema | 7 |
| 1 | Centrifuge | 4 |
| ı | Centrifuge, refrigerated | 3 |
| | Cleaning equipment, optics | 3 2 4 |
| 1 | Cleaning materials, EVA | |
| Į | Computer (VAX 11/780 or equivalent) | 4 |
| ١ | Computer, Al | 1 |
| ı | Computer, experiment control | 1 |
| I | Computer, graphics/experiment control | 3 |
| ı | Computer, parallel processor | 1 2 7 |
| Į | Computer, process control | 2 |
| 1 | Computer-video generator | |
| ١ | Counter | 1 |
| | Cryo storage/transfer facility, lab LHe | 1 |
| 1 | Cryogen storage/transfer facility | 3 3 |
| | Cryogen storage/transfer facility, LHe Data recorder, digital | 4 |
| İ | Digital word generator | 1 |
| ı | Docking assembly | 1 |
| | Docking system | _ |
| | Dummy payload | 1 |
| - | Dynamometer | 2 |
| ı | Electrical stimulation pulse generator | 1 |
| ١ | Electrical test/checkout equipment | 1 |
| 1 | Electrode impedance meter | 9 |
| 1 | EMU ' | 2 |
| | Ergometer | 1 2 1 1 9 2 2 13 |
| J | Exposure tray | 13 |
| J | Film locker, cinema | 5 6 |
| ł | Film magazines | 6 |
| J | Frequency analyzer | 1 |
| Į | Frequency standard, hydrogen maser | 1 |
| | Gas chromatograph/mass spectrometer | 5 |
| 1 | Gas sampling bottles | 1 |
| - | | |

| Gas storage/transfer facility Global Positioning System (GPS) Graphics display, high resolution Hall probe Hand tools, laboratory Hand wash facility Image intensifier Inertial reference unit Interferometer, holographic Isolator, mechanical Joystick Laser Doppler anemometer Laser measurement unit Leak detector, He Leak detector, He Leak detector, propellant Lighting, external Logic analyzer Magnetometer Manned Maneuvering Unit (MMU) Manned Maneuvering Unit (MMU) with FSS Mass spectrometer Mixing facilities Noise dosemeter Noise monitor OMV OMV (with Smart Front End) OMV support systems 19 Optical disk drive Optical pyrometer Orbit transfer vehicle, low thrust OTV Photo processor unit Physiological monitor Plasma diagnostic probe Plasma diagnostic probe Plasma diagnostic probe Plasma diagnostic probe Plasma ground Plethysmograph Pointing mount, two-axis solar Potential probe Power amplifier Power supply, programmable Propellant storage/transfer facility Prozimity sensor Radiation monitor, internal Radiometer Range sensor, radar Range sensor, radar | | |
|---|--------------------------------------|------------------|
| Global Positioning System (GPS) Graphics display, high resolution Hall probe Hand tools, laboratory Hand wash facility Image intensifier Imaging radiometer Inertial reference unit Interferometer, holographic Isolator, mechanical Joystick Laser Doppler anemometer Laser measurement unit Leak detector, He Leak detector, He Leak detector, propellant Lighting, external Logic analyzer Manned Maneuvering Unit (MMU) Manned Maneuvering Unit (MMU) Manned Maneuvering Unit (MMU) Mixing facilities Noise dosemeter Noise monitor OMV OMV (with Smart Front End) OMV support systems 19 Optical disk drive Optical pyrometer Orbit transfer vehicle, low thrust OTV Photo processor unit Physiological monitor Plasma diagnostic probe Plasma diagnostic probe Plasma diagnostic probe Plasma ground Plethysmograph Pointing mount, two-axis solar Potential probe Power amplifier Power supply, programmable Propellant storage/transfer facility Proximity sensor Radiation monitor, internal Radiometer Range sensor, laser Range sensor, radar Reflectometer | ITEM | MISSION COUNT |
| Global Positioning System (GPS) Graphics display, high resolution Hall probe Hand tools, laboratory Hand wash facility Image intensifier Imaging radiometer Inertial reference unit Interferometer, holographic Isolator, mechanical Joystick Laser Doppler anemometer Laser measurement unit Leak detector, He Leak detector, He Leak detector, propellant Lighting, external Logic analyzer Manned Maneuvering Unit (MMU) Manned Maneuvering Unit (MMU) Manned Maneuvering Unit (MMU) Mixing facilities Noise dosemeter Noise monitor OMV OMV (with Smart Front End) OMV support systems 19 Optical disk drive Optical pyrometer Orbit transfer vehicle, low thrust OTV Photo processor unit Physiological monitor Plasma diagnostic probe Plasma diagnostic probe Plasma diagnostic probe Plasma ground Plethysmograph Pointing mount, two-axis solar Potential probe Power amplifier Power supply, programmable Propellant storage/transfer facility Proximity sensor Radiation monitor, internal Radiometer Range sensor, laser Range sensor, radar Reflectometer | Gas storage/transfer facility | 3 |
| Hand wash facility Image intensifier Imaging radiometer Inertial reference unit Interferometer, holographic Isolator, mechanical Joystick Laser Doppler anemometer Laser measurement unit Leak detector, He Leak detector, Propellant Logic analyzer Magnetometer Manned Maneuvering Unit (MMU) Manned Maneuvering Unit (MMU) with FSS Mass spectrometer Mixing facilities Noise dosemeter Noise monitor OMV OMV (with Smart Front End) OMV support systems Optical disk drive Optical disk drive Optical pyrometer Orbit transfer vehicle, low thrust OTV Photo processor unit Physiological monitor Plasma diagnostic package Plasma diagnostic probe Plasma ground Plethysmograph Pointing mount, two-axis solar Potential probe Power amplifier Power supply, programmable Propellant storage/transfer facility Proximity sensor Radiation monitor, EM Radiation monitor, internal Reflectometer S 11 11 11 11 12 12 13 14 15 16 17 17 18 17 18 19 19 10 10 11 11 11 11 11 11 11 11 11 11 11 | | 2 |
| Hand wash facility Image intensifier Imaging radiometer Inertial reference unit Interferometer, holographic Isolator, mechanical Joystick Laser Doppler anemometer Laser measurement unit Leak detector, He Leak detector, Propellant Logic analyzer Magnetometer Manned Maneuvering Unit (MMU) Manned Maneuvering Unit (MMU) with FSS Mass spectrometer Mixing facilities Noise dosemeter Noise monitor OMV OMV (with Smart Front End) OMV support systems Optical disk drive Optical disk drive Optical pyrometer Orbit transfer vehicle, low thrust OTV Photo processor unit Physiological monitor Plasma diagnostic package Plasma diagnostic probe Plasma ground Plethysmograph Pointing mount, two-axis solar Potential probe Power amplifier Power supply, programmable Propellant storage/transfer facility Proximity sensor Radiation monitor, EM Radiation monitor, internal Reflectometer S 11 11 11 11 12 12 13 14 15 16 17 17 18 17 18 19 19 10 10 11 11 11 11 11 11 11 11 11 11 11 | | 9 |
| Hand wash facility Image intensifier Imaging radiometer Inertial reference unit Interferometer, holographic Isolator, mechanical Joystick Laser Doppler anemometer Laser measurement unit Leak detector, He Leak detector, Propellant Logic analyzer Magnetometer Manned Maneuvering Unit (MMU) Manned Maneuvering Unit (MMU) with FSS Mass spectrometer Mixing facilities Noise dosemeter Noise monitor OMV OMV (with Smart Front End) OMV support systems Optical disk drive Optical disk drive Optical pyrometer Orbit transfer vehicle, low thrust OTV Photo processor unit Physiological monitor Plasma diagnostic package Plasma diagnostic probe Plasma ground Plethysmograph Pointing mount, two-axis solar Potential probe Power amplifier Power supply, programmable Propellant storage/transfer facility Proximity sensor Radiation monitor, EM Radiation monitor, internal Reflectometer S 11 11 11 11 12 12 13 14 15 16 17 17 18 17 18 19 19 10 10 11 11 11 11 11 11 11 11 11 11 11 | | 2 |
| Hand wash facility Image intensifier Imaging radiometer Inertial reference unit Interferometer, holographic Isolator, mechanical Joystick Laser Doppler anemometer Laser measurement unit Leak detector, He Leak detector, Propellant Logic analyzer Magnetometer Manned Maneuvering Unit (MMU) Manned Maneuvering Unit (MMU) with FSS Mass spectrometer Mixing facilities Noise dosemeter Noise monitor OMV OMV (with Smart Front End) OMV support systems Optical disk drive Optical disk drive Optical pyrometer Orbit transfer vehicle, low thrust OTV Photo processor unit Physiological monitor Plasma diagnostic package Plasma diagnostic probe Plasma ground Plethysmograph Pointing mount, two-axis solar Potential probe Power amplifier Power supply, programmable Propellant storage/transfer facility Proximity sensor Radiation monitor, EM Radiation monitor, internal Reflectometer S 11 11 11 11 12 12 13 14 15 16 17 17 18 17 18 19 19 10 10 11 11 11 11 11 11 11 11 11 11 11 | | 2 |
| Image intensifier Imaging radiometer Inertial reference unit Interferometer, holographic Isolator, mechanical Joystick Laser Doppler anemometer Laser measurement unit Leak detector, He Leak detector, propellant Lighting, external Logic analyzer Manned Maneuvering Unit (MMU) Manned Maneuvering Unit (MMU) Manned Maneuvering Unit (MMU) Mixing facilities Noise dosemeter Noise monitor OMV OMV (with Smart Front End) OMV support systems Optical disk drive Optical pyrometer Orbit transfer vehicle, low thrust OTV Photo processor unit Physiological monitor Plasma diagnostic package Plasma diagnostic probe Plasma ground Plethysmograph Pointing mount, two-axis solar Power supply, programmable Propellant storage/transfer facility Proximity sensor Radiation monitor, EM Radiometer Range sensor, laser Range sensor, radar Reflectometer 1 11 11 11 11 11 11 11 11 11 11 11 11 | | |
| Imaging radiometer Inertial reference unit Interferometer, holographic Isolator, mechanical Joystick Laser Doppler anemometer Laser measurement unit Leak detector, He Leak detector, propellant Lighting, external Logic analyzer Magnetometer Manned Maneuvering Unit (MMU) Manned Maneuvering Unit (MMU) with FSS Mass spectrometer Mixing facilities Noise dosemeter Noise monitor OMV OMV (with Smart Front End) OMV support systems Optical disk drive Optical pyrometer Orbit transfer vehicle, low thrust OTV Photo processor unit Physiological monitor Plasma diagnostic package Plasma diagnostic probe Plasma ground Plethysmograph Pointing mount, two-axis solar Power supply, programmable Propellant storage/transfer facility Proximity sensor Radiation monitor, EM Radiation monitor, internal Radiometer Range sensor, radar Range sensor, radar Reflectometer | | |
| Inertial reference unit Interferometer, holographic Isolator, mechanical Joystick Laser Doppler anemometer Laser measurement unit Leak detector, He Leak detector, Propellant Logic analyzer Magnetometer Manned Maneuvering Unit (MMU) Manned Maneuvering Unit (MMU) Manned Maneuvering Unit (MMU) with FSS Mass spectrometer Mixing facilities Noise dosemeter Noise monitor OMV OMV (with Smart Front End) OMV support systems Optical disk drive Optical pyrometer Orbit transfer vehicle, low thrust OTV Photo processor unit Physiological monitor Plasma diagnostic package Plasma diagnostic probe Plasma ground Plethysmograph Pointing mount, two-axis solar Potential probe Power amplifier Power supply, programmable Propellant storage/transfer facility Proximity sensor Radiation monitor, EM Radiation monitor, internal Radiometer Range sensor, radar Reflectometer | | 1 |
| Interferometer, holographic Isolator, mechanical Joystick Laser Doppler anemometer Laser measurement unit Leak detector, He Leak detector, propellant Logic analyzer Magnetometer Manned Maneuvering Unit (MMU) Manned Maneuvering Unit (MMU) Mansed Maneuvering Unit (MMU) Mass spectrometer Mixing facilities Noise dosemeter Noise monitor OMV 18 OMV (with Smart Front End) OMV support systems 19 Optical disk drive Optical pyrometer Orbit transfer vehicle, low thrust OTV Photo processor unit Physiological monitor Plasma diagnostic package Plasma diagnostic probe Plasma diagnostic probe Plasma ground Plethysmograph Pointing mount, two-axis solar Potential probe Power amplifier Power supply, programmable Propellant storage/transfer facility Proximity sensor Radiation monitor, EM Radiation monitor, internal Radiometer Range sensor, laser Range sensor, radar Reflectometer | | 8 |
| Isolator, mechanical Joystick Laser Doppler anemometer Laser measurement unit Leak detector, He Leak detector, propellant Lighting, external Logic analyzer Magnetometer Manned Maneuvering Unit (MMU) Manned Maneuvering Unit (MMU) Manned Maneuvering Unit (MMU) Mixing facilities Noise dosemeter Noise monitor OMV OMV (with Smart Front End) OMV (with Smart Front End) OMV support systems 19 Optical disk drive Optical pyrometer Orbit transfer vehicle, low thrust OTV Photo processor unit Physiological monitor Plasma diagnostic package Plasma diagnostic probe Plasma ground Plethysmograph Pointing mount, two-axis solar Potential probe Power amplifier Power supply, programmable Propellant storage/transfer facility Proximity sensor Radiation monitor, EM Radiation monitor, internal Radiometer Range sensor, laser Range sensor, radar Reflectometer | | |
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| Proximity sensor Radiation monitor Radiation monitor, EM Radiation monitor, internal Radiometer Range sensor, laser Range sensor, radar Reflectometer 4 2 Radiation monitor 9 Range sensor 1 Reflectometer | Power supply, programmable | 1 |
| Radiation monitor 2 Radiation monitor, EM 1 Radiation monitor, internal 2 Radiometer 9 Range sensor, laser 3 Range sensor, radar 1 Reflectometer 5 | Propellant storage/transfer facility | 9 |
| | | 4 |
| | | 2 |
| | | 1 |
| | | 2 |
| | | 9 |
| | | 3 |
| | Range sensor, radar | 1 |
| Rendezvous radar 1 | Reflectometer | |
| | Rendezvous radar | 1 |

ALPHABETIC LISTING OF EQUIPMENT ITEMS WITH COMMON-USE POTENTIAL (Sheet 2 of 2)

| ITPI | MISSION |
|---------------------------------------|---------|
| ITEM | COUNT |
| Respiratory monitoring system | ! |
| Retarding potential analyzer | 1 1 |
| Retroreflective targets | 3 |
| RF power meter | 1 |
| Sample containers | 19 |
| Satellite Servicing Facility | 3 |
| Scanning electron microscope system | 3 |
| Servicing/maintenance hangar | 3 |
| Shroud, cover | 1 1 |
| Solid Rocket Motor Research Facility | 4 |
| Sound level meter | 1 |
| Space Station Construction Platform | 1 |
| Spectrophotometer | 2 |
| Spectrophotometer, imaging (external) | 1 |
| Spectrum analyzer | 1 |
| Speech generator | 10 |
| Spirometer | 1 |
| Sterilization facility | 1 |
| Storage, isolation | 1 |
| Storage, pressurized | 1 1 |
| Storage, unpressurized | 61 |
| Stress test machine | 4 |
| Sun sensor | 8 |
| Tape recorder, audio | 17 |
| Temperature monitor, ambient | 1 |

| ITEM | MISSION |
|------------------------------|---------|
| Test instruments, electronic | 1 |
| Tether alignment system | 2 |
| Tether system | 1 1 |
| Tether tracking system | 5 |
| Tethered pointing system | [1] |
| Tools, optical alignment | 1 |
| Transmitter/receiver | 1 |
| Transmitter/receiver, RF | 5 |
| Treadmill | 1 |
| Truss extension arm | 1 |
| Ultrasonic test unit | 2 |
| Urine sample kit | 2 |
| Vacuum chamber | 3 |
| Video, external (SRRL) | 5 |
| Video, high resolution | 4 |
| Video, low light (external) | 7 |
| Visual pulse generator | 2 |
| Visual task generator | 9 |
| Waveform digitizer | 1 |
| Window, high-quality optical | 2 |
| Window, viewing | 6 |
| Workbench, optical | 1 |
| Workstation, teleoperator | 8 |
| Workstation, telerobotic | 9 |
| X-ray unit | 1 |

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|--|--|--|
| . Report No. | 2. Government Accession | on No. 3. Recipient's Catalog No. |
| NASA CR-181707 | | |
| Title and Subtitle | | 5. Report Date |
| Space Station RT&E Utilization Study | | September 1989 |
| | | 6. Performing Organization Code |
| Author(s) | | 8. Performing Organization Report No. |
| P. K. Wunsch and P. H. Anderson | | |
| | v | 10. Work Unit No. |
| | | 480-51-23-03 |
| Performing Organization Name | | 11. Contract or Grant No. |
| Teledyne Brown Eng: Cummings Research | - | |
| Huntsville, AL 35807 | | NAS1-18228 |
| - | | 13. Type of Report and Period Covered |
| 2 Sponsoring Agency Name and Address National Aeroanutics and Space Administra Langley Research Center Hampton, VA 23665-5225 | | Contractor Report |
| | | 14. Sponsoring Agency Code |
| Langley Technical N Final Report - Task | Monitor: Lenwood G. Cl k 4 | ark |
| establish prelimina missions. The miss development activity included both press needs were compared user communities, a Outfitting implement | ary Space Station outfi sions studied cover the ties envisioned for ear surized volume and attad with outfitting plans and a number of potenti | el mission concepts were reviewed to ting needs for technology development full range of in-space technology by Space Station operations and the payload requirements. Equipment for the life sciences and microgravity al outfitting additions were identified. |
| | technical themes, by or | by selecting a strawman mission complement ganizing the missions into flight and outfitting buildup for planning impact |
| | technical themes, by or assessing the associate thor(s)) | ganizing the missions into flight |
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